

# Universal Algebra and Computational Complexity

## Lecture 1

Ross Willard

University of Waterloo, Canada

Třešt', September 2008

# Outline

## LECTURE 1: Decision problems and Complexity Classes

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LECTURE 2: Nondeterminism, Reductions and Complete problems

LECTURE 1: Decision problems and Complexity Classes

LECTURE 2: Nondeterminism, Reductions and Complete problems

LECTURE 3: Results and problems from Universal Algebra

# Three themes: problems, algorithms, efficiency

A *Decision Problem* is . . .

- A *YES/NO question*
- parametrized by one or more *inputs*.
  - Inputs must:
    - range over an *infinite* class.
    - be “finitistically described”

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What we seek:

- An *algorithm* which correctly answers the question for all possible inputs.

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  - Inputs must:
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    - be “finitistically described”

What we seek:

- An *algorithm* which correctly answers the question for all possible inputs.

What we ask:

- How *efficient* is this algorithm?
- Is there a better (more efficient) algorithm?

# Directed Graph Reachability problem (PATH)

INPUT:

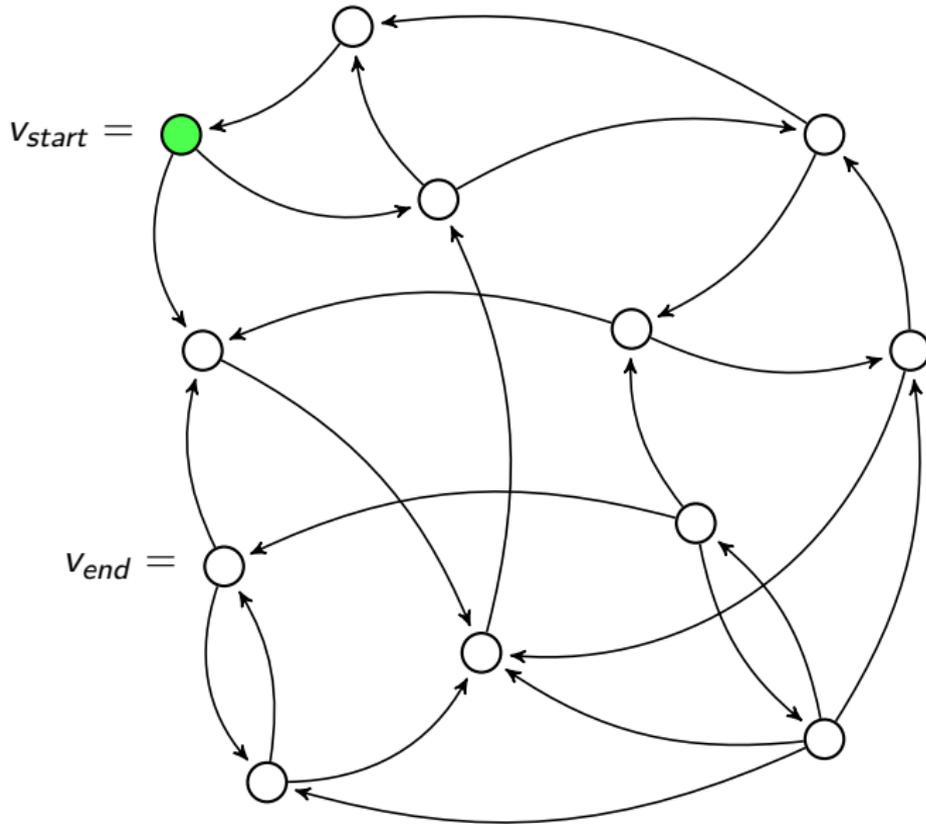
- A finite directed graph  $G = (V, E)$
- Two distinguished vertices  $v_{start}, v_{end} \in V$ .

QUESTION:

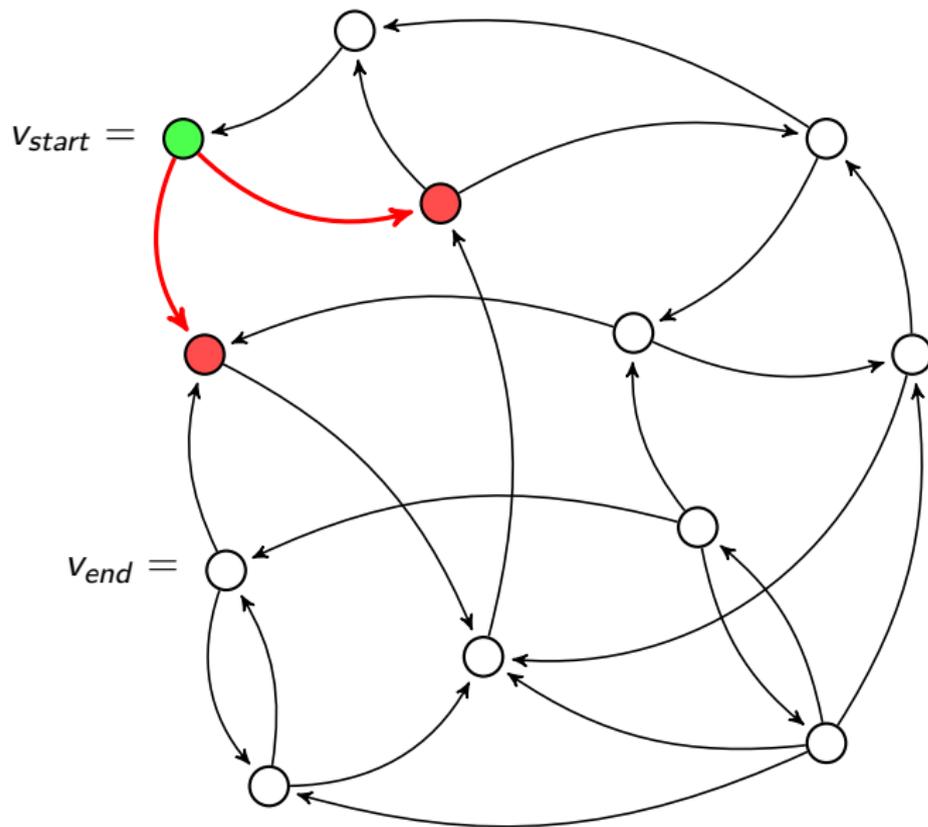
- Does there exist in  $G$  a *directed path* from  $v_{start}$  to  $v_{end}$ ?



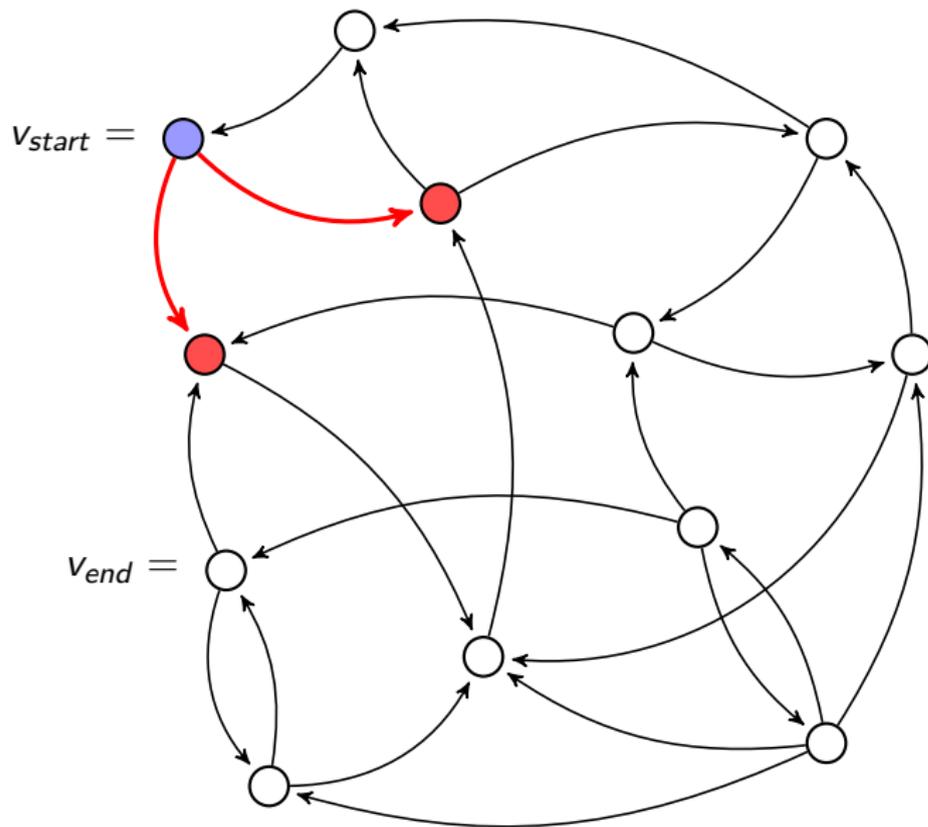
# An Algorithm for PATH



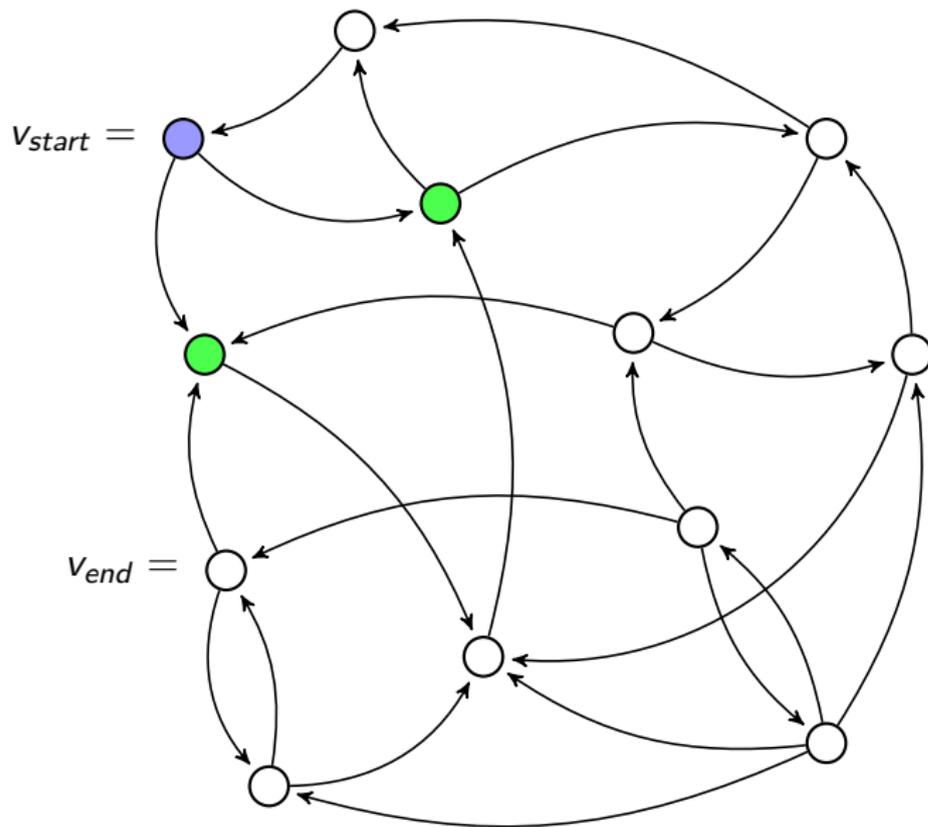
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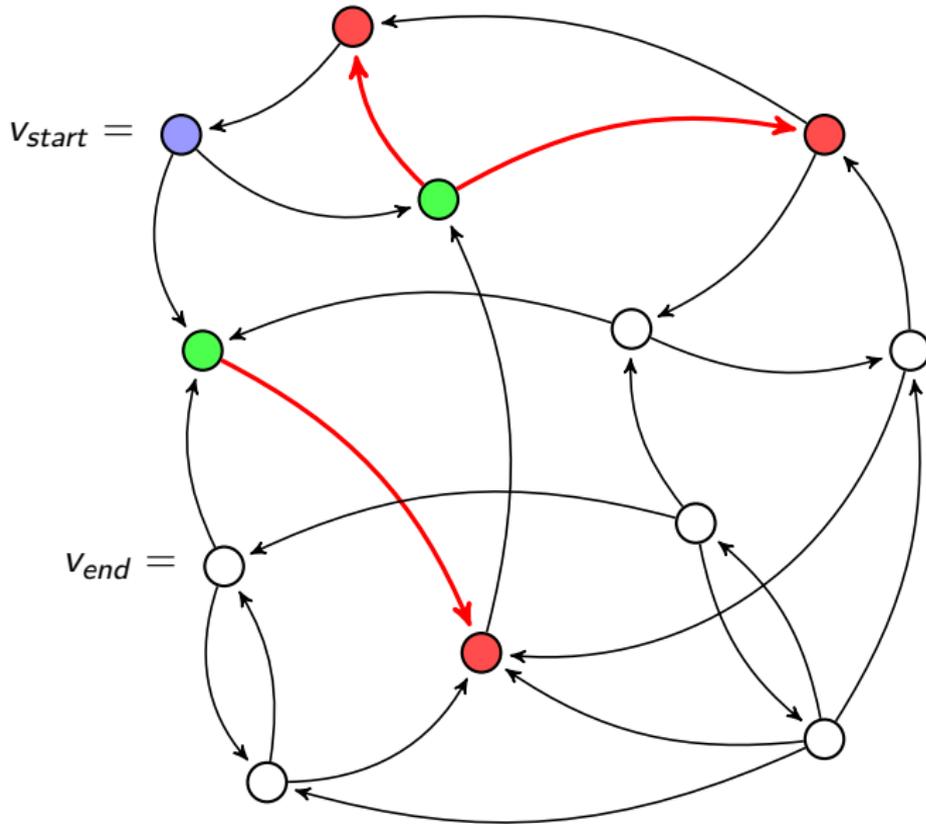
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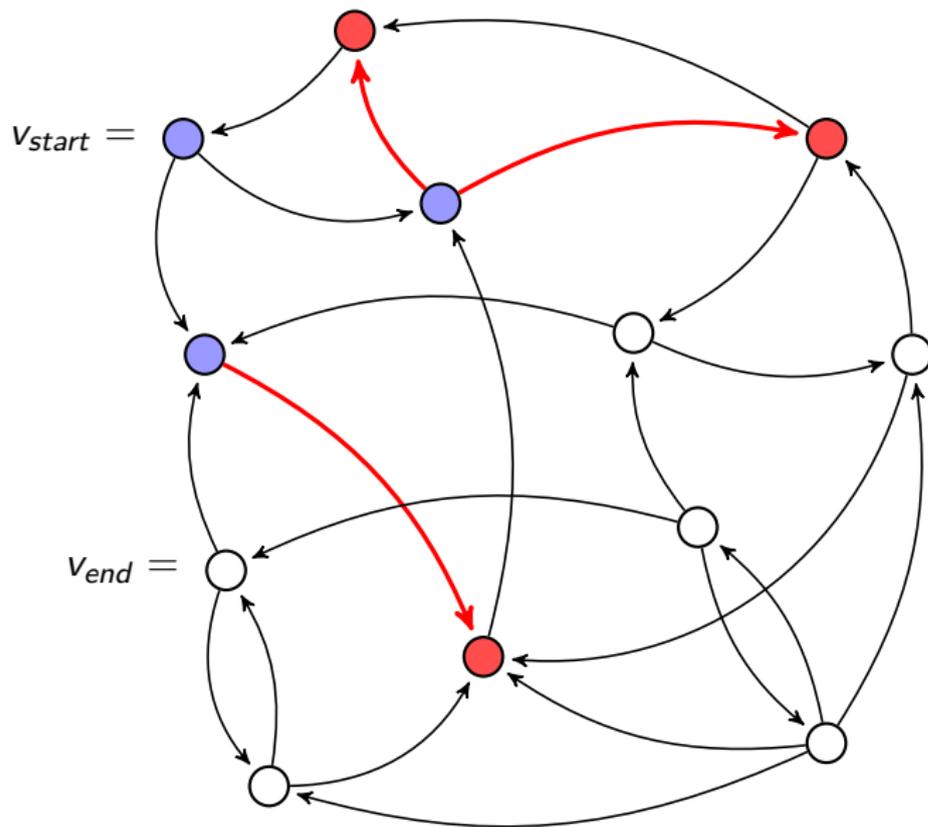
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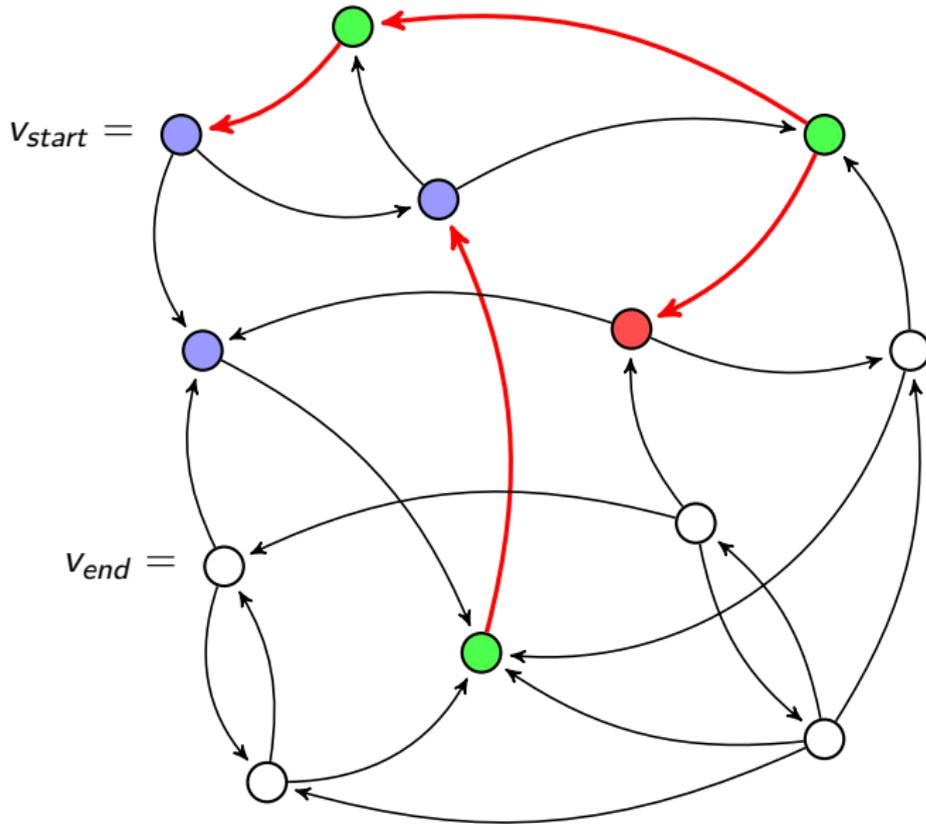


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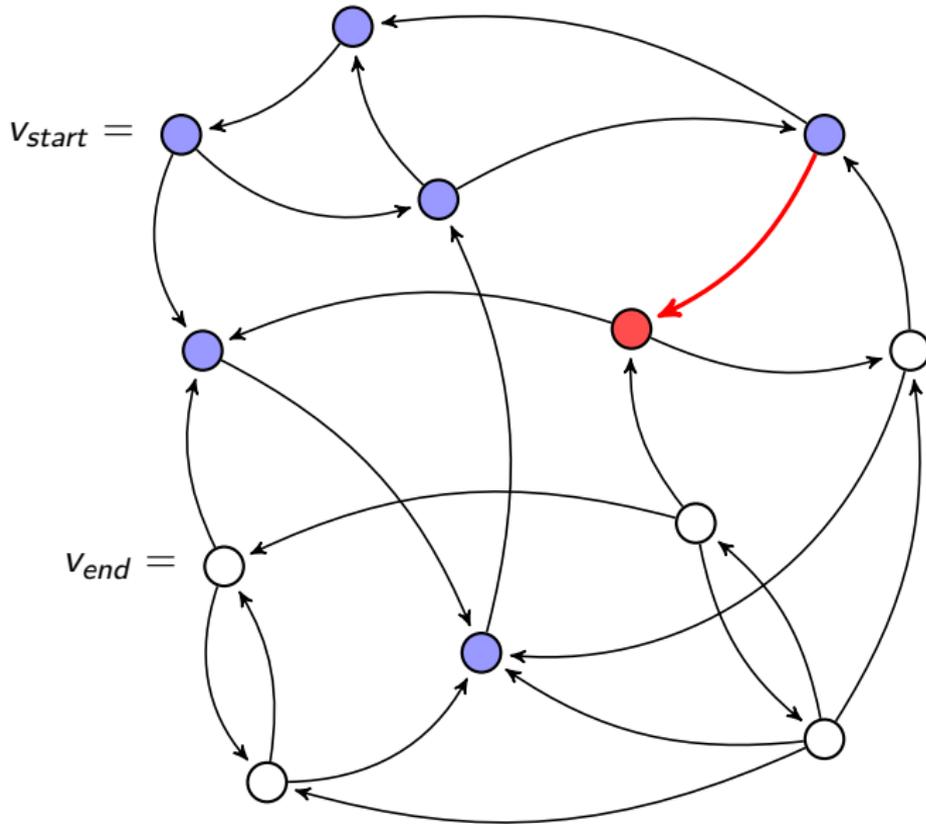




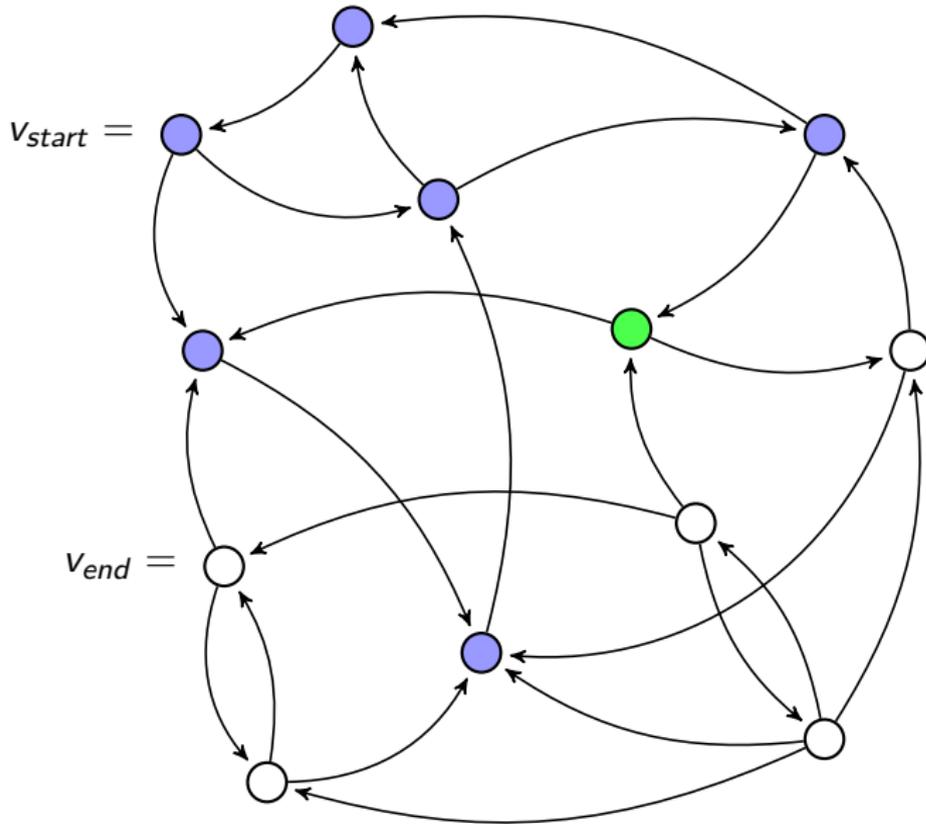
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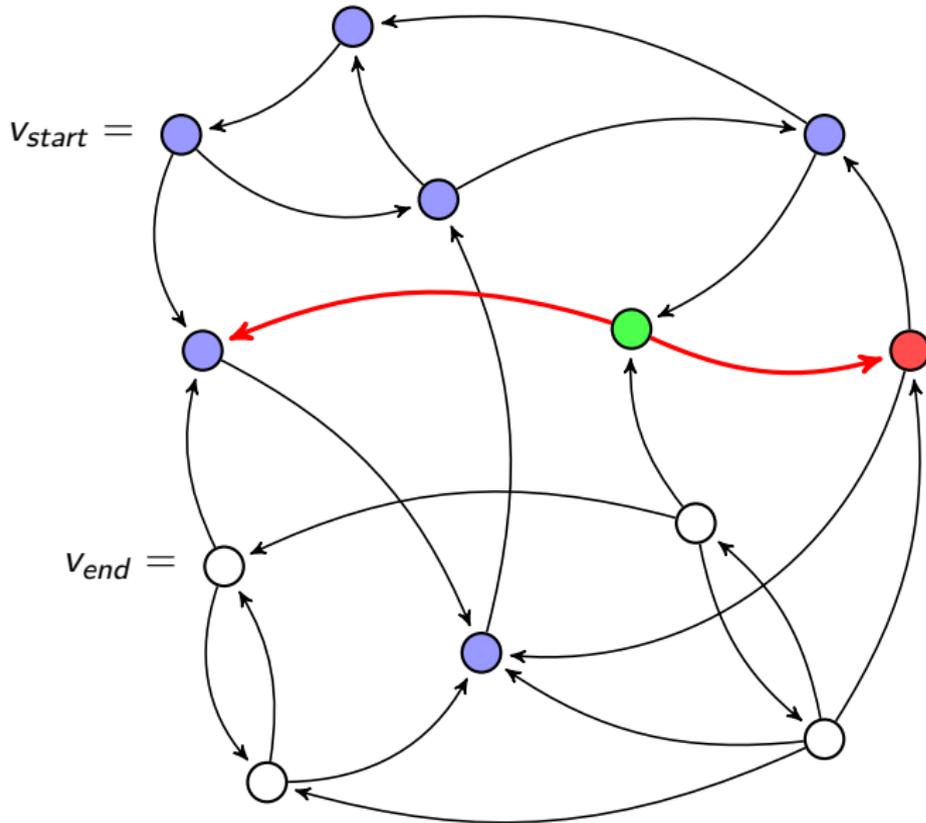
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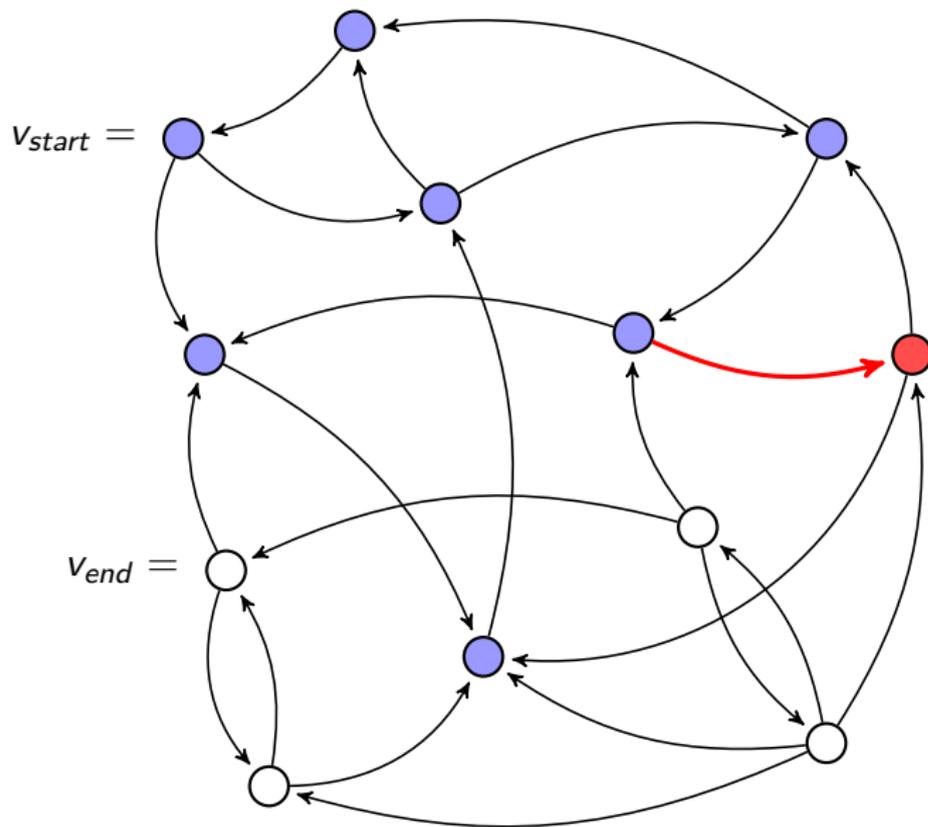
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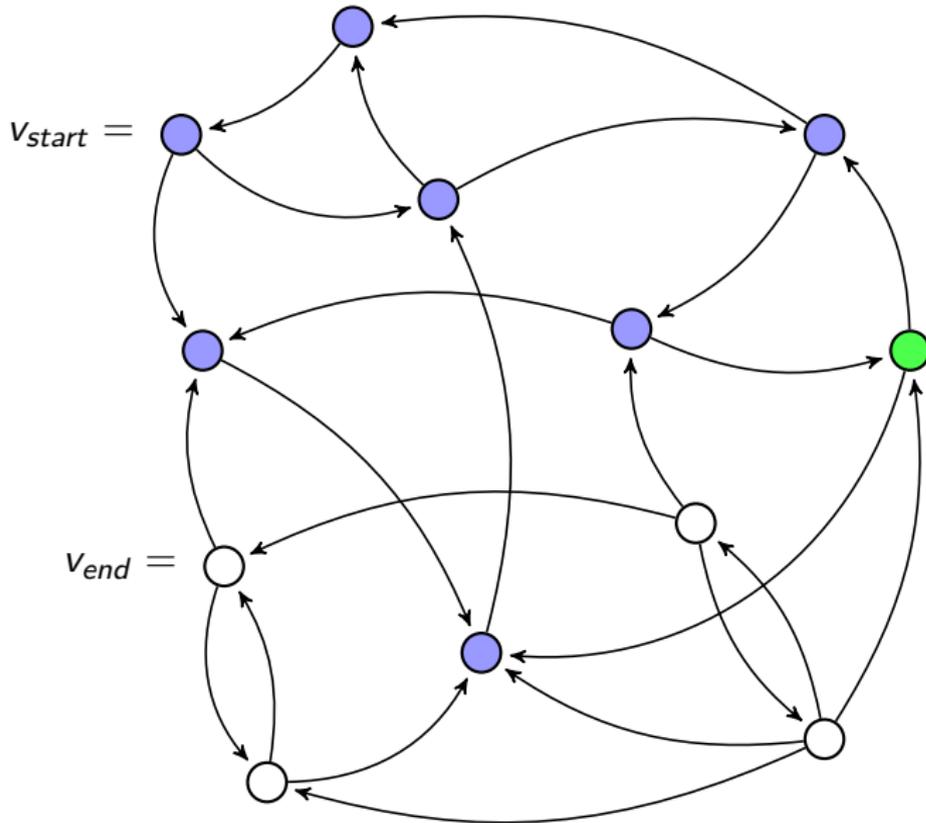
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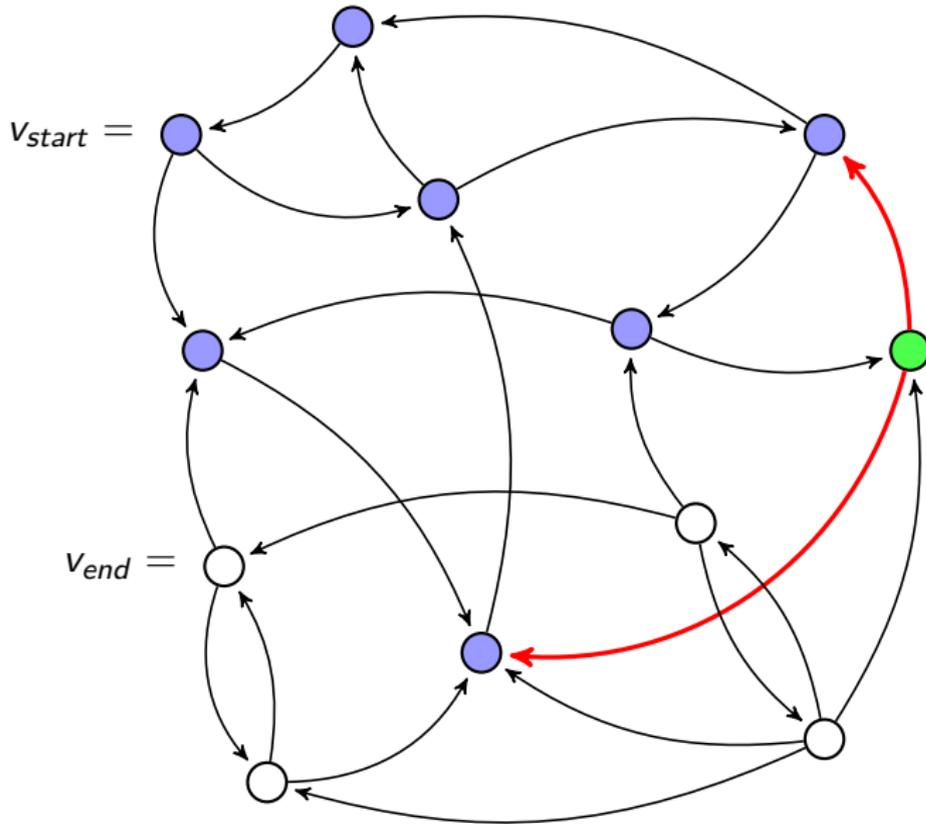
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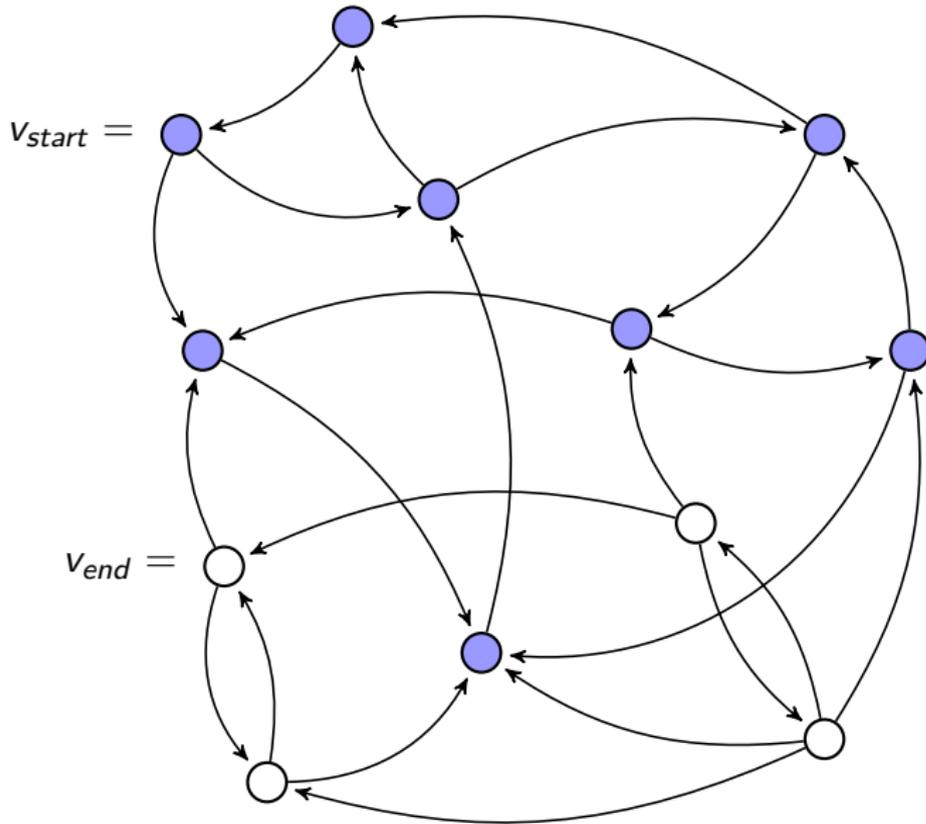
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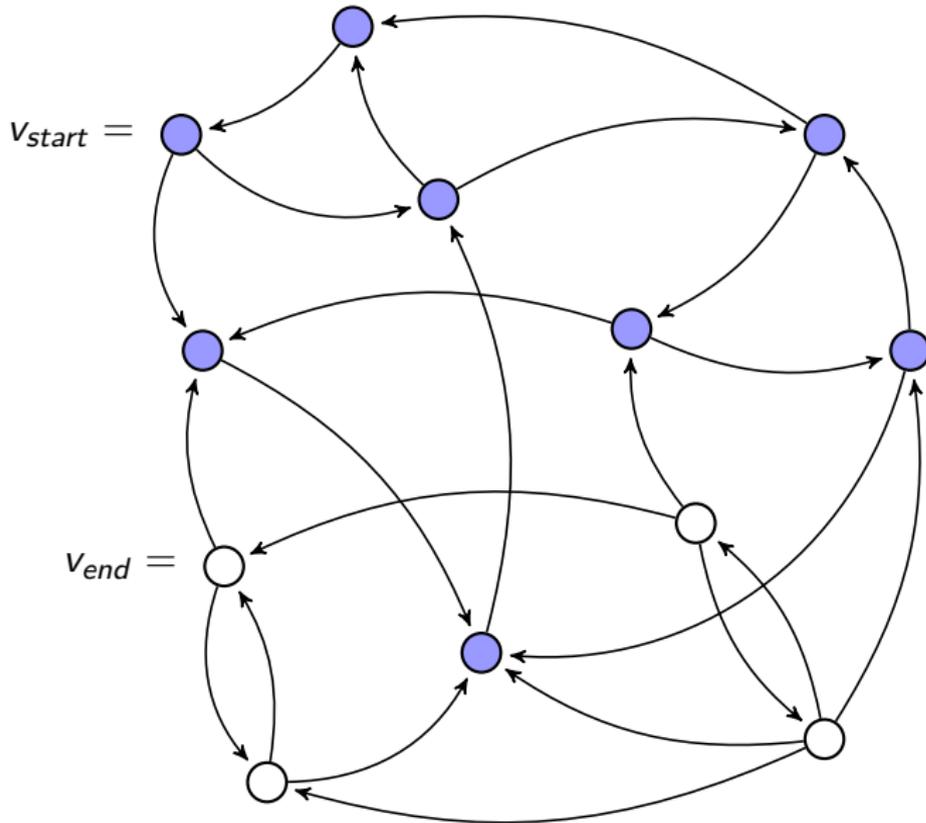
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Answer: "NO"

# Efficiency of this algorithm

How long does this algorithm take?

- I.e., how many steps ...

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How long does this algorithm take?

- I.e., how many steps ...
- ... as a function of the size of the input graph.

I'll give three answers to this.

# First answer – Heuristics

Only **action** is changing a vertex's color.

Only **changes** possible are

- white  $\Rightarrow$  red
- red  $\Rightarrow$  green
- green  $\Rightarrow$  blue.

So if  $n = |V|$ , then the algorithm requires **at most  $3n$  vertex-color changes**.

## Second answer – pseudo-code

Simplifying assumptions:

- $V = \{0, 1, \dots, n - 1\}$
- $E$  is encoded by the adjacency matrix  $M_E = [e_{i,j}]$  where

$$e_{i,j} = \begin{cases} 1 & \text{if } (i,j) \in E, \\ 0 & \text{else.} \end{cases}$$

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Auxiliary variables:

- $i, j$  will range over  $\{0, 1, \dots, n-1\}$ .
- For  $i < n$  let  $c_i$  be a variable recording the color of vertex  $i$ .
- Let *GreenVar* be a variable storing whether there are green-colored vertices.

## Second answer – pseudo-code

Algorithm:

- Input  $n$ ,  $M_E$ ,  $start$  and  $end$ .
- For  $i = 0$  to  $n - 1$  set  $c_i := white$ .
- Set  $c_{start} = green$ .
- Set  $GreenVar := yes$ .

## Second answer – pseudo-code

Algorithm:

- Input  $n$ ,  $M_E$ ,  $start$  and  $end$ .
- For  $i = 0$  to  $n - 1$  set  $c_i := white$ .
- Set  $c_{start} = green$ .
- Set  $GreenVar := yes$ .
- MAIN LOOP: While  $GreenVar = yes$  do:
  - For  $i = 0$  to  $n - 1$ ; for  $j = 0$  to  $n - 1$ 
    - if  $e_{i,j} = 1$  and  $c_i = green$  and  $c_j = white$  then set  $c_j := red$ .
  - For  $i = 0$  to  $n - 1$ 
    - If  $c_i = green$  then set  $c_i := blue$
  - Set  $GreenVar := no$
  - For  $i = 0$  to  $n - 1$ 
    - If  $c_i = red$  then (set  $c_i := green$  and set  $GreenVar := yes$ )

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    - If  $c_i = red$  then (set  $c_i := green$  and set  $GreenVar := yes$ )
- If  $c_{end} = blue$  then output YES; else output NO.

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$n$  loops

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$n$  loops  
 $n^2$  cases

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$n$  loops  
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$O(n^3)$ steps if $n =  V $
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## Third answer – machine implementation

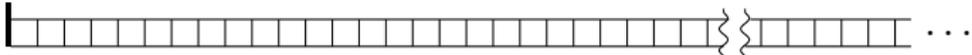
Again assume  $V = \{0, 1, \dots, n - 1\}$ .

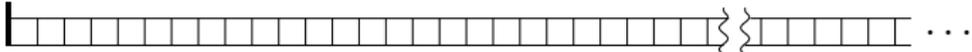
Assume also that  $v_{start} = 0$  and  $v_{end} = 1$ .

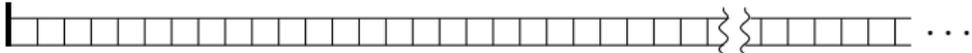
Assume the adjacency matrix is presented as a binary string of length  $n^2$ .

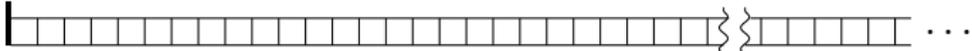
Implement the algorithm on a *Turing machine*.

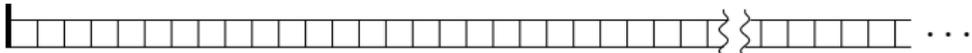
# Turing machine

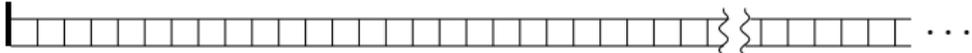
Input (ROM): 

R/W Tape 1: 

R/W Tape 2: 

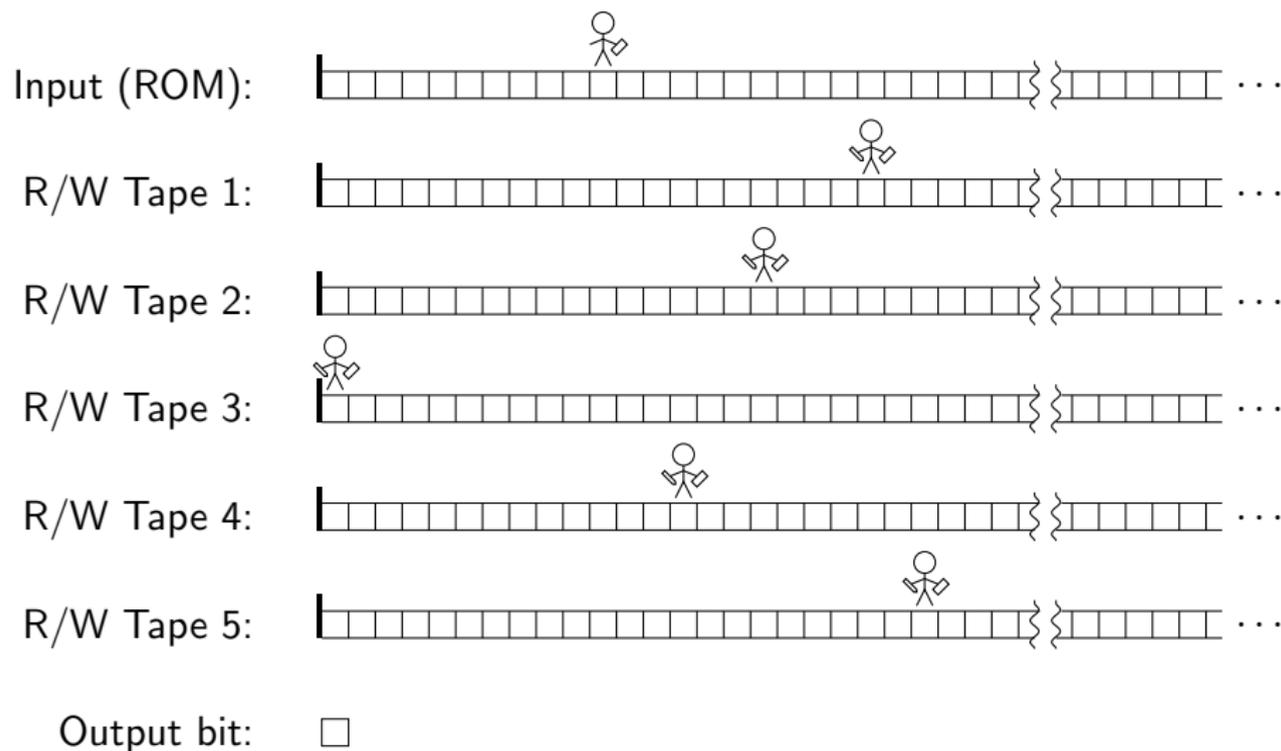
R/W Tape 3: 

R/W Tape 4: 

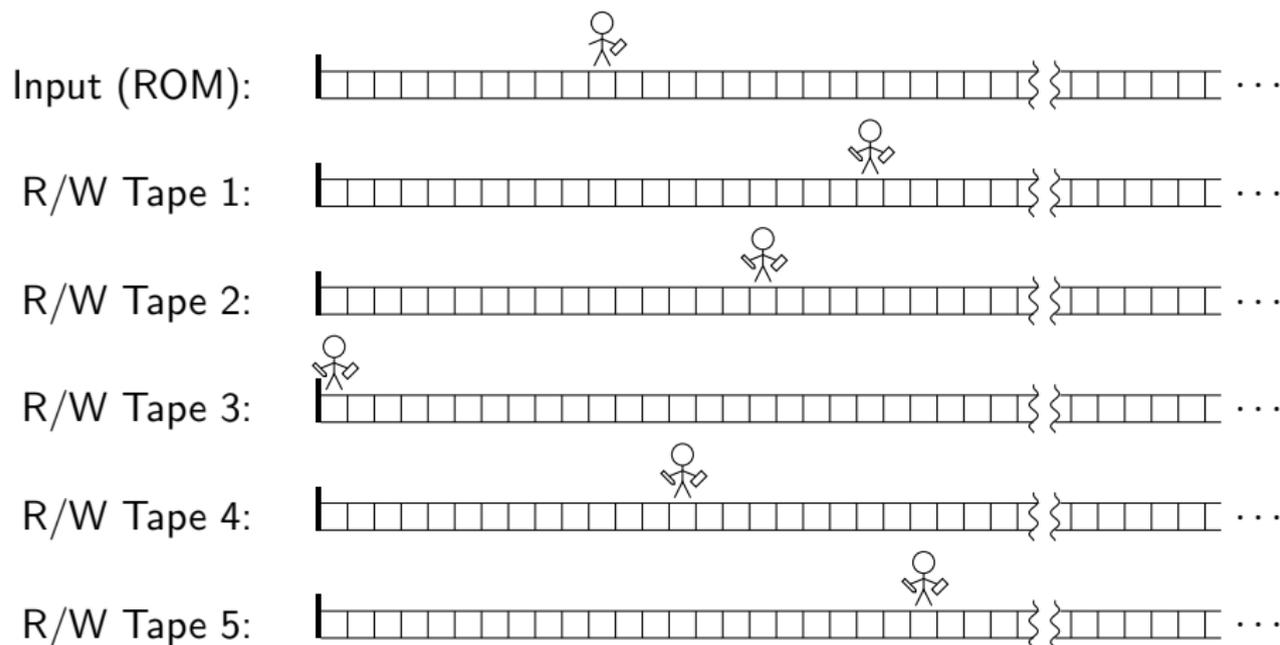
R/W Tape 5: 

Output bit:

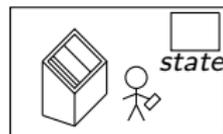
# Turing machine



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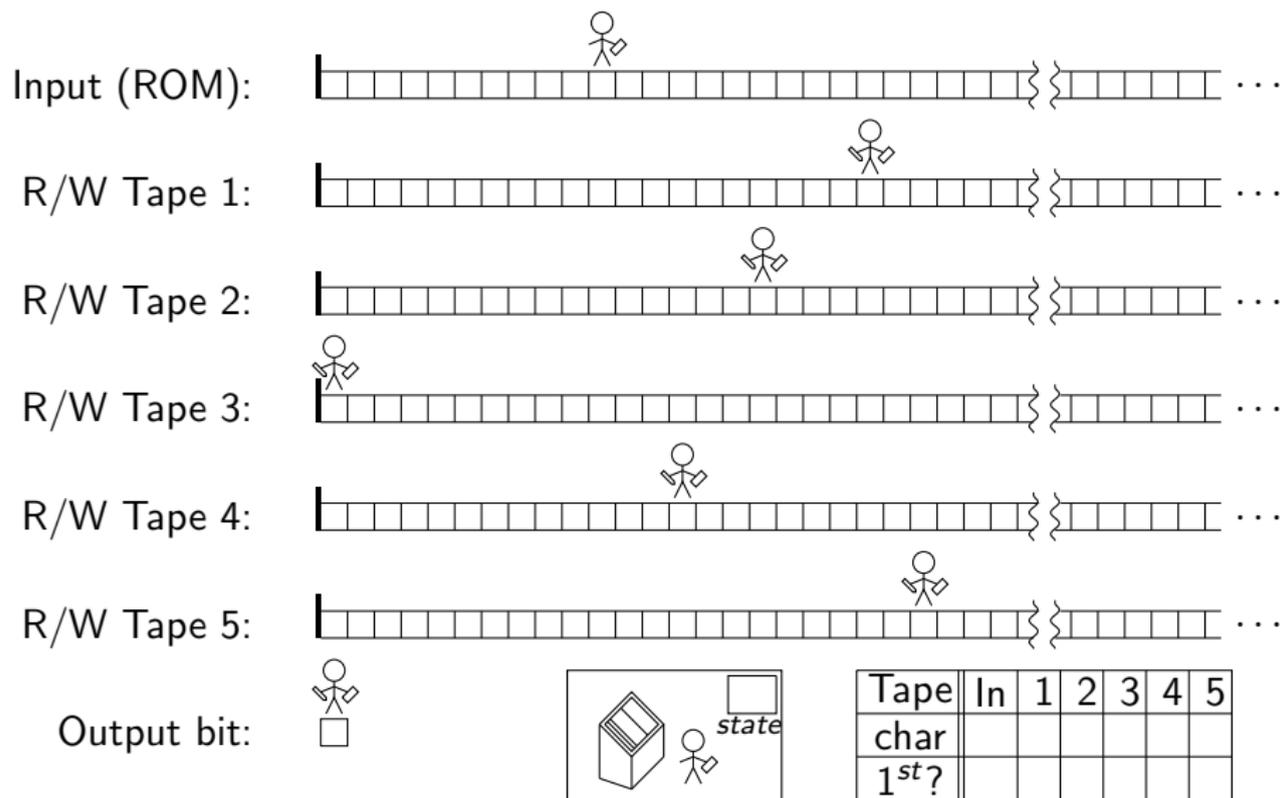


Output bit:

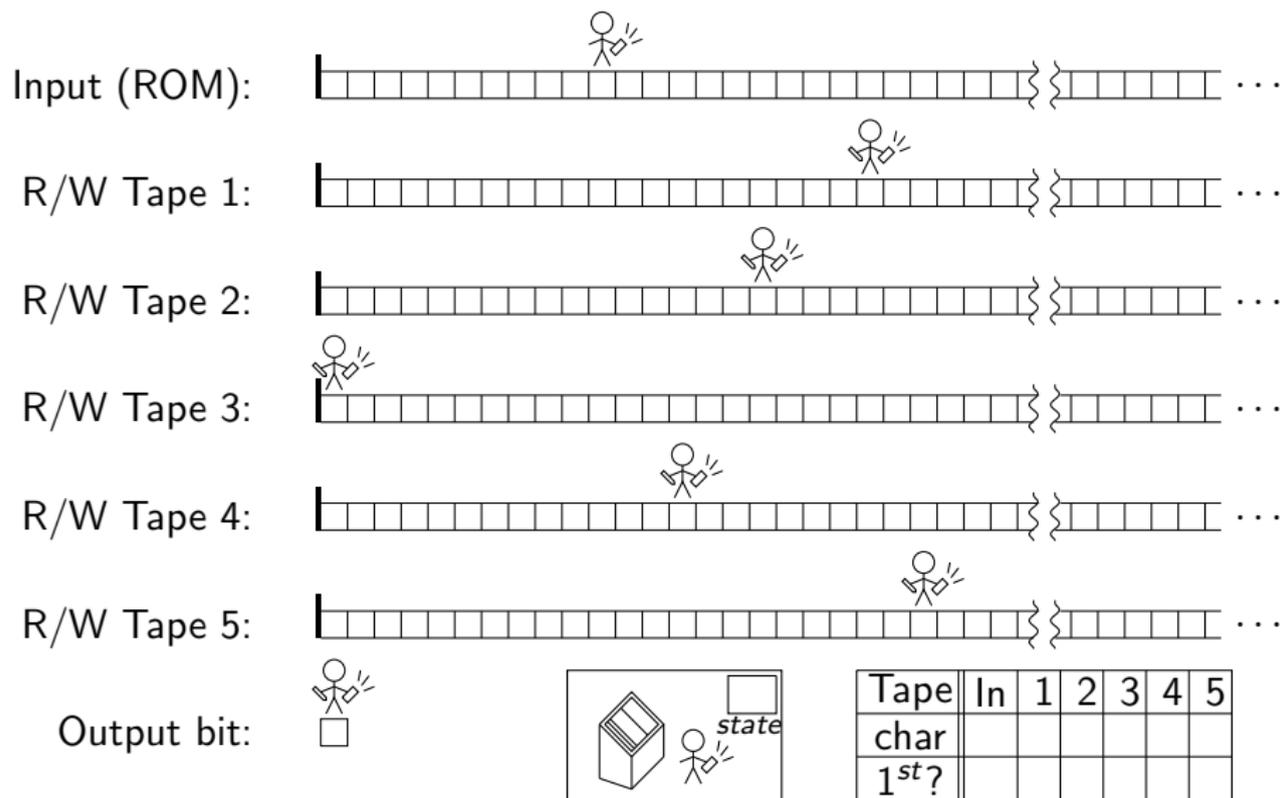


Tape	In	1	2	3	4	5
char						
1 <sup>st</sup> ?						

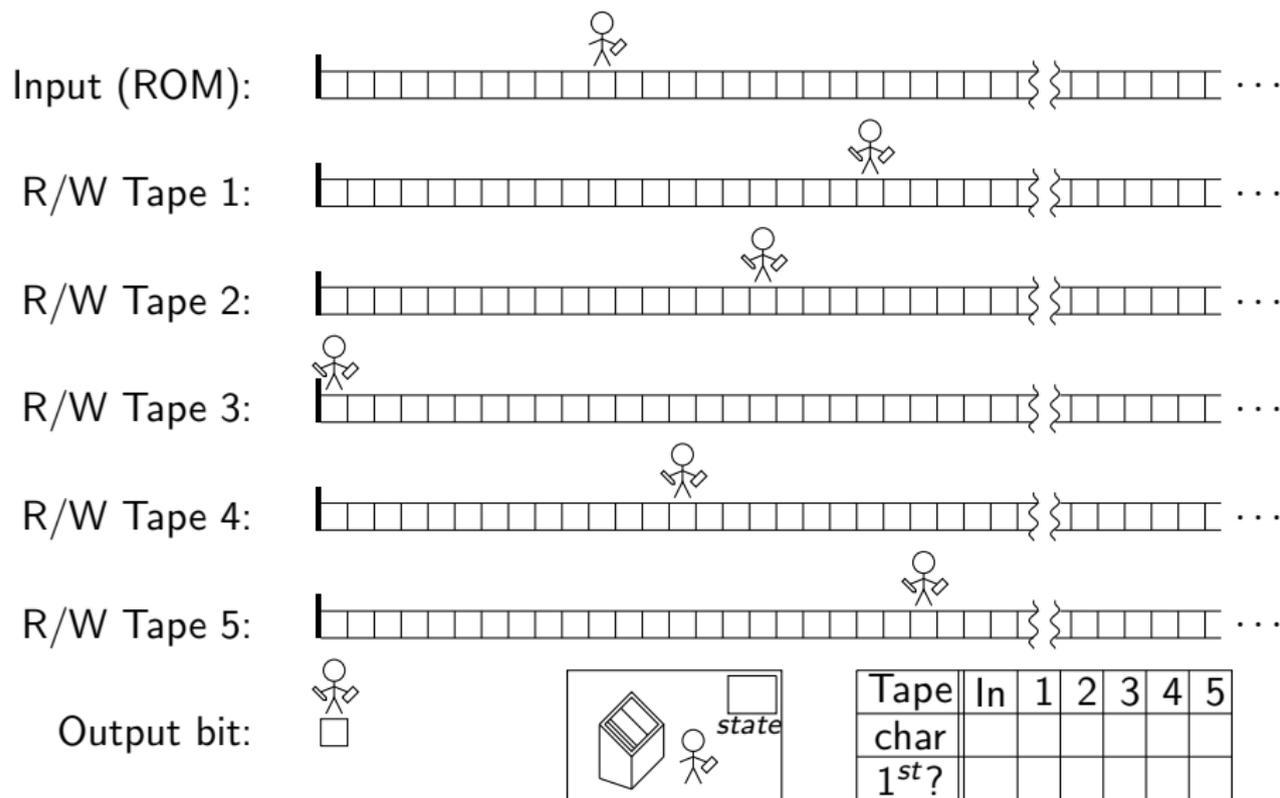
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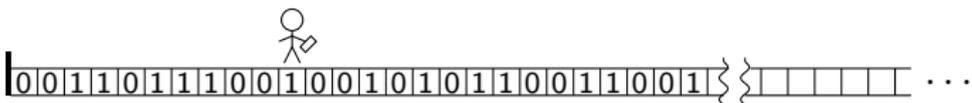
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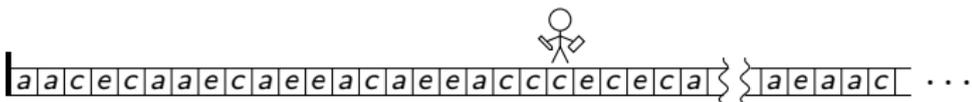


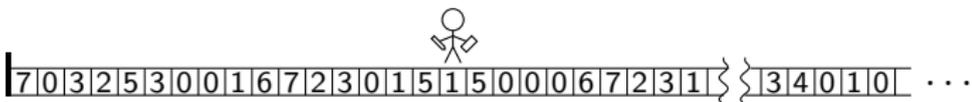
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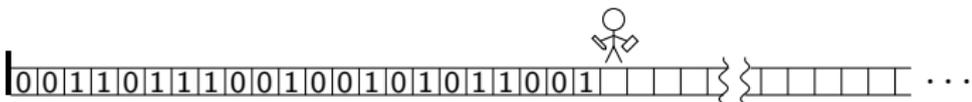
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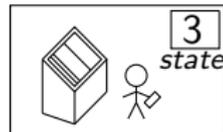
R/W Tape 2: 

R/W Tape 3: 

R/W Tape 4: 

R/W Tape 5: 

Output bit: 



Tape	In	1	2	3	4	5
char						
1 <sup>st</sup> ?						

# Turing machine

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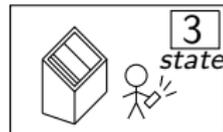
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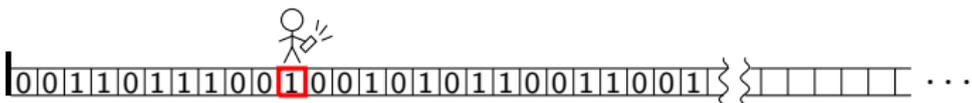
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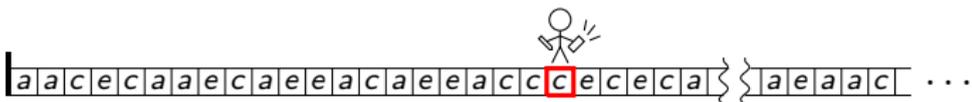


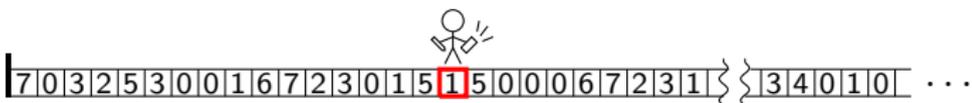
Tape	In	1	2	3	4	5
char						
1 <sup>st</sup> ?						

Prof asks for status

# Turing machine

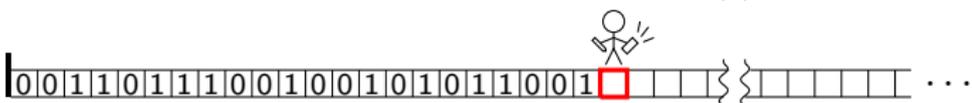
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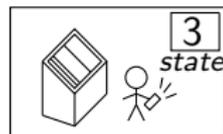
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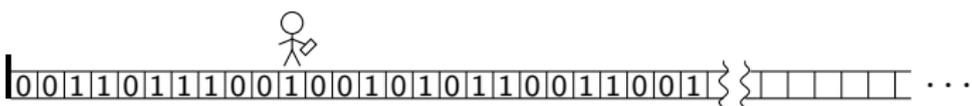
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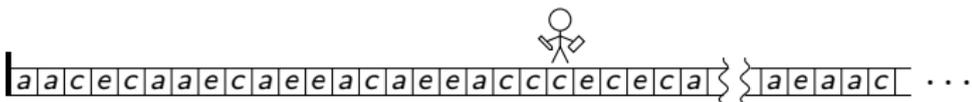


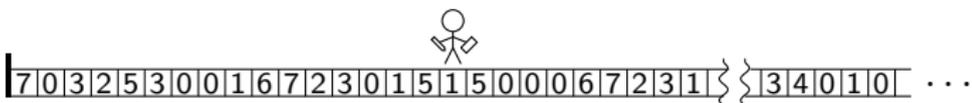
Tape	In	1	2	3	4	5
char	1	c	1	x	E	
1 <sup>st</sup> ?				✓		

Students send reports

# Turing machine

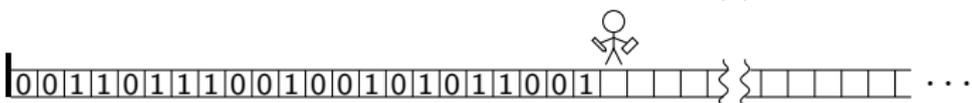
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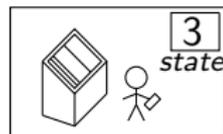
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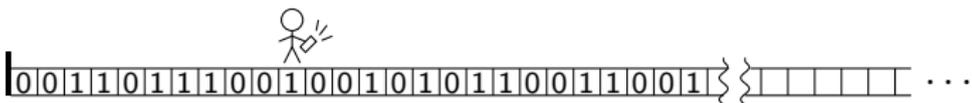
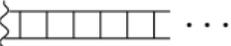
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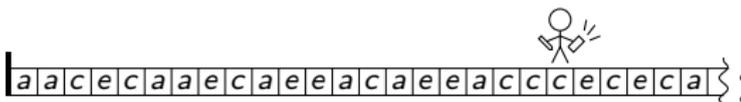
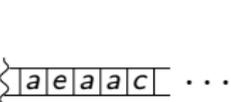


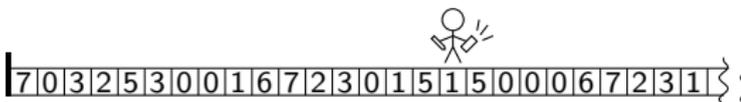
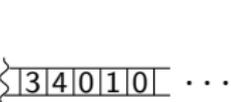
Tape	In	1	2	3	4	5
char	1	c	1	x	E	
1 <sup>st</sup> ?				✓		

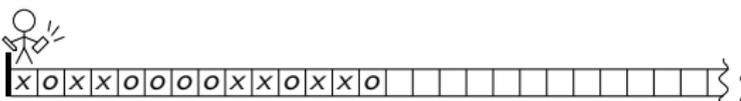
Prof consults manual

# Turing machine

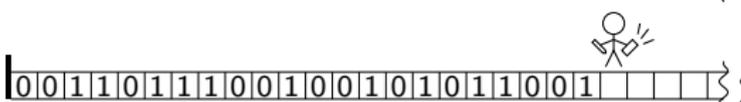
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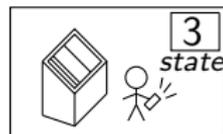
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R/W Tape 4:   ...

R/W Tape 5:   ...

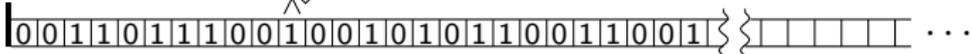
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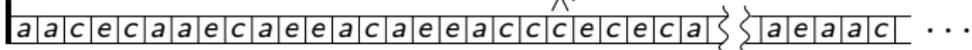


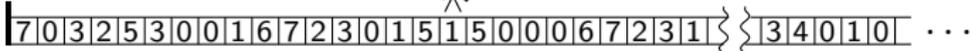
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char	1	c	1	x	E	
1 <sup>st</sup> ?				✓		

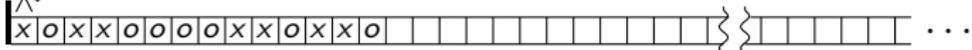
Prof sends instructions

# Turing machine

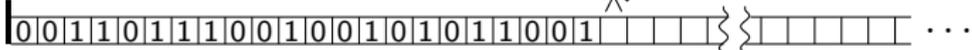
Input (ROM): 

R/W Tape 1: 

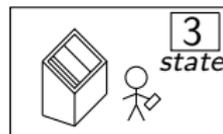
R/W Tape 2: 

R/W Tape 3: 

R/W Tape 4: 

R/W Tape 5: 

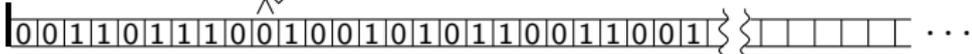
Output bit: 

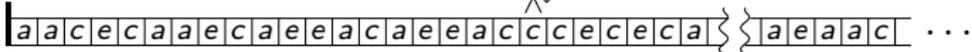


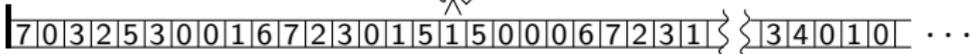
Tape	In	1	2	3	4	5
char	1	c	1	x	E	
1 <sup>st</sup> ?				✓		

Action 1: 4 writes "O".

# Turing machine

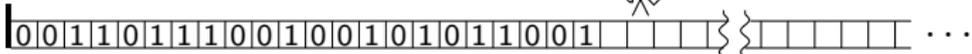
Input (ROM): 

R/W Tape 1: 

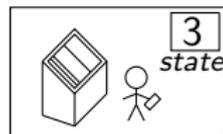
R/W Tape 2: 

R/W Tape 3: 

R/W Tape 4: 

R/W Tape 5: 

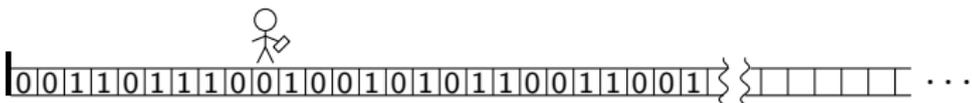
Output bit: 



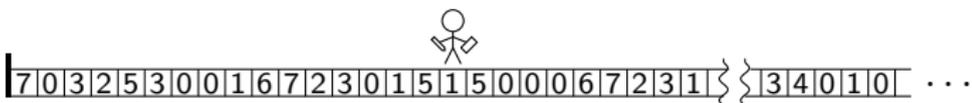
Tape	In	1	2	3	4	5
char	1	c	1	x	E	
1 <sup>st</sup> ?				✓		

Action 2: Students move as directed

# Turing machine

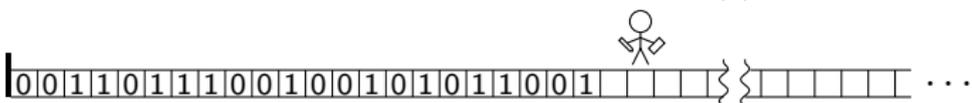
Input (ROM):   $\{ \}$   $\{ \}$  ...

R/W Tape 1:   $\{ \}$   $\{ \}$  ...

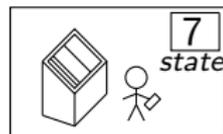
R/W Tape 2:   $\{ \}$   $\{ \}$  ...

R/W Tape 3:   $\{ \}$   $\{ \}$  ...

R/W Tape 4:   $\{ \}$   $\{ \}$  ...

R/W Tape 5:   $\{ \}$   $\{ \}$  ...

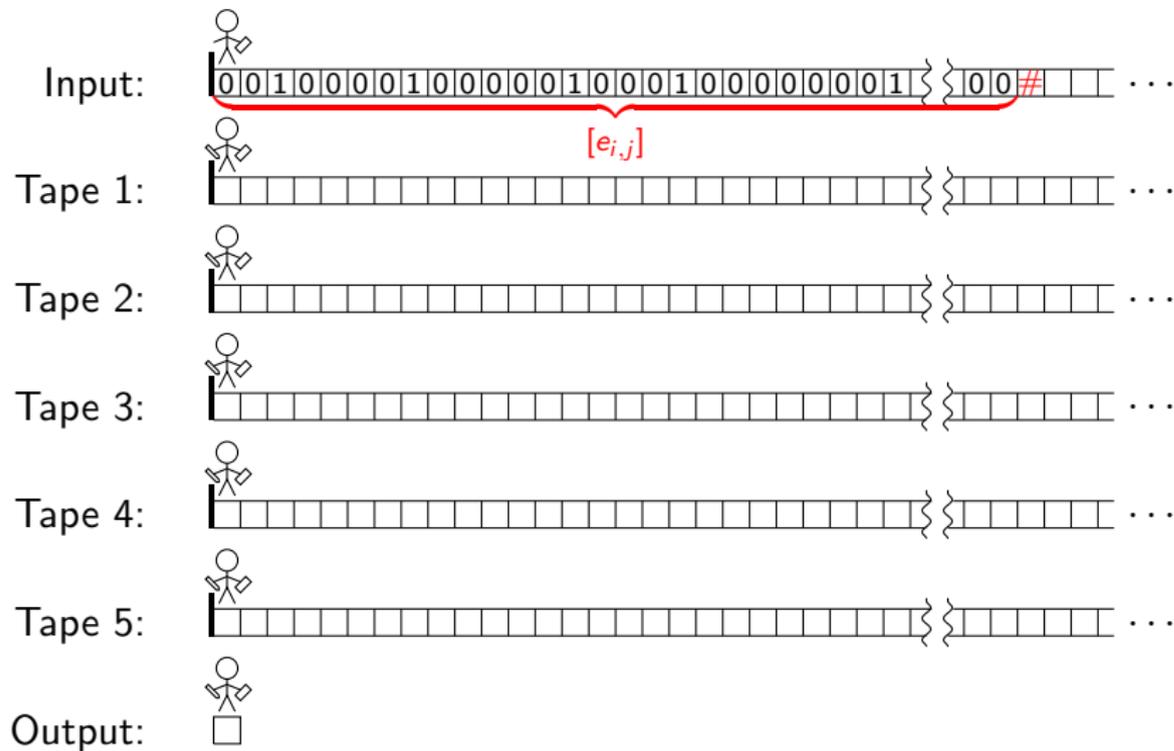
Output bit: 



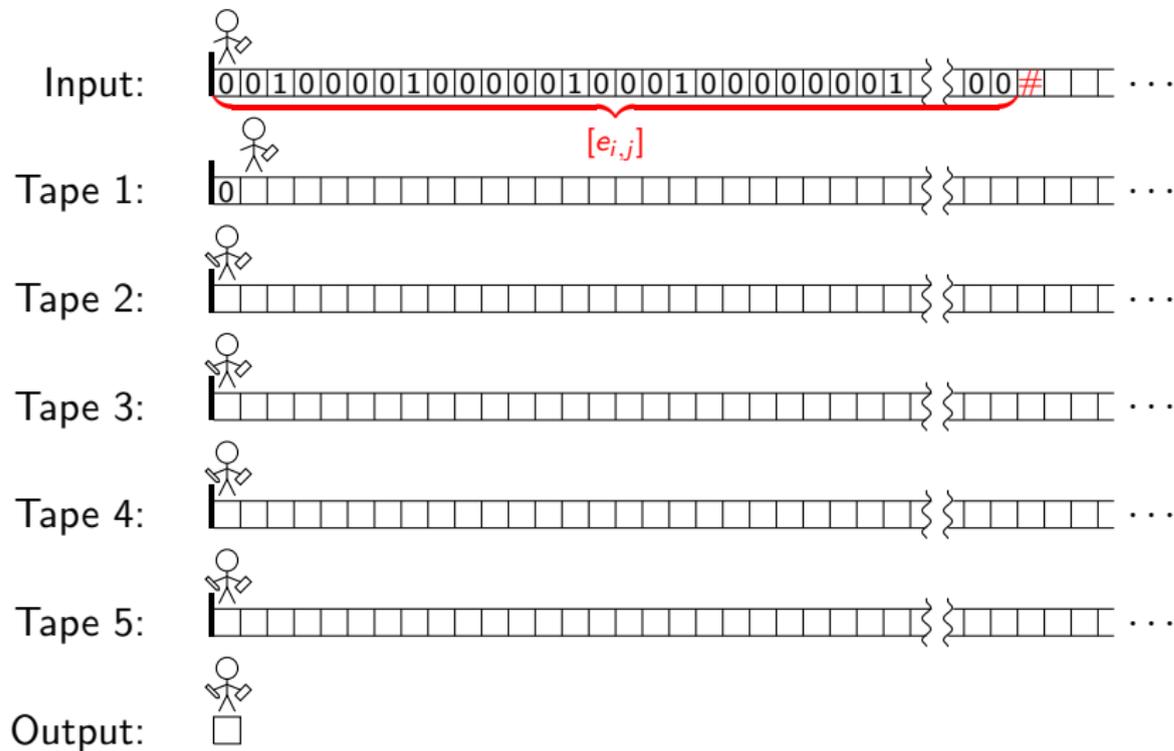
Tape	In	1	2	3	4	5
char						
1 <sup>st</sup> ?						

Action 3: Update state, ready for next "step"

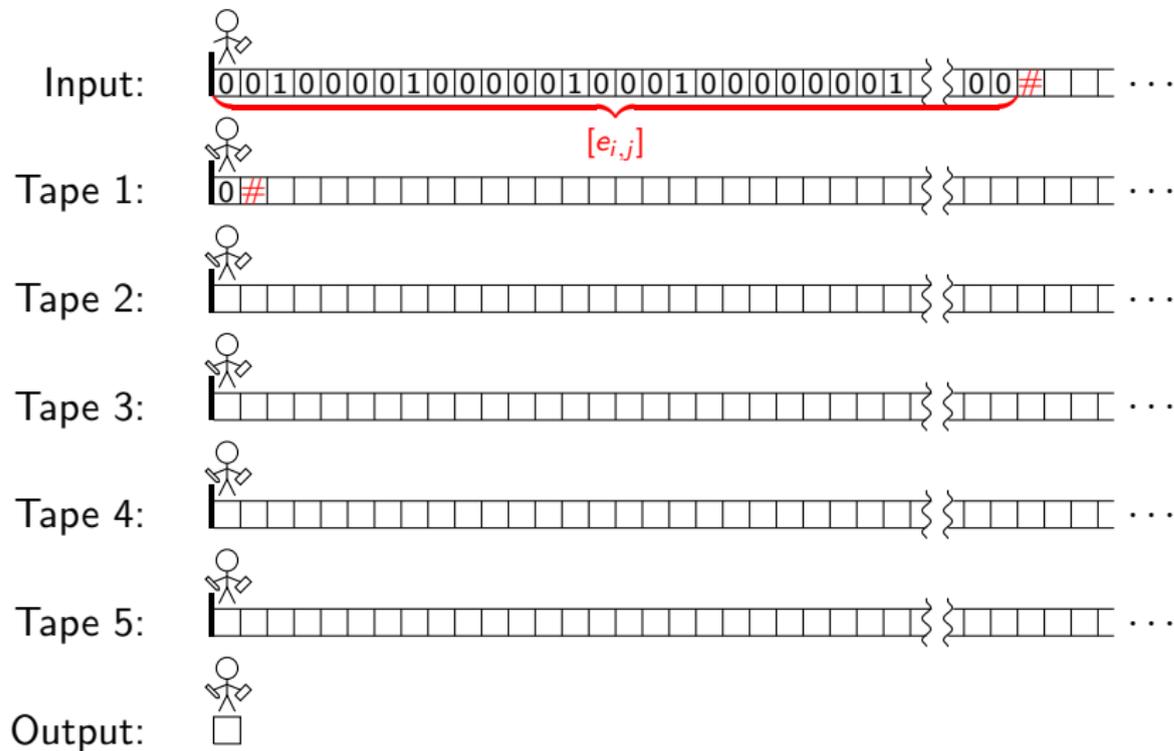
# Implementing the algorithm for *PATH*



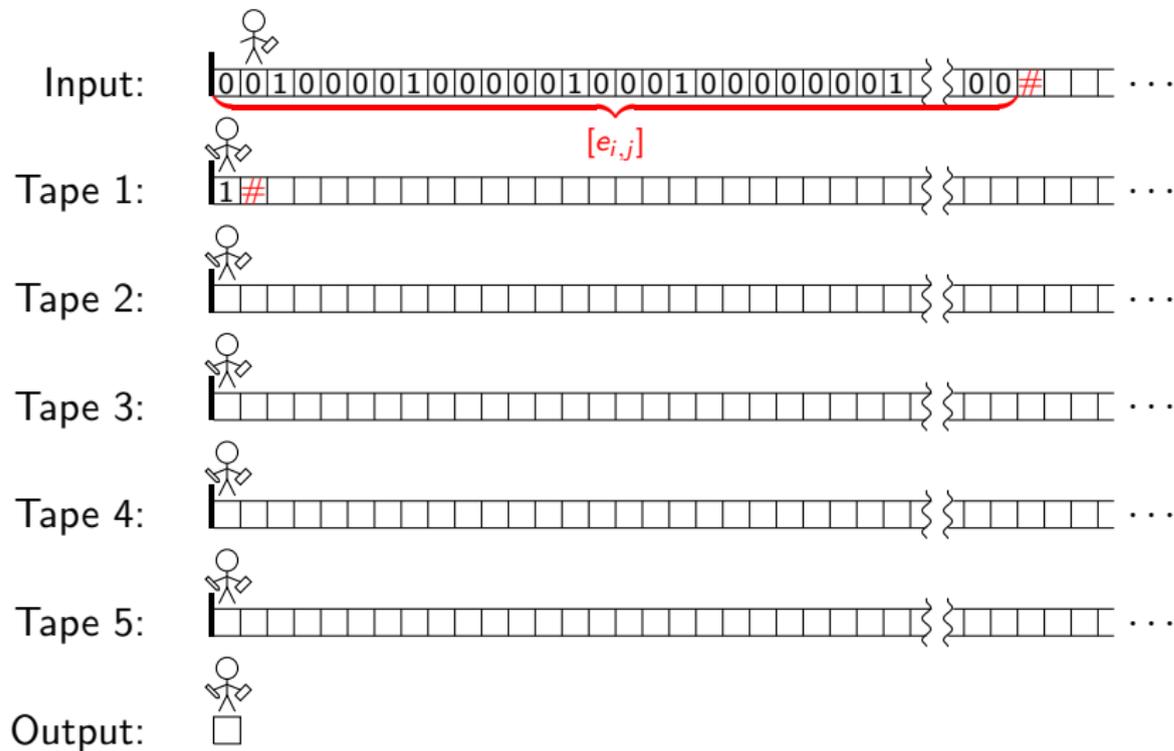
# Implementing the algorithm for *PATH*



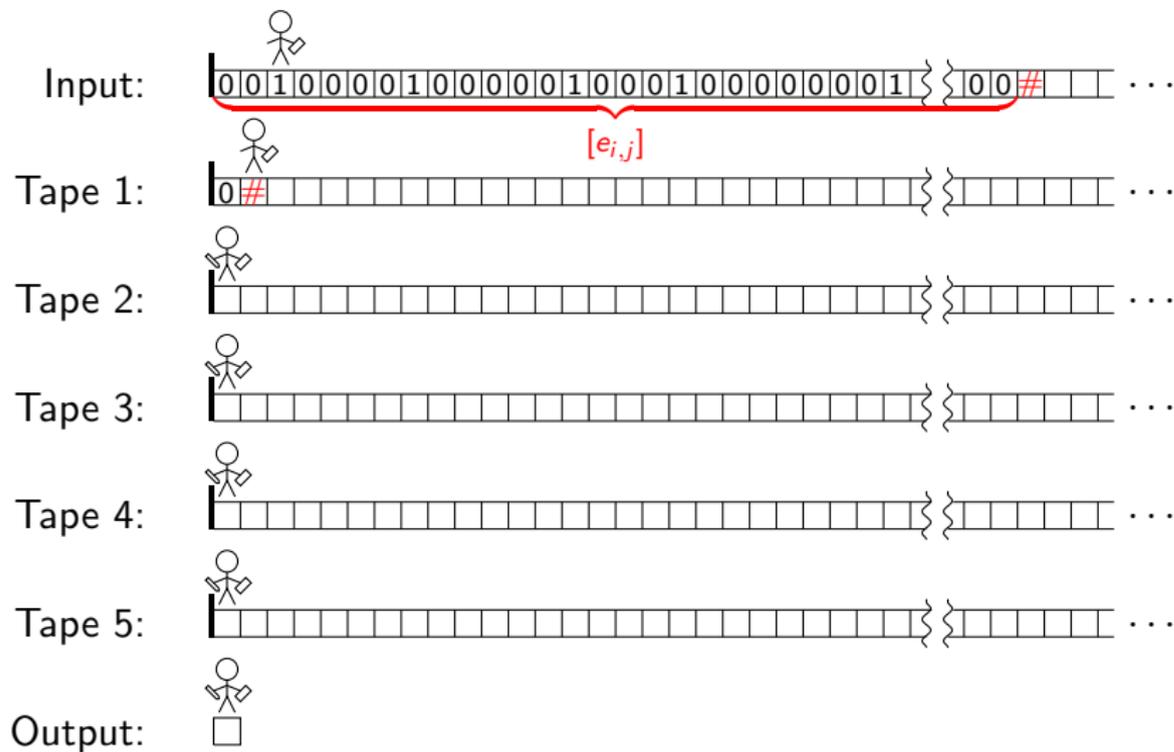
# Implementing the algorithm for *PATH*



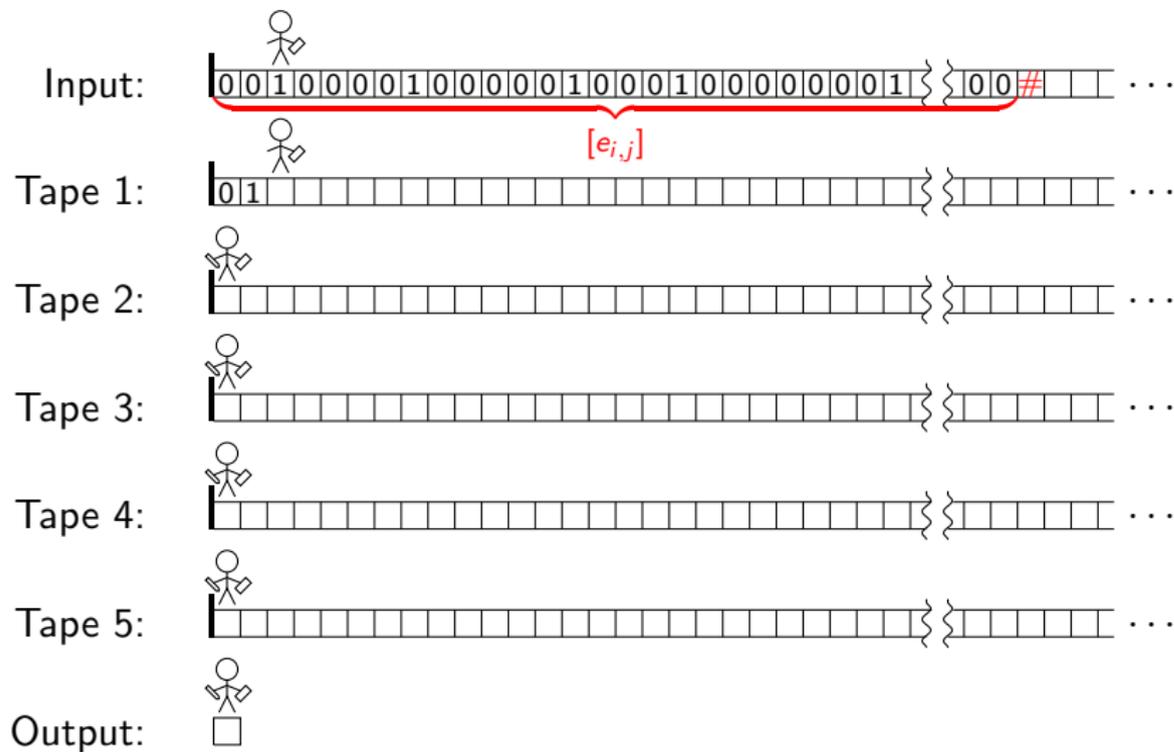
# Implementing the algorithm for *PATH*



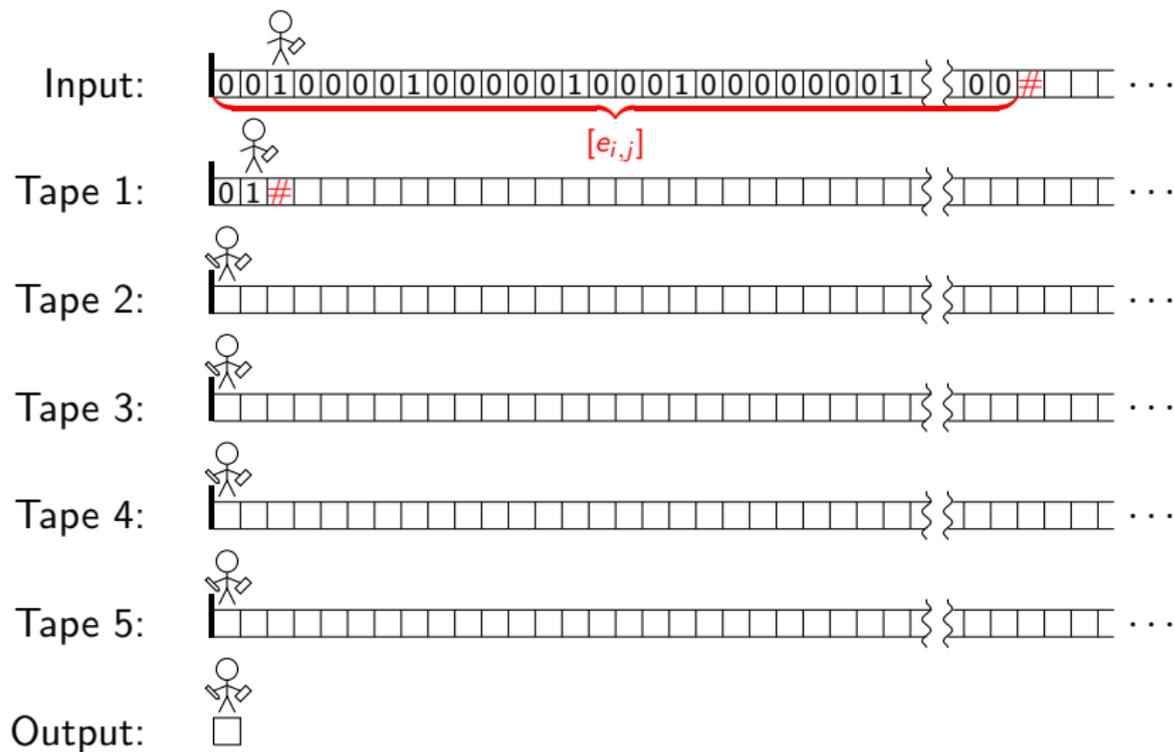
# Implementing the algorithm for *PATH*



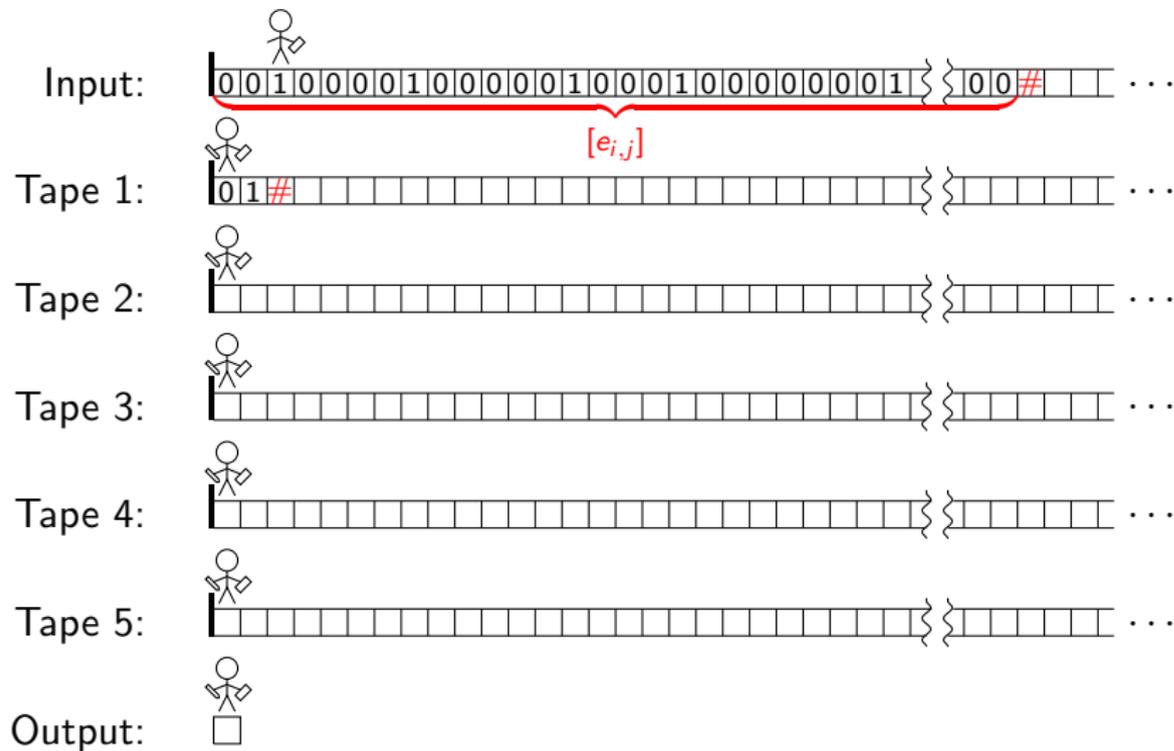
# Implementing the algorithm for *PATH*



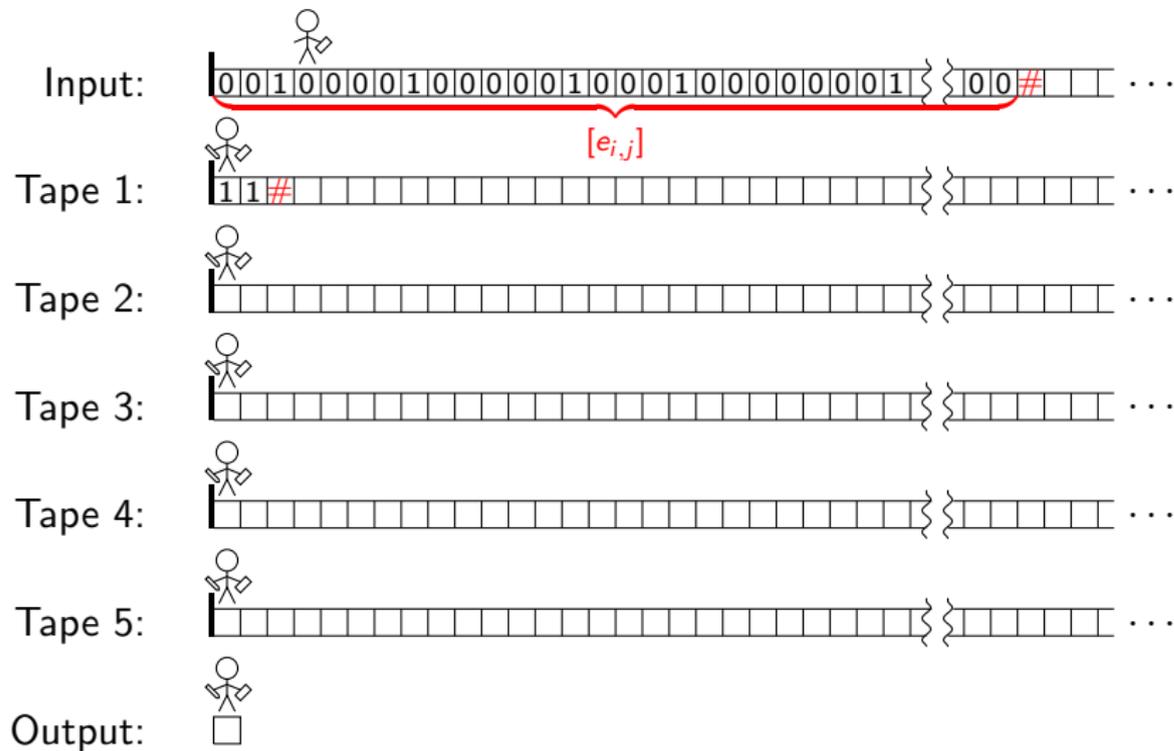
# Implementing the algorithm for *PATH*



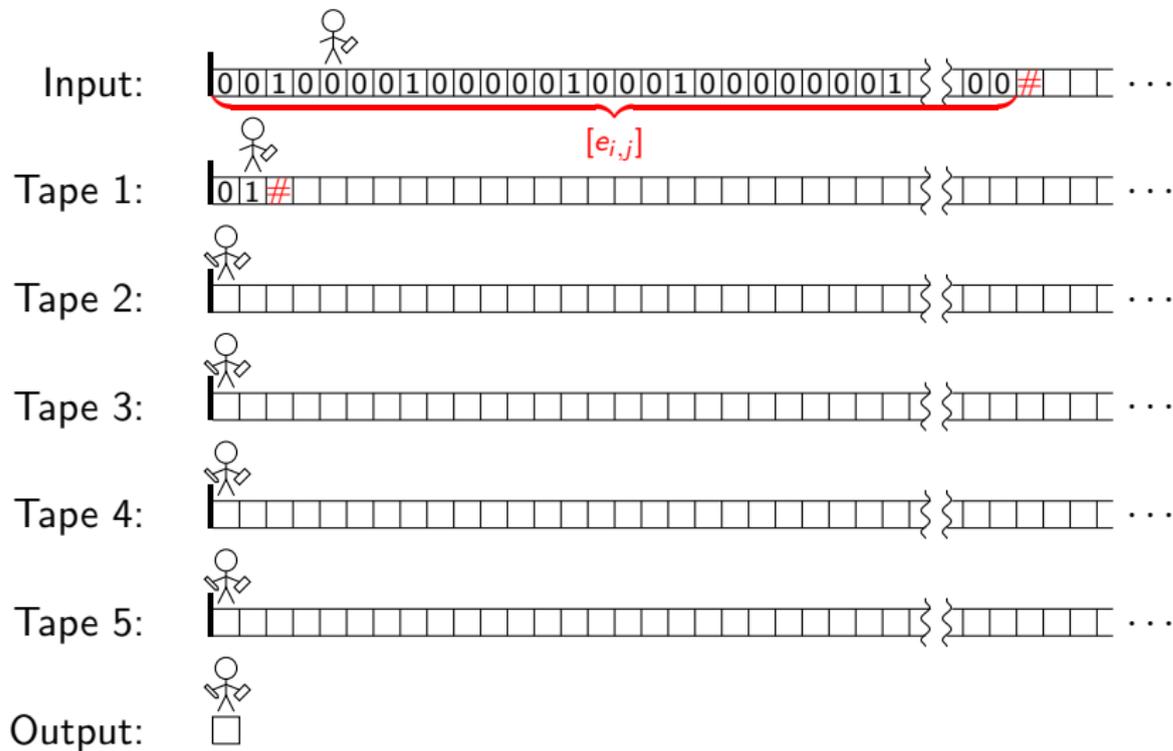
# Implementing the algorithm for *PATH*



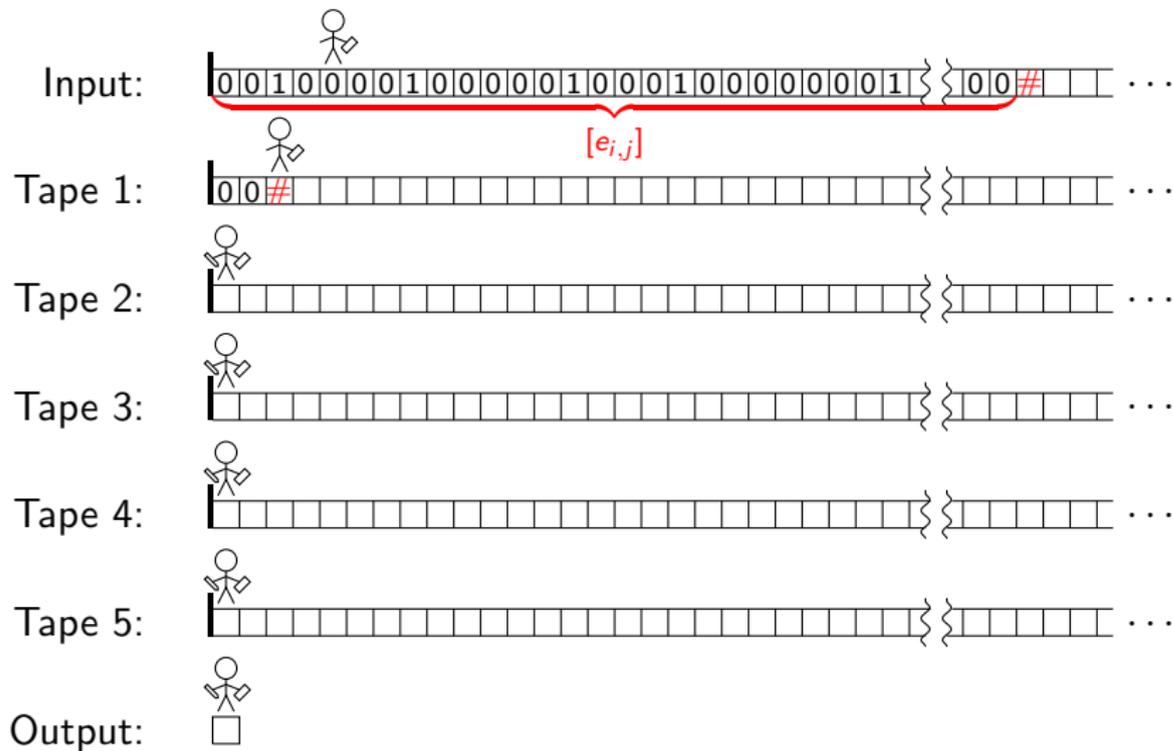
# Implementing the algorithm for *PATH*



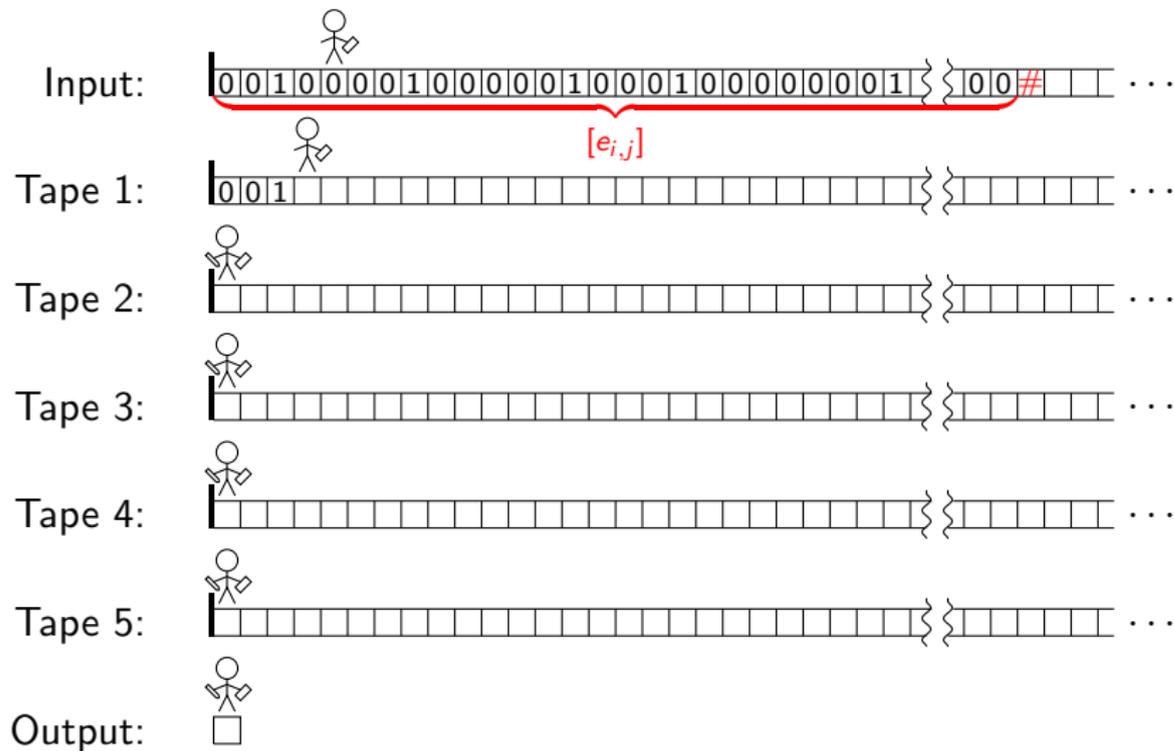
# Implementing the algorithm for *PATH*



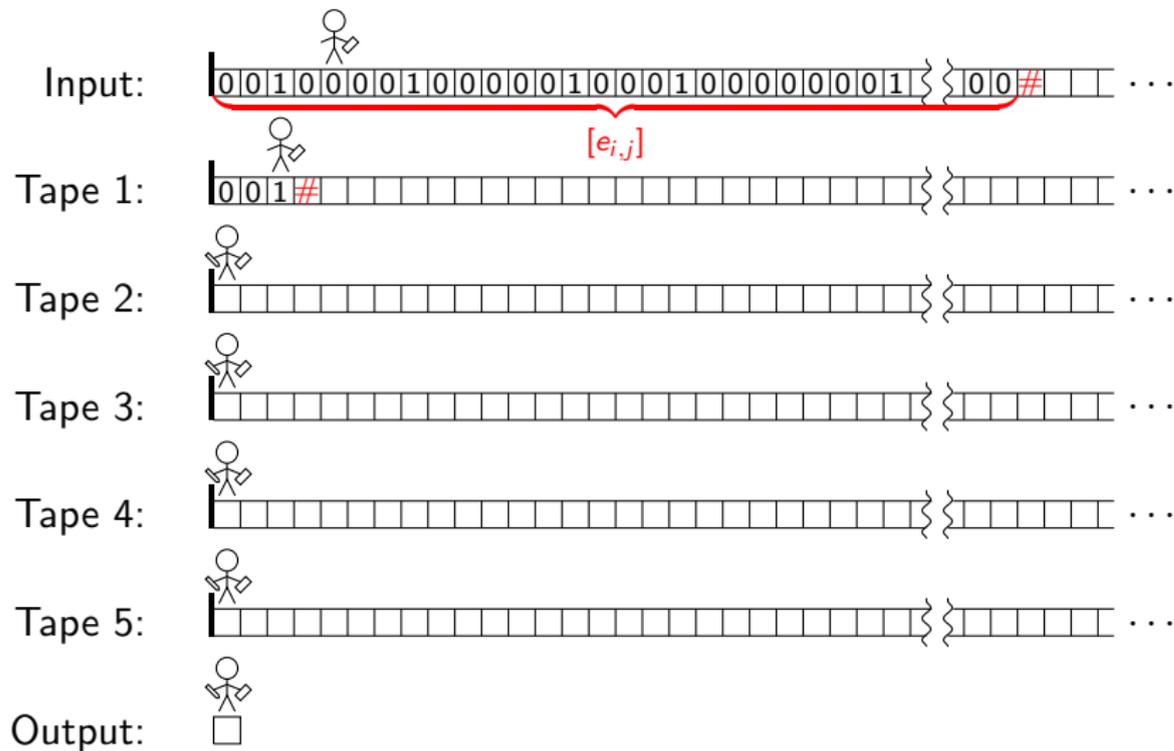
# Implementing the algorithm for *PATH*



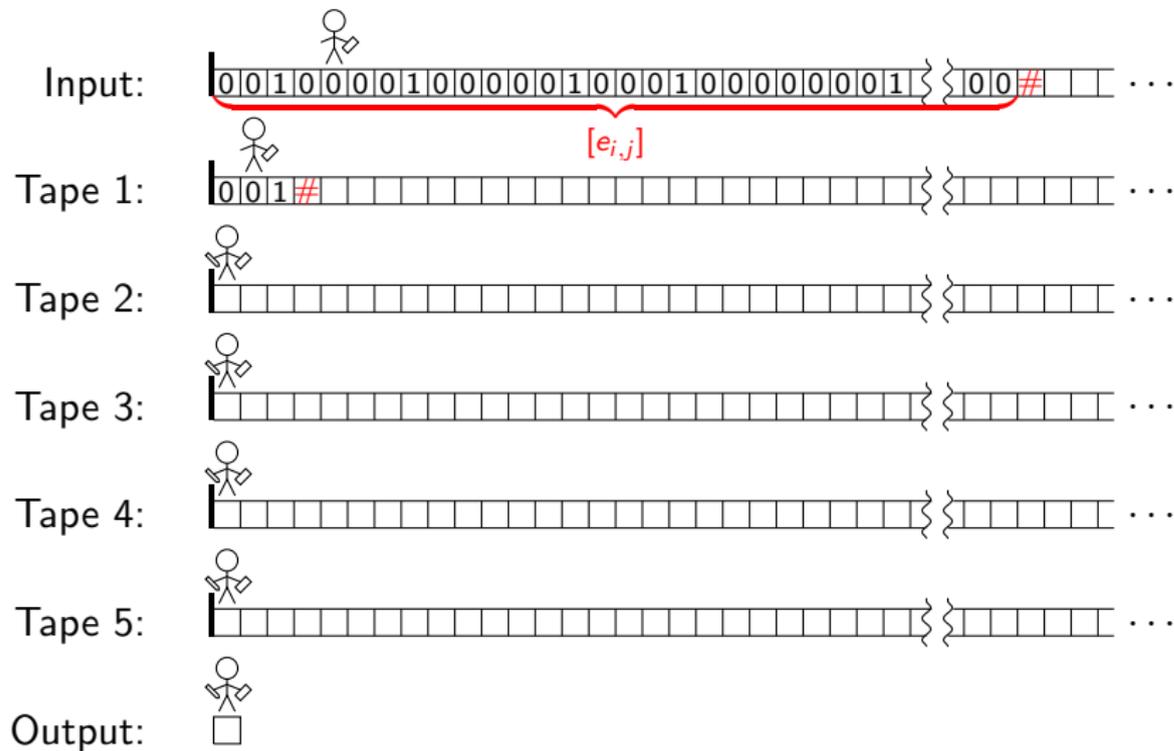
# Implementing the algorithm for *PATH*



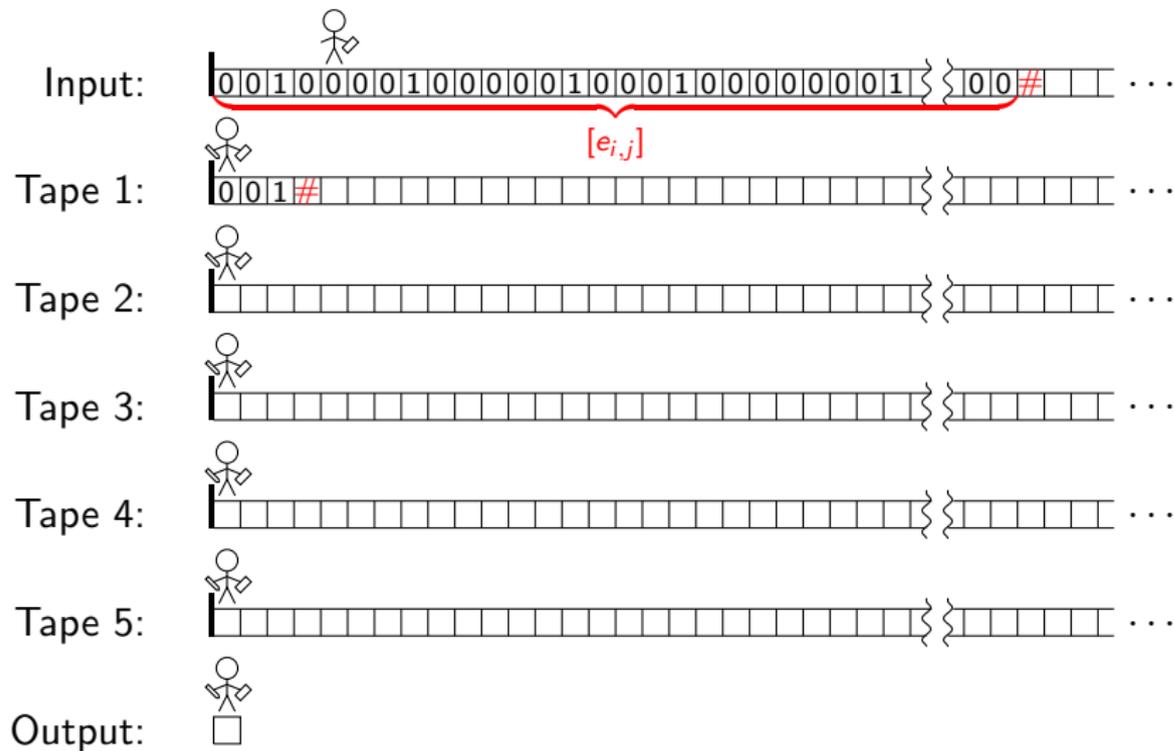
# Implementing the algorithm for *PATH*



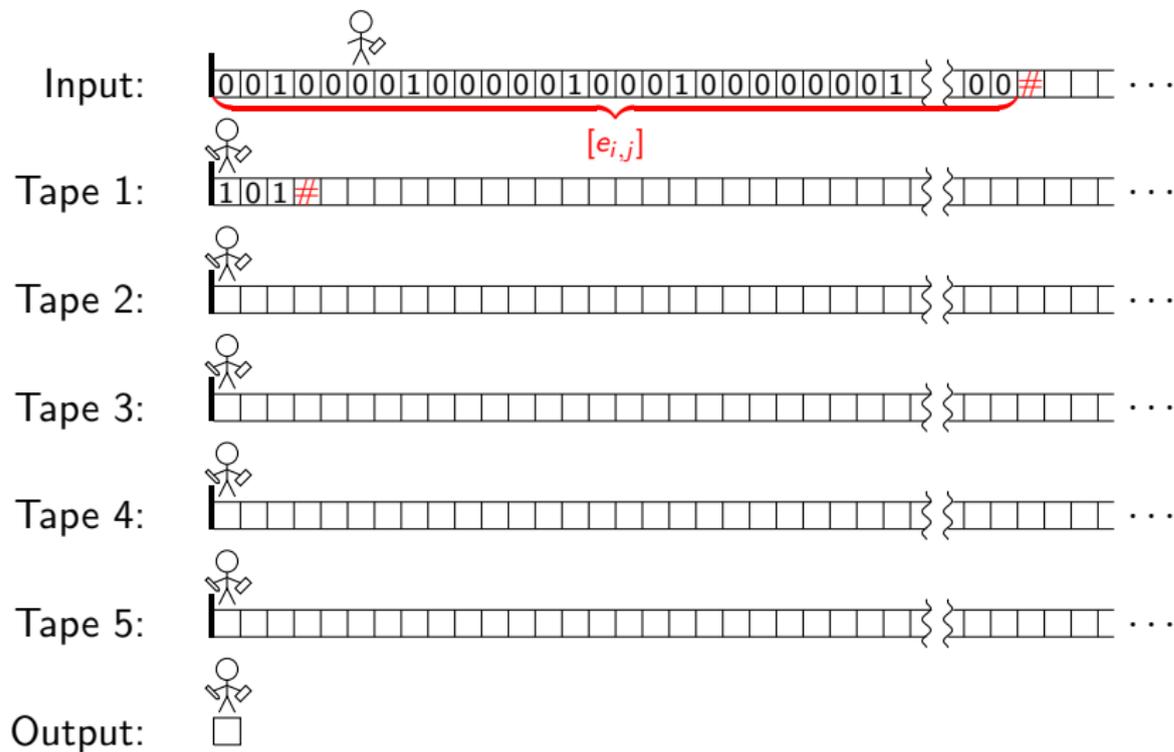
# Implementing the algorithm for *PATH*



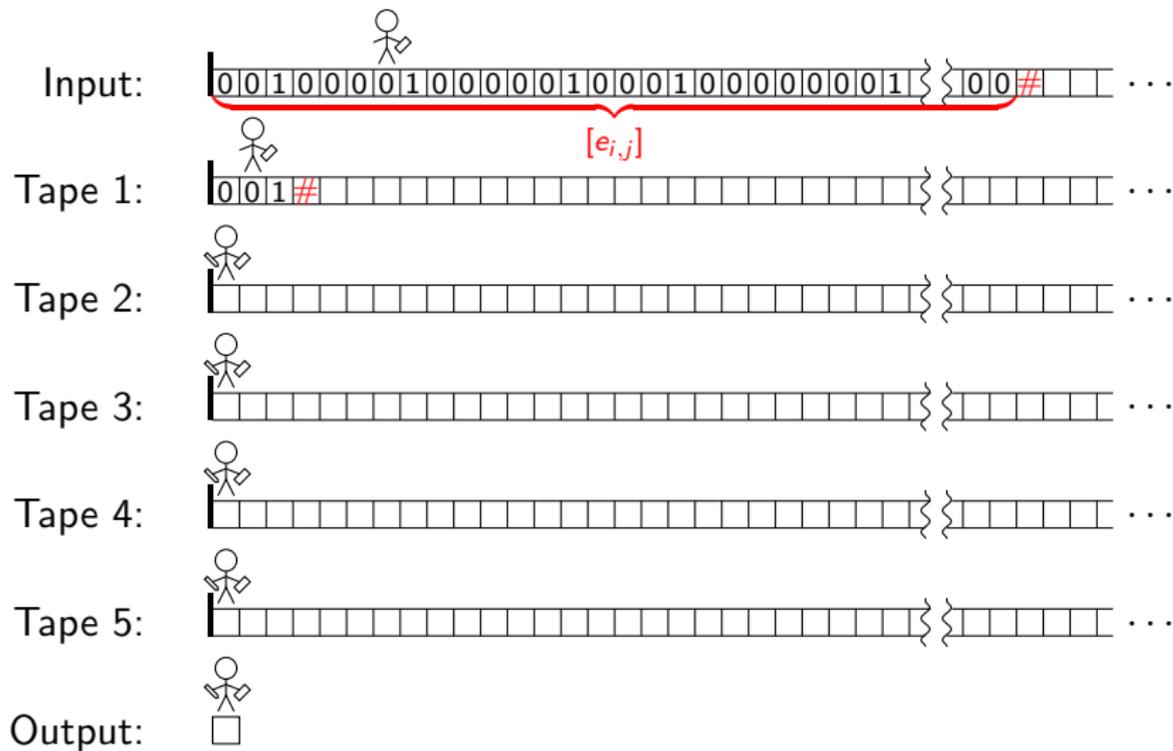
# Implementing the algorithm for *PATH*



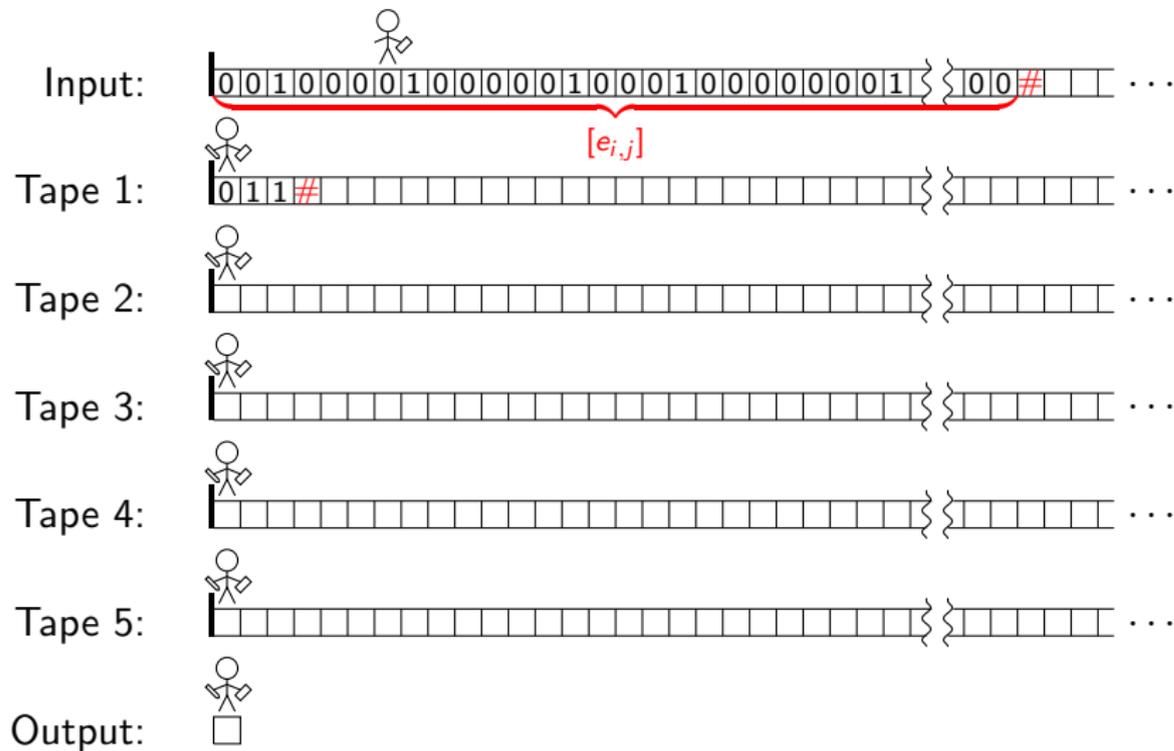
# Implementing the algorithm for *PATH*



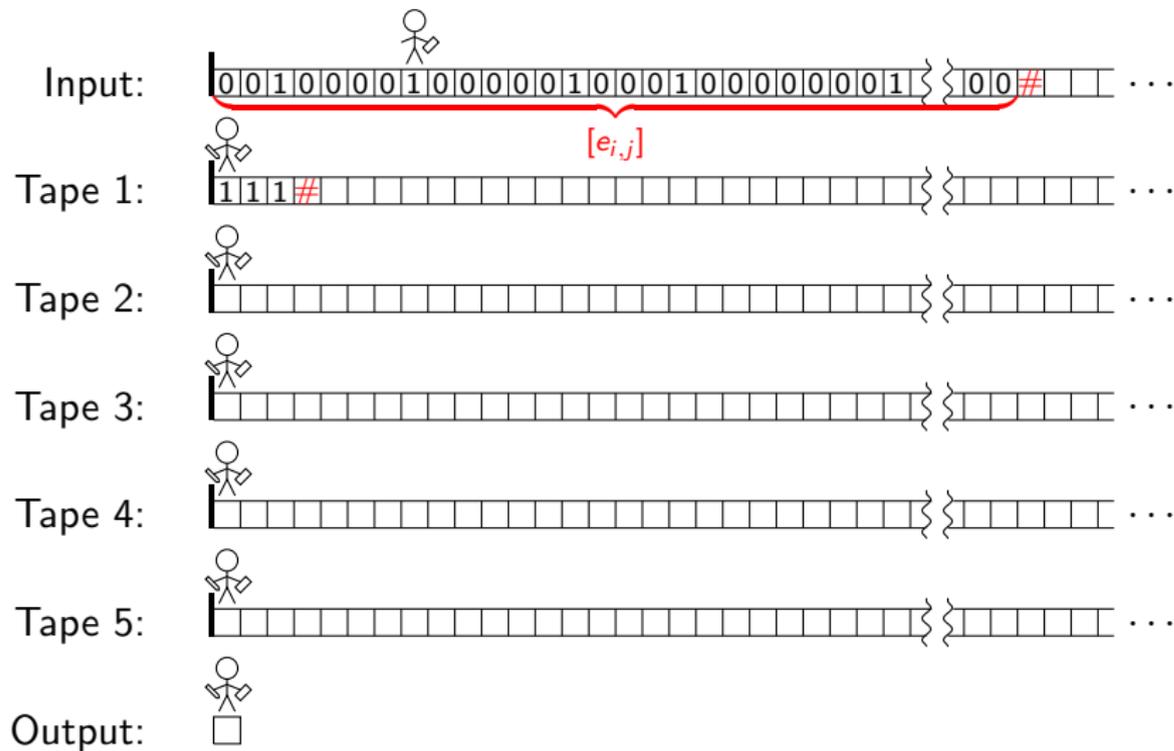
# Implementing the algorithm for *PATH*



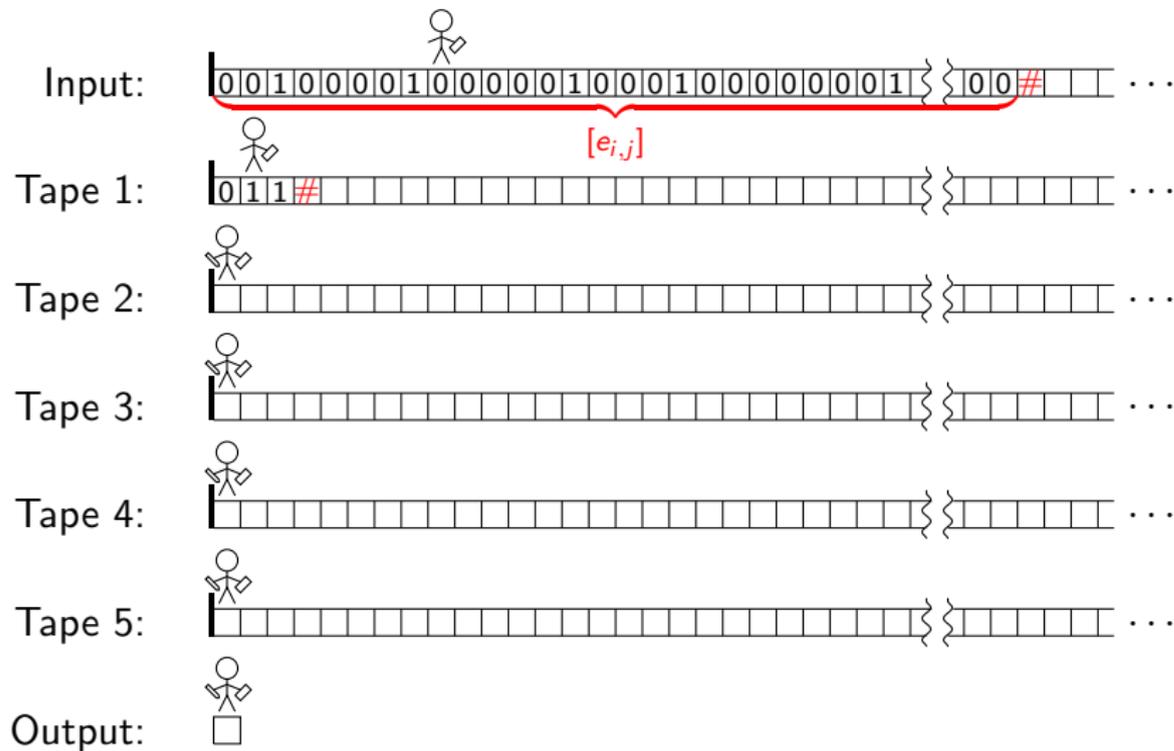
# Implementing the algorithm for *PATH*



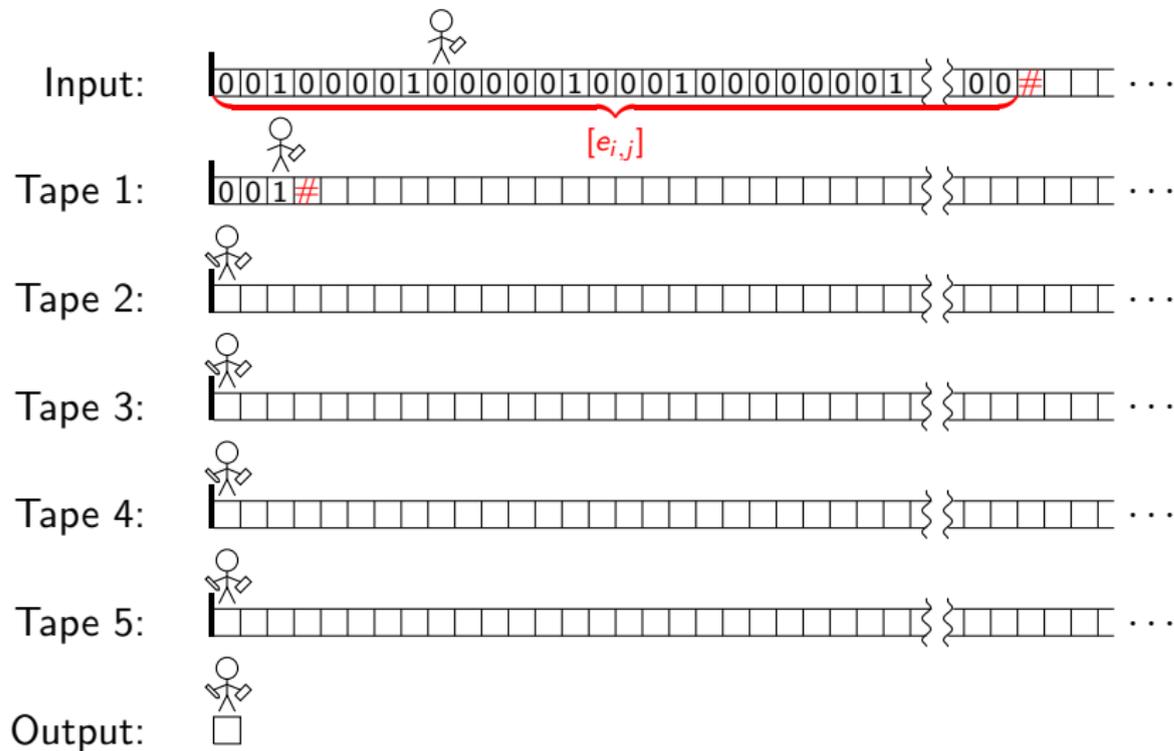
# Implementing the algorithm for *PATH*



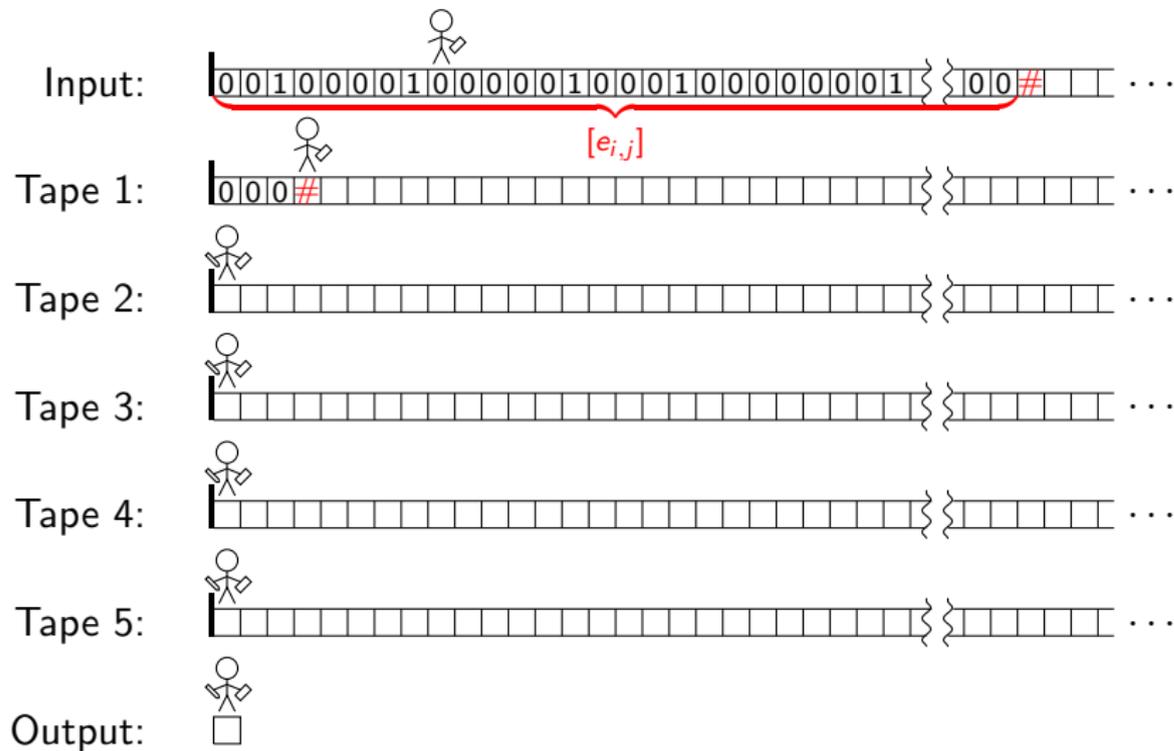
# Implementing the algorithm for *PATH*



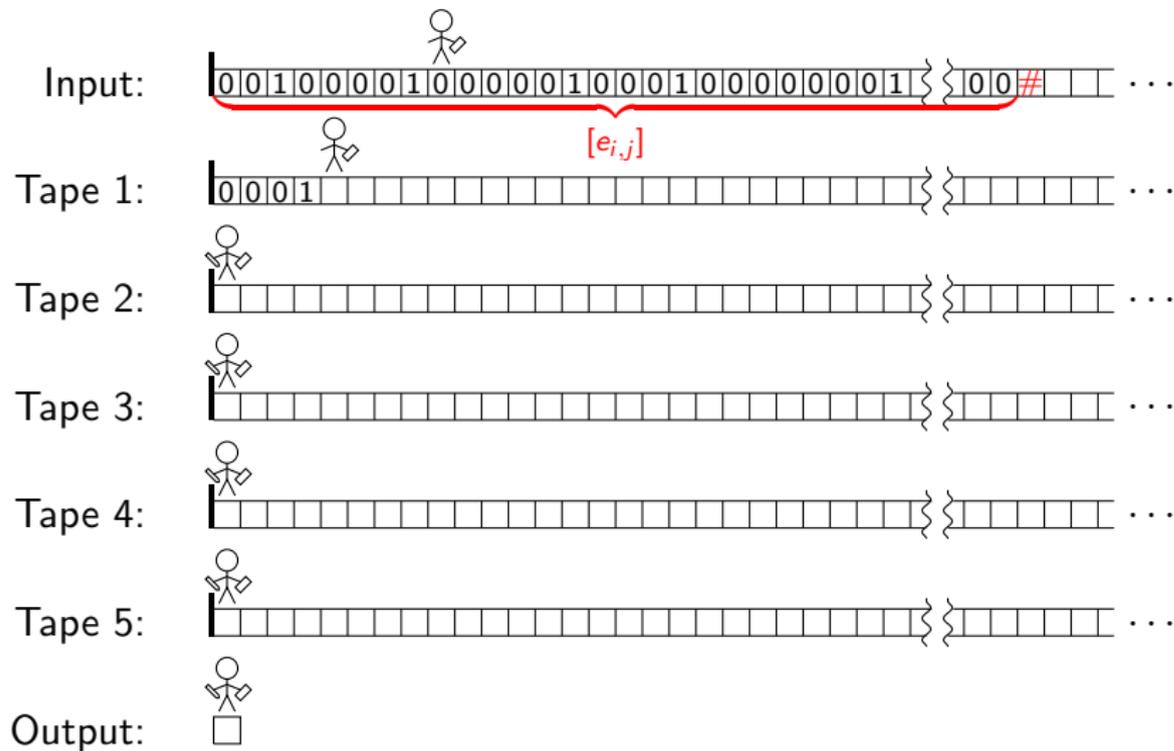
# Implementing the algorithm for *PATH*



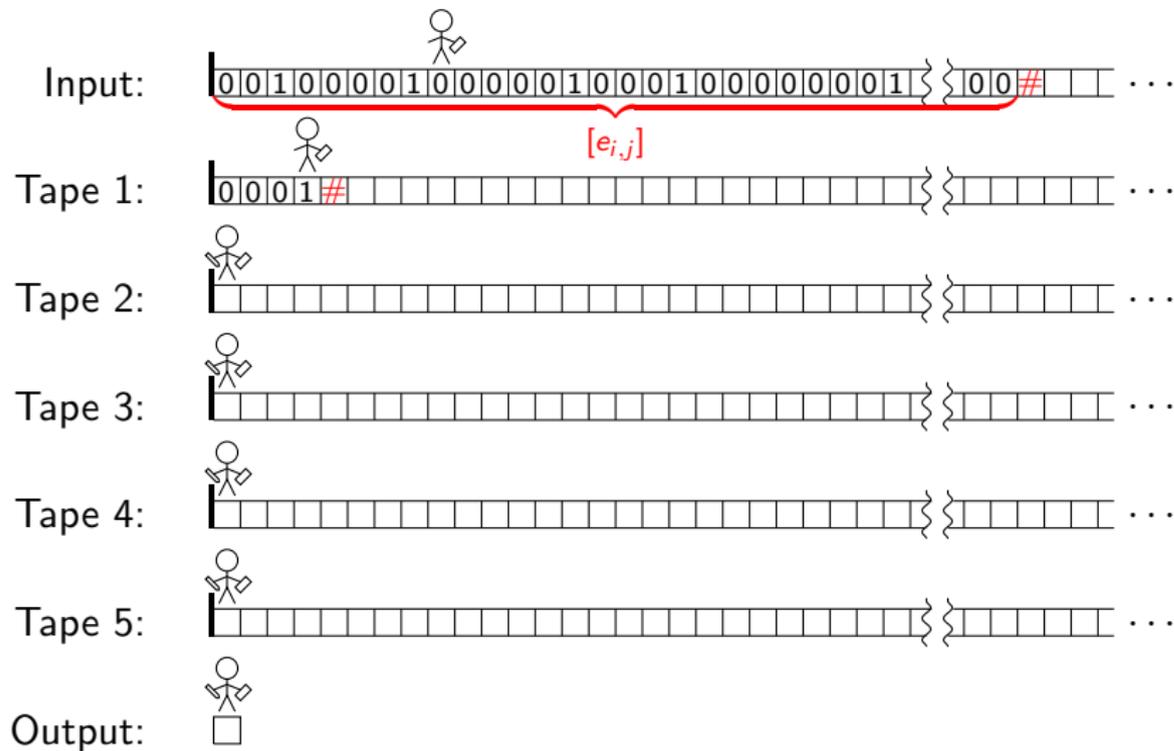
# Implementing the algorithm for *PATH*



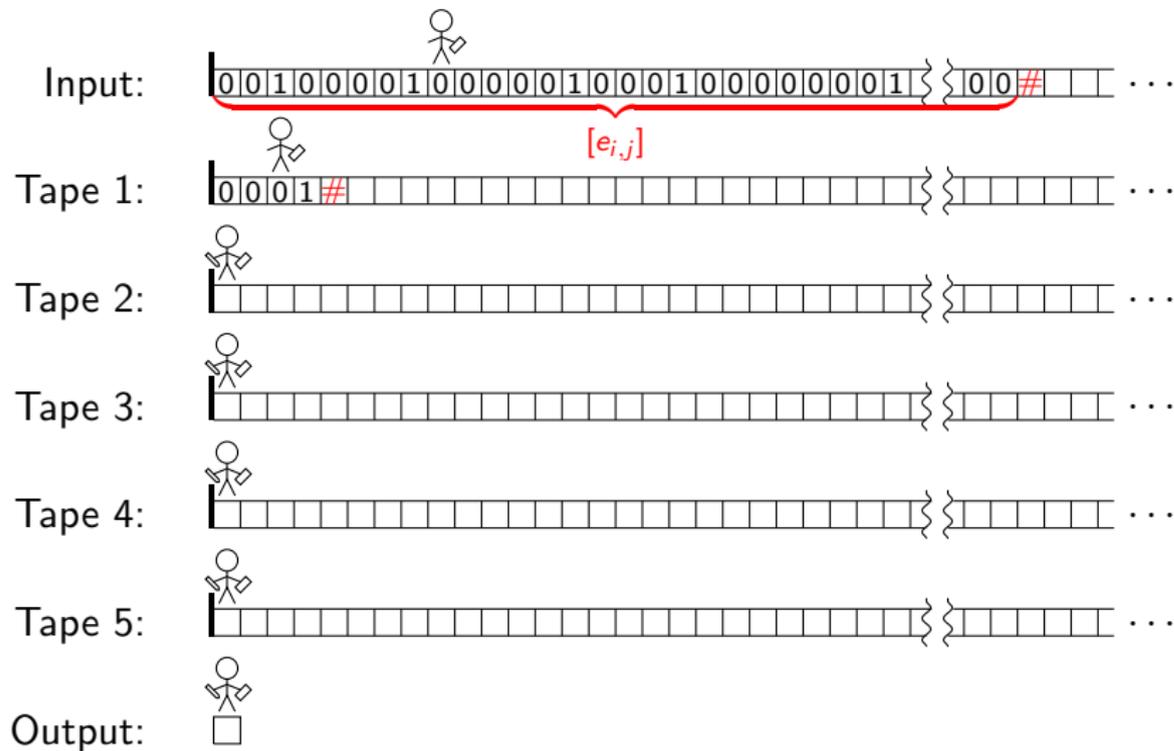
# Implementing the algorithm for *PATH*



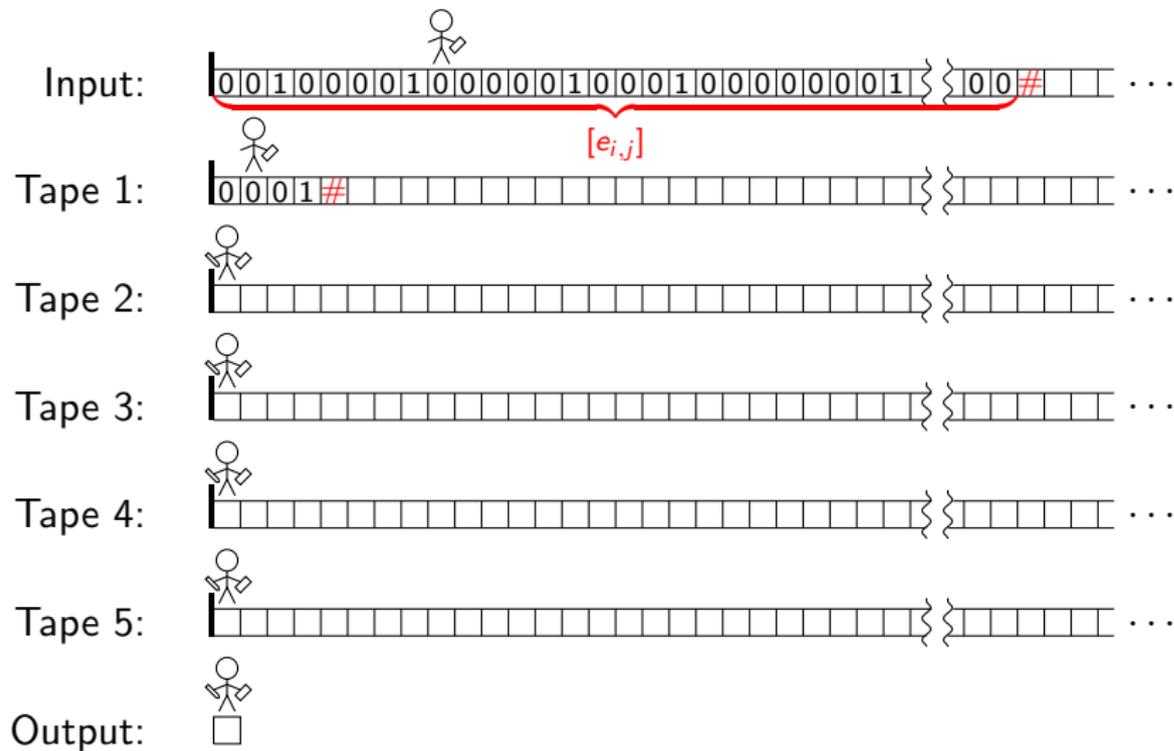
# Implementing the algorithm for *PATH*



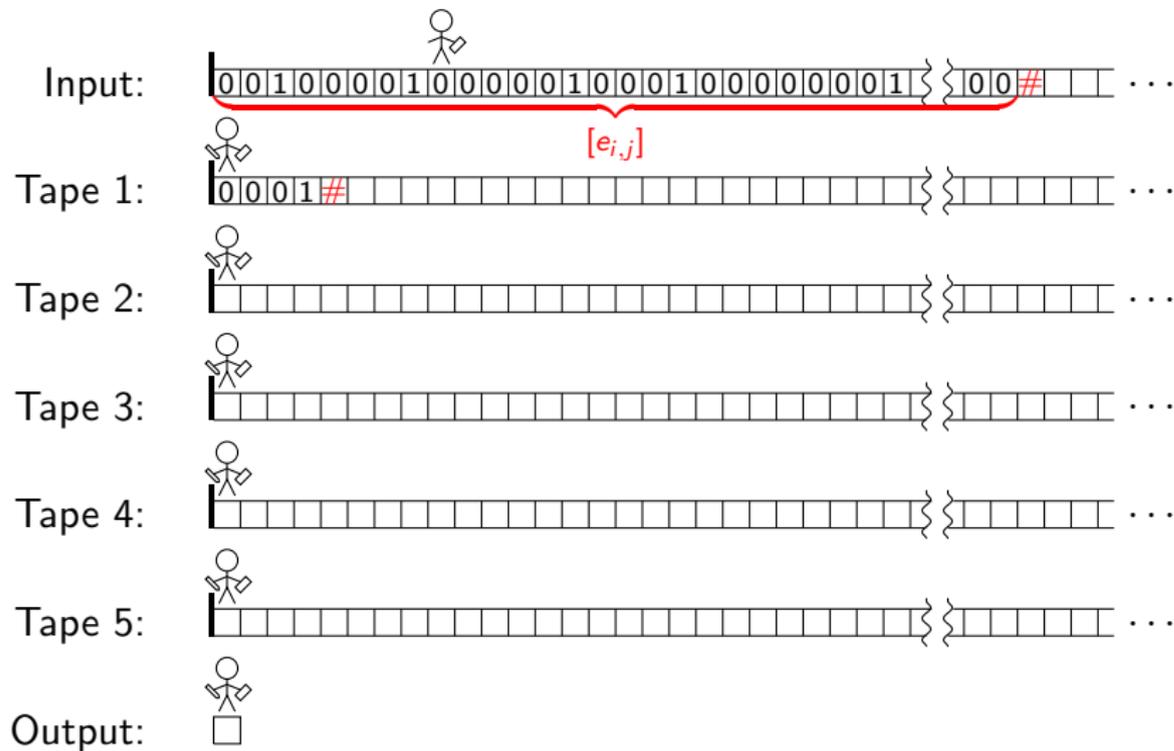
# Implementing the algorithm for *PATH*



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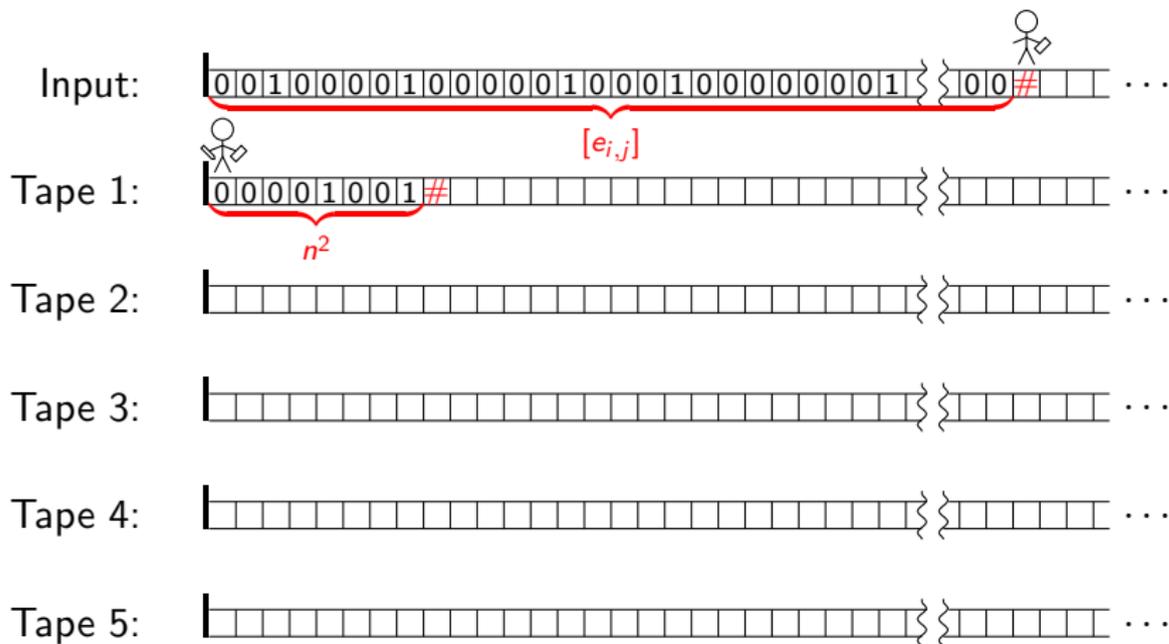
# Implementing the algorithm for *PATH*



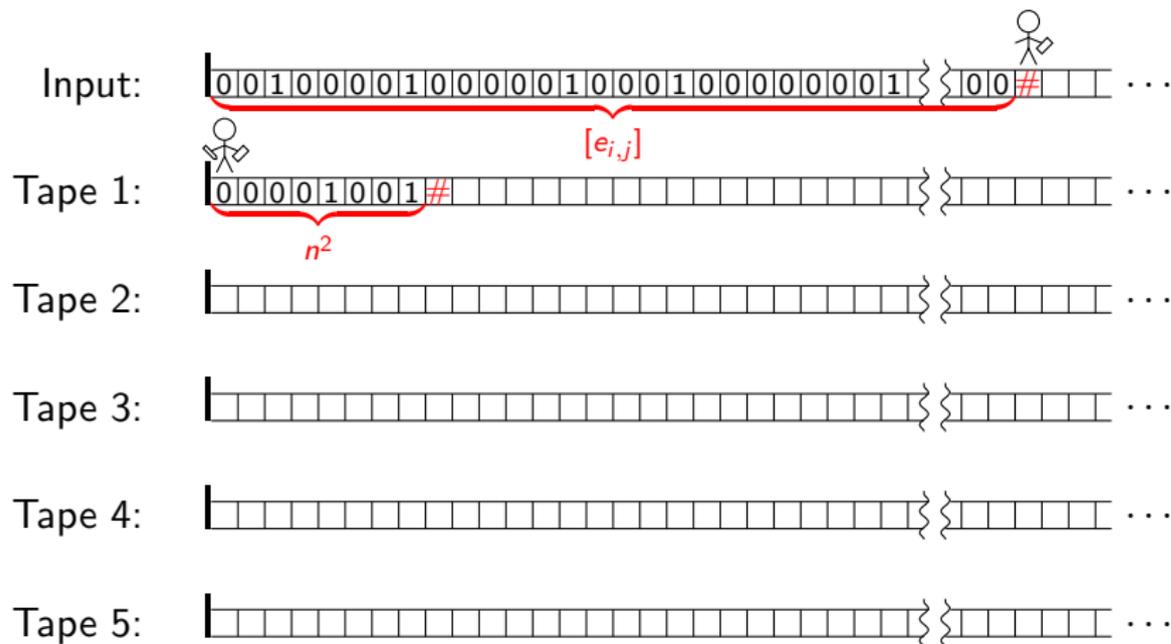
# Implementing the algorithm for *PATH*

Many steps later . . .

# Implementing the algorithm for *PATH*

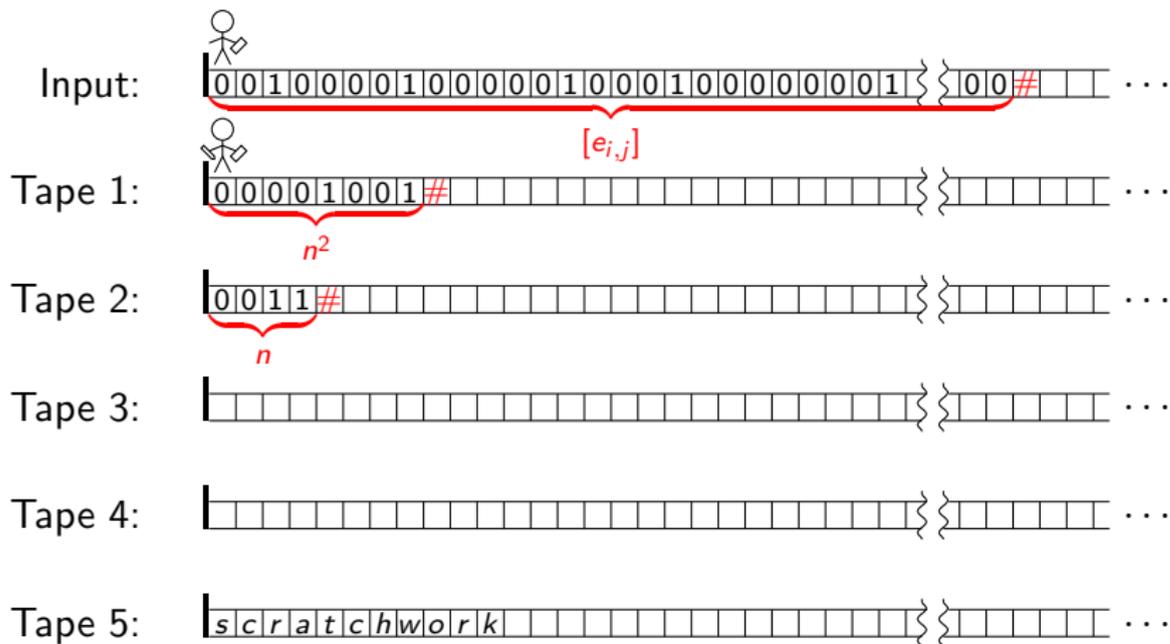


# Implementing the algorithm for *PATH*

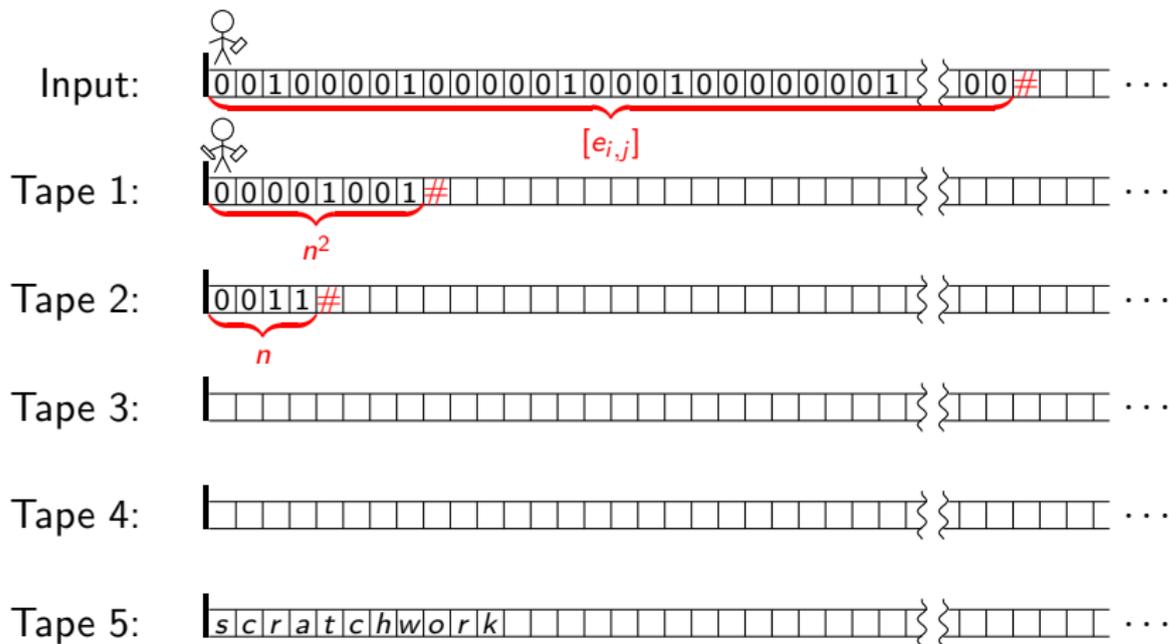


Many more steps later ...

# Implementing the algorithm for *PATH*

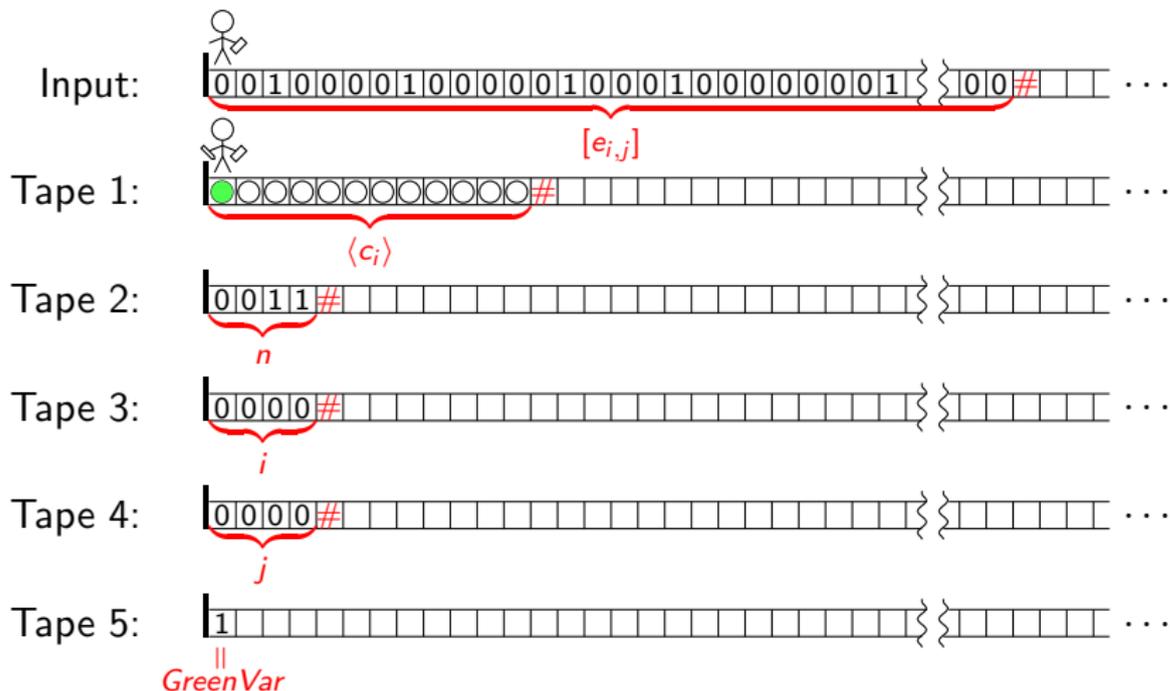


# Implementing the algorithm for *PATH*



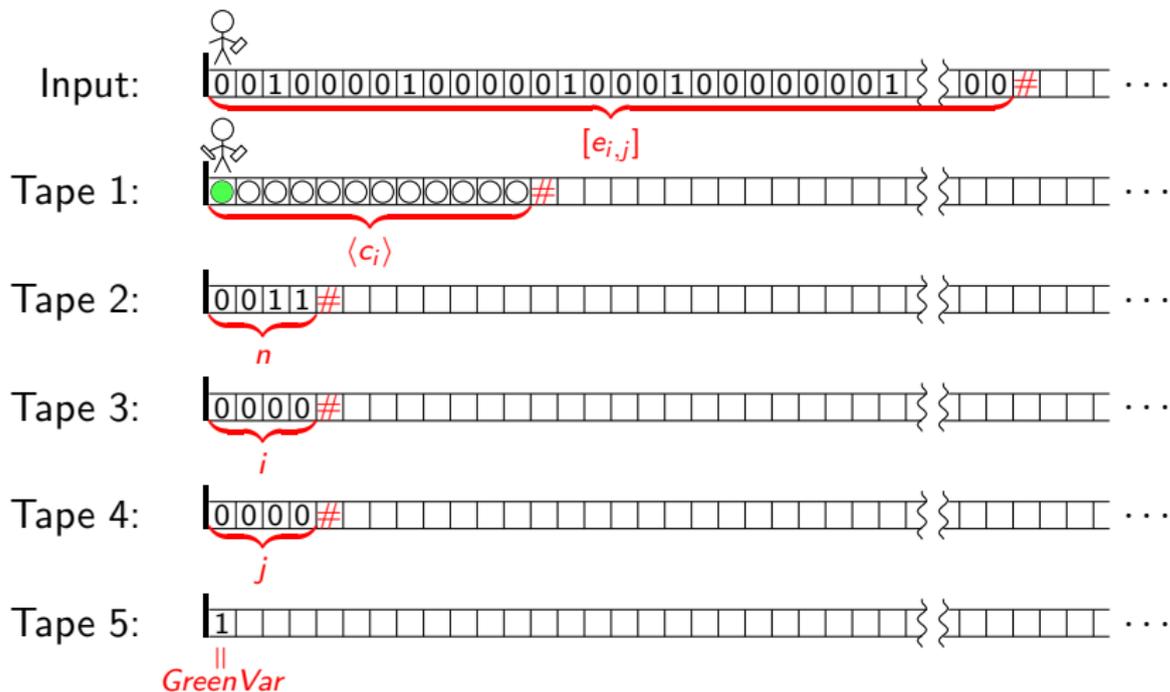
Set up variables ...

# Implementing the algorithm for *PATH*



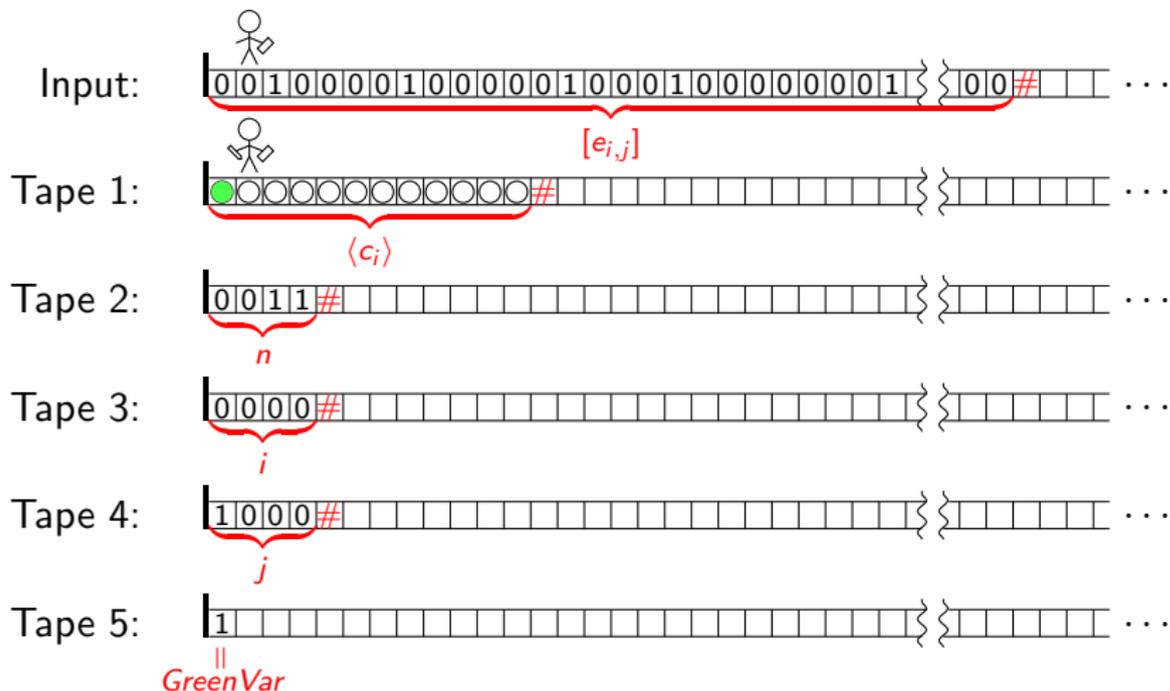
Set up variables ...

# Implementing the algorithm for *PATH*



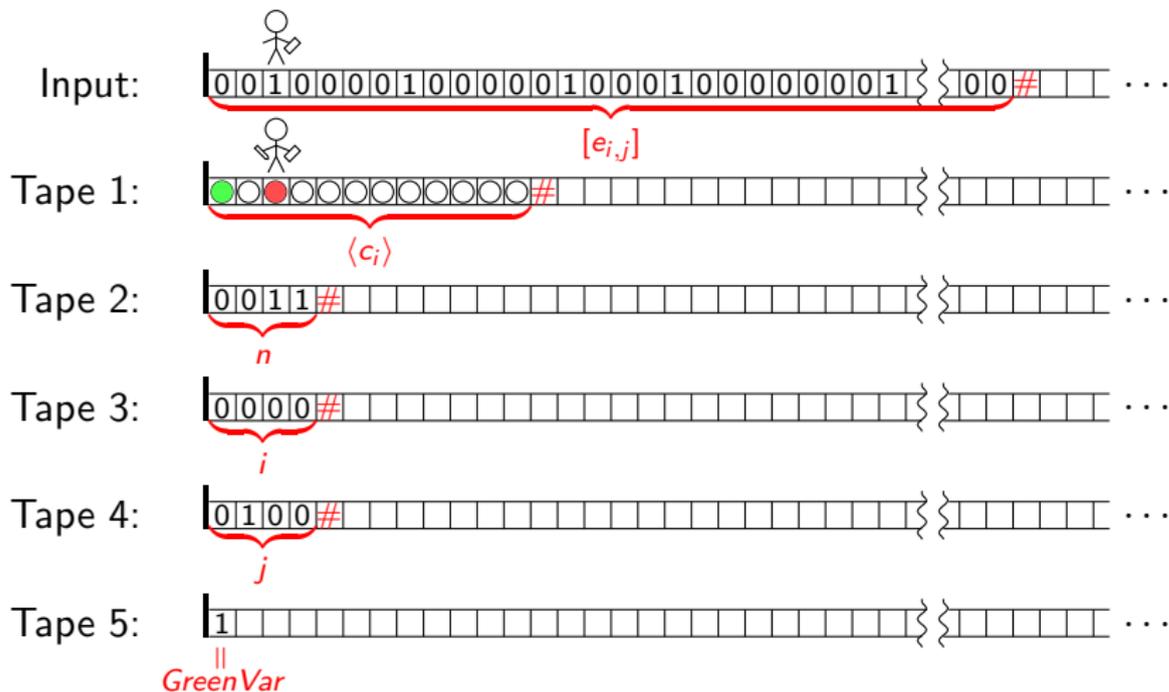
Main loop: For  $i, j = 0$  to  $n - 1$  ...

# Implementing the algorithm for *PATH*



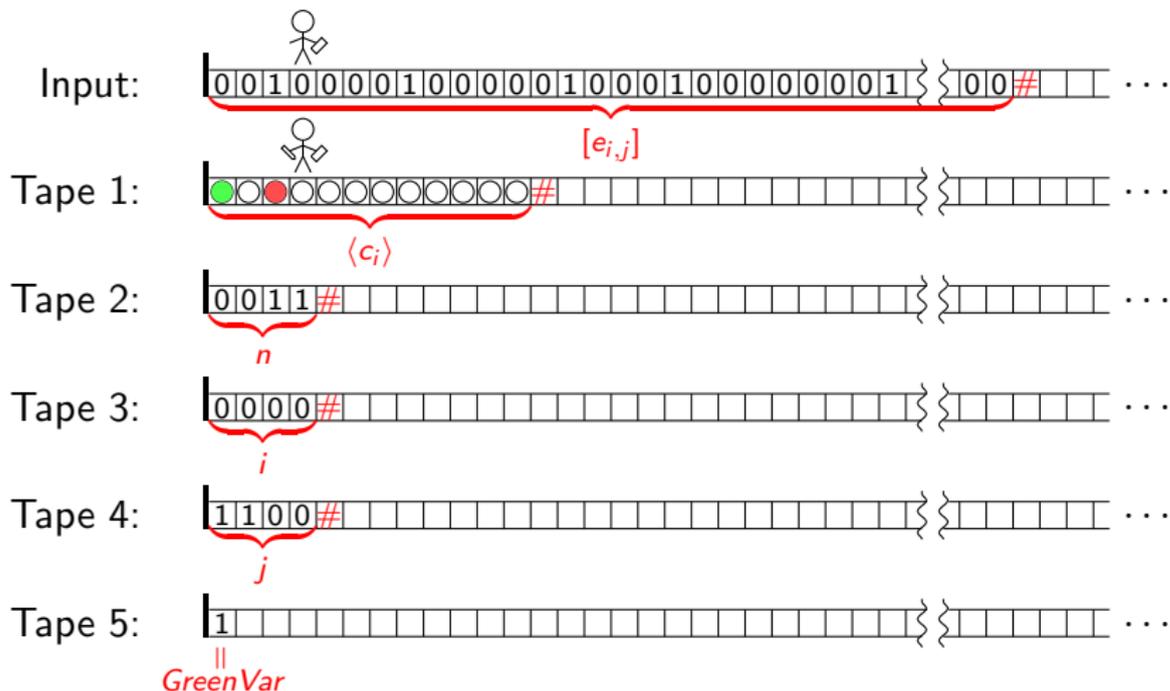
Main loop: For  $i, j = 0$  to  $n - 1$  ...

# Implementing the algorithm for *PATH*



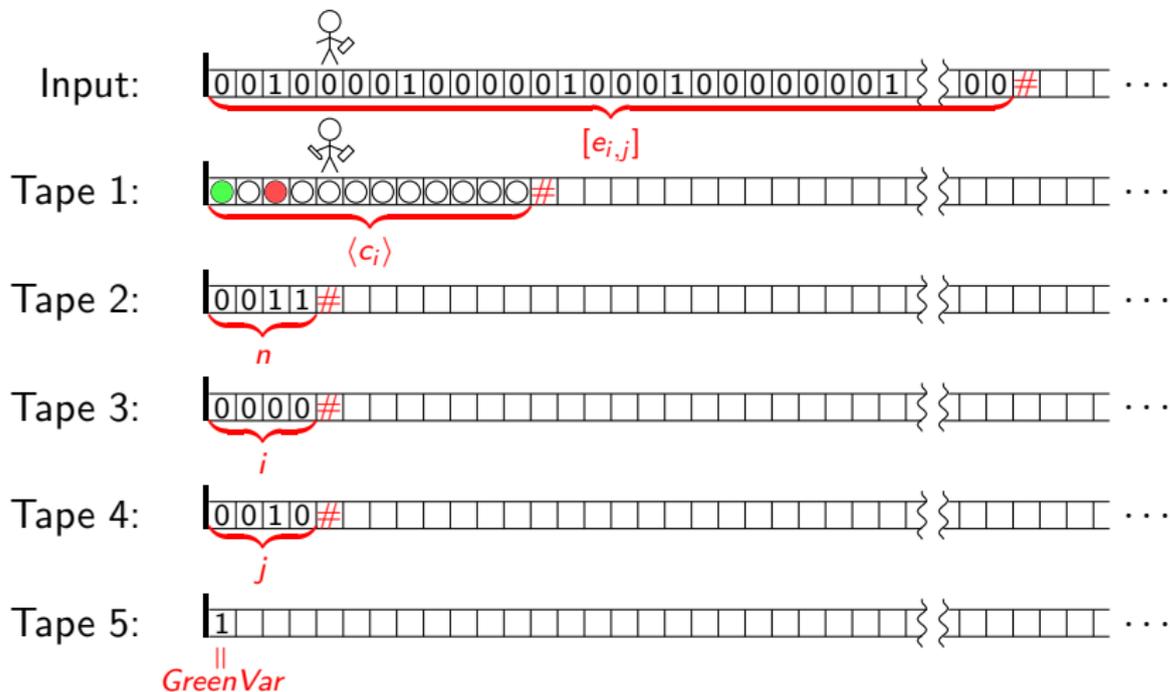
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# Implementing the algorithm for *PATH*



Main loop: For  $i, j = 0$  to  $n - 1 \dots$

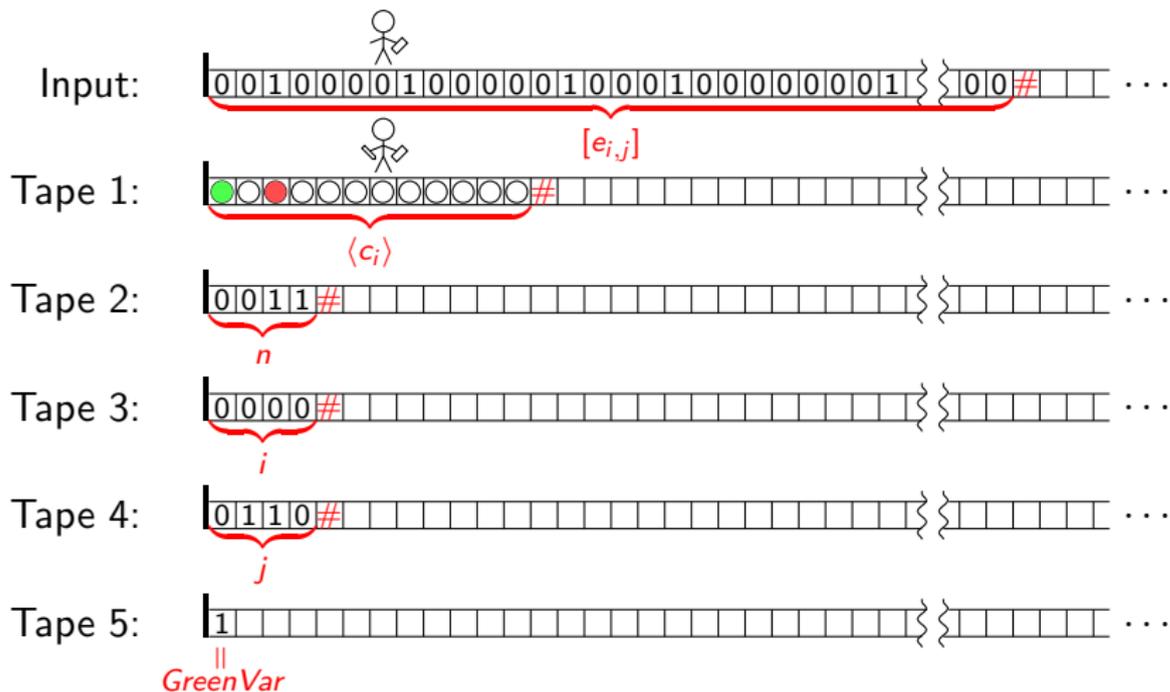
# Implementing the algorithm for *PATH*



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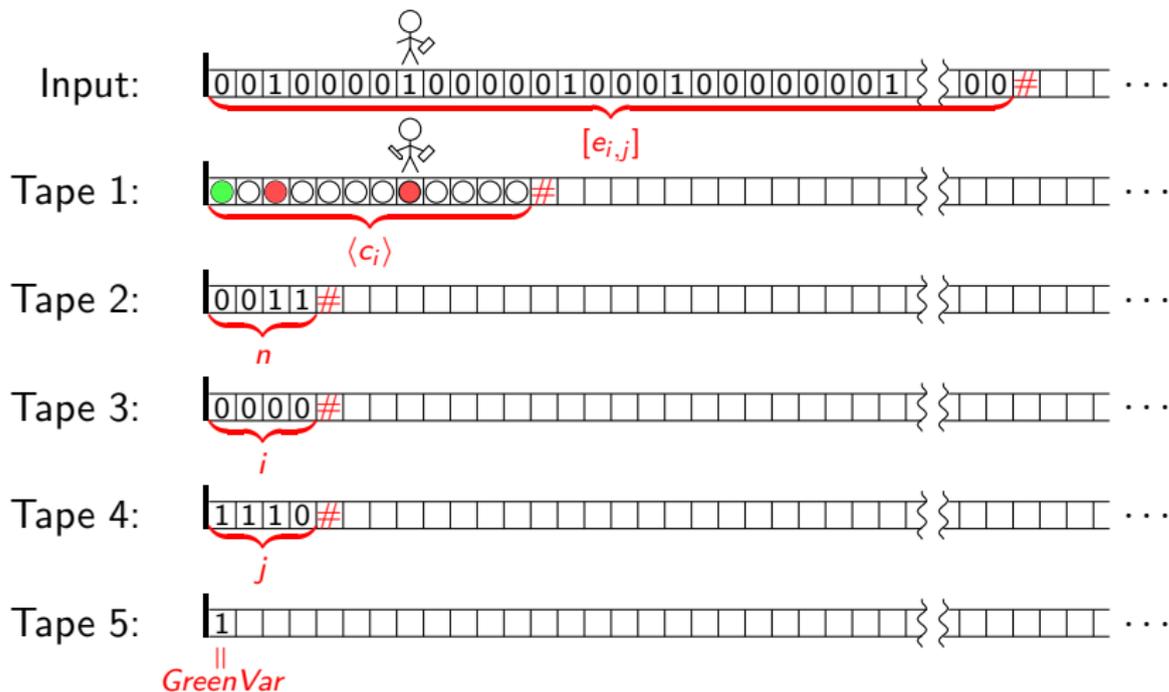


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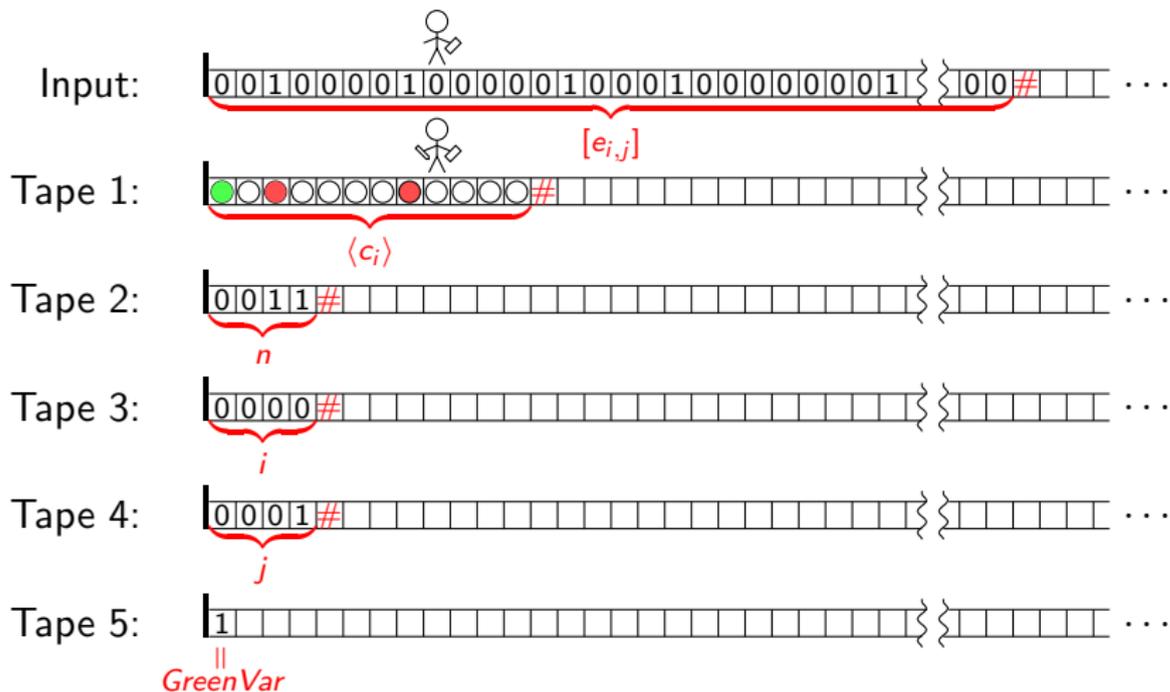
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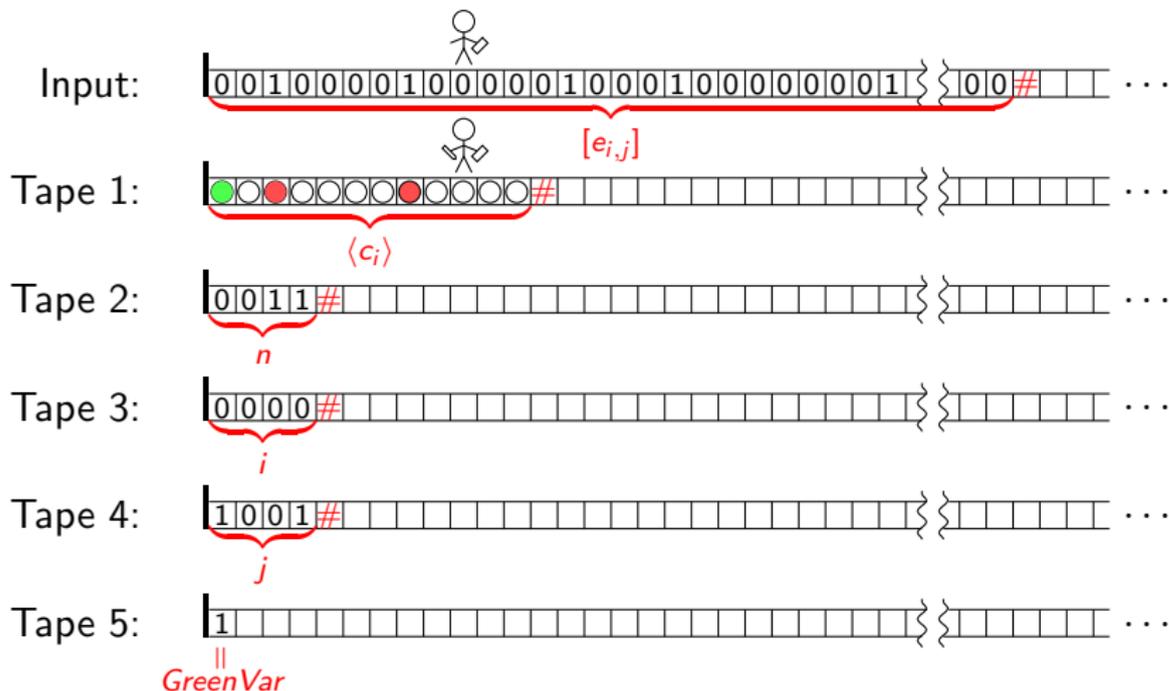
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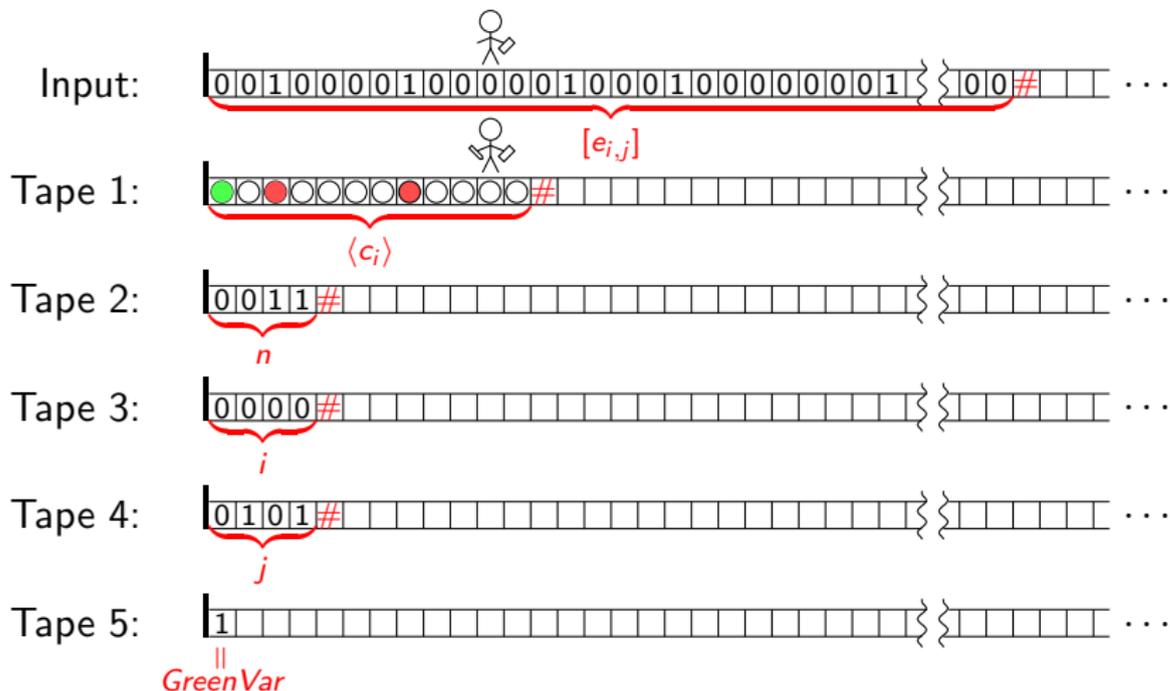
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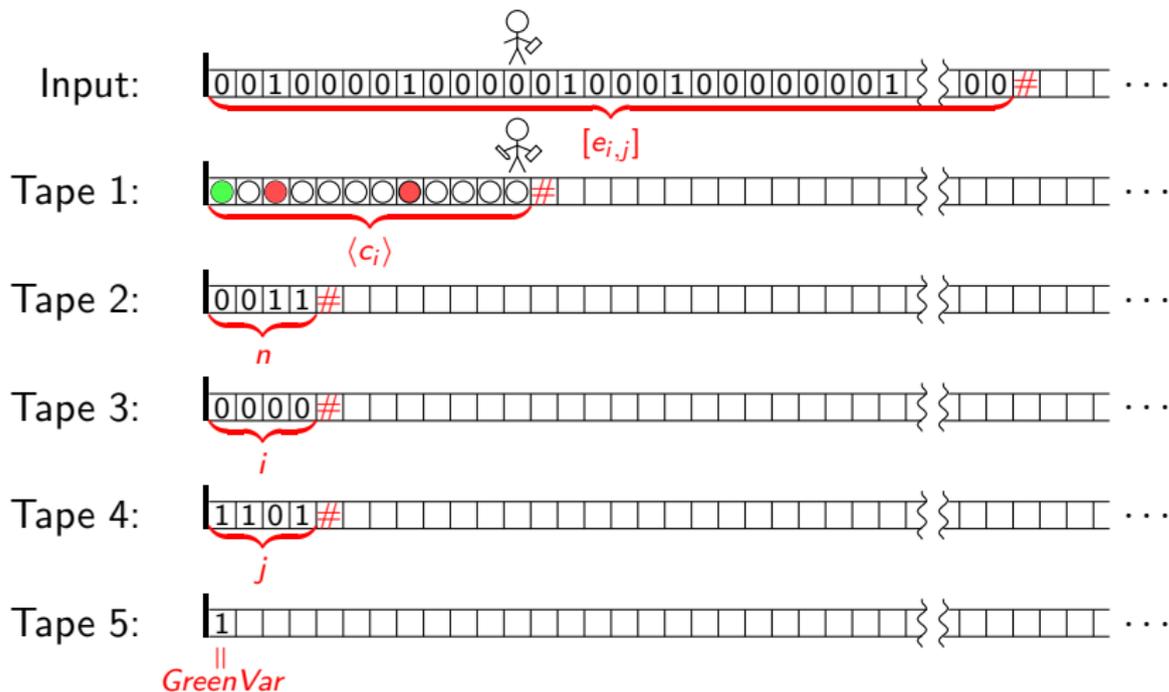
Main loop: For  $i, j = 0$  to  $n - 1 \dots$

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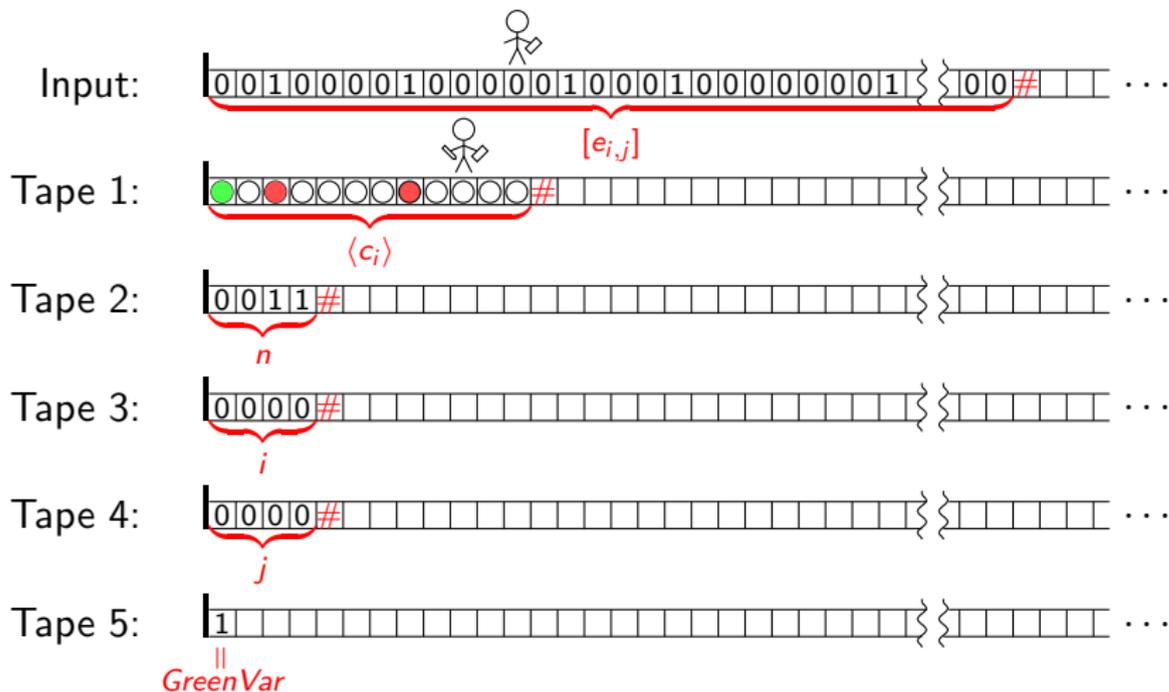
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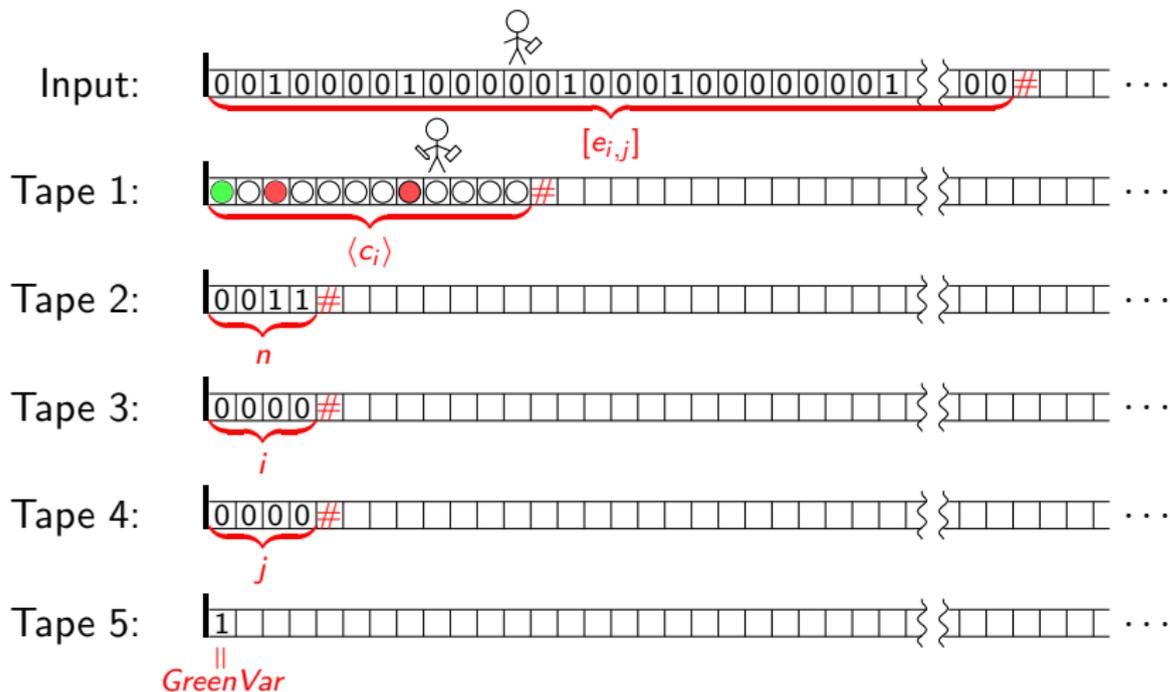


# Implementing the algorithm for *PATH*



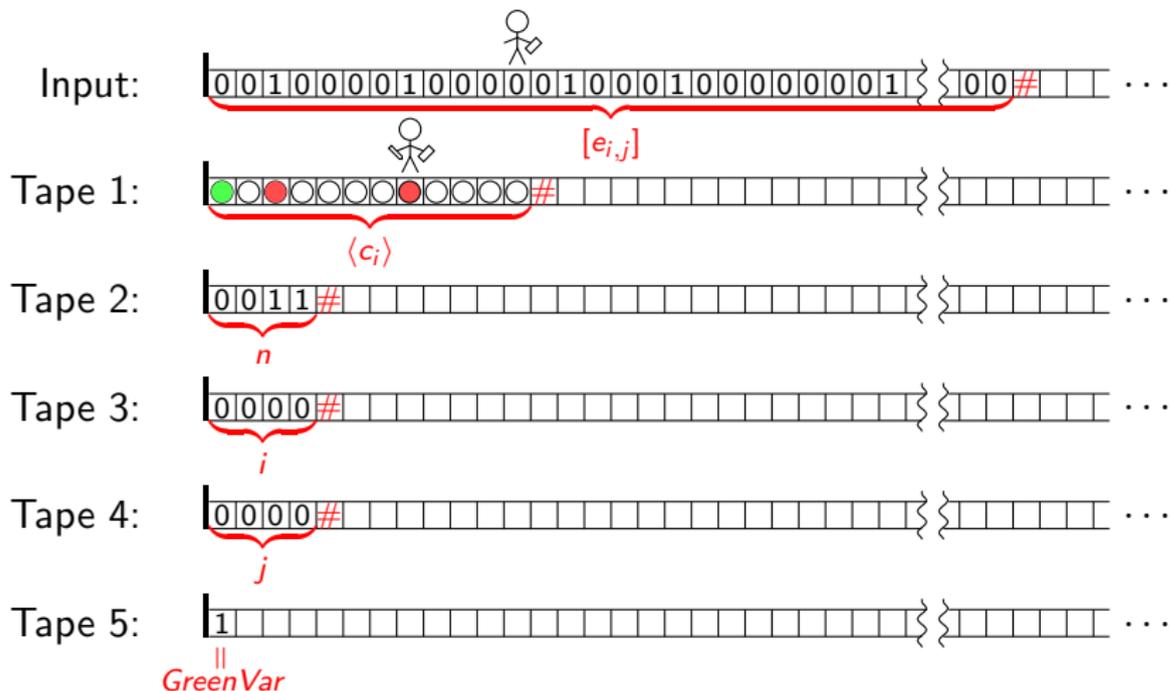
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# Implementing the algorithm for *PATH*



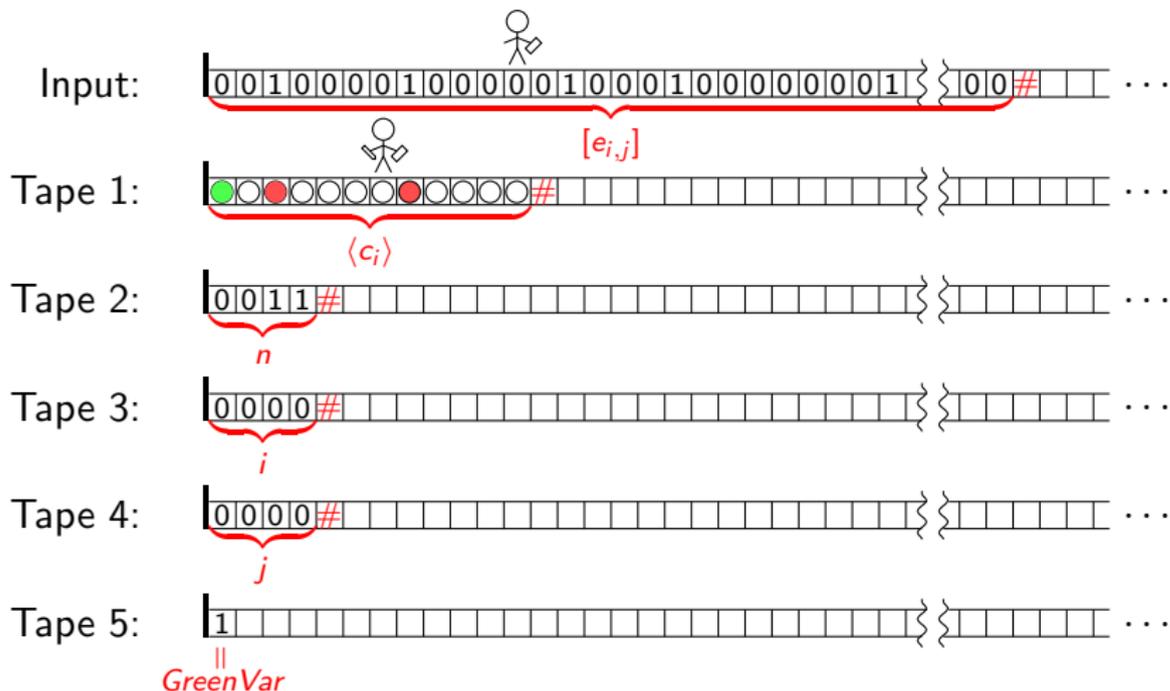
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# Implementing the algorithm for *PATH*



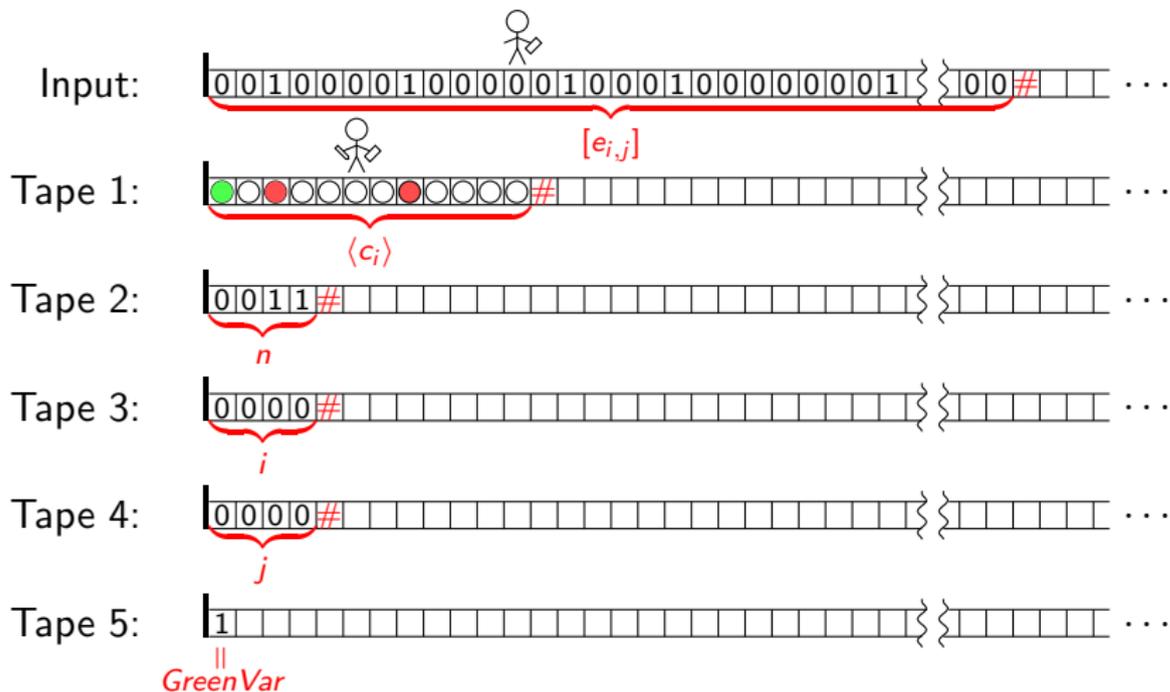
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# Implementing the algorithm for *PATH*



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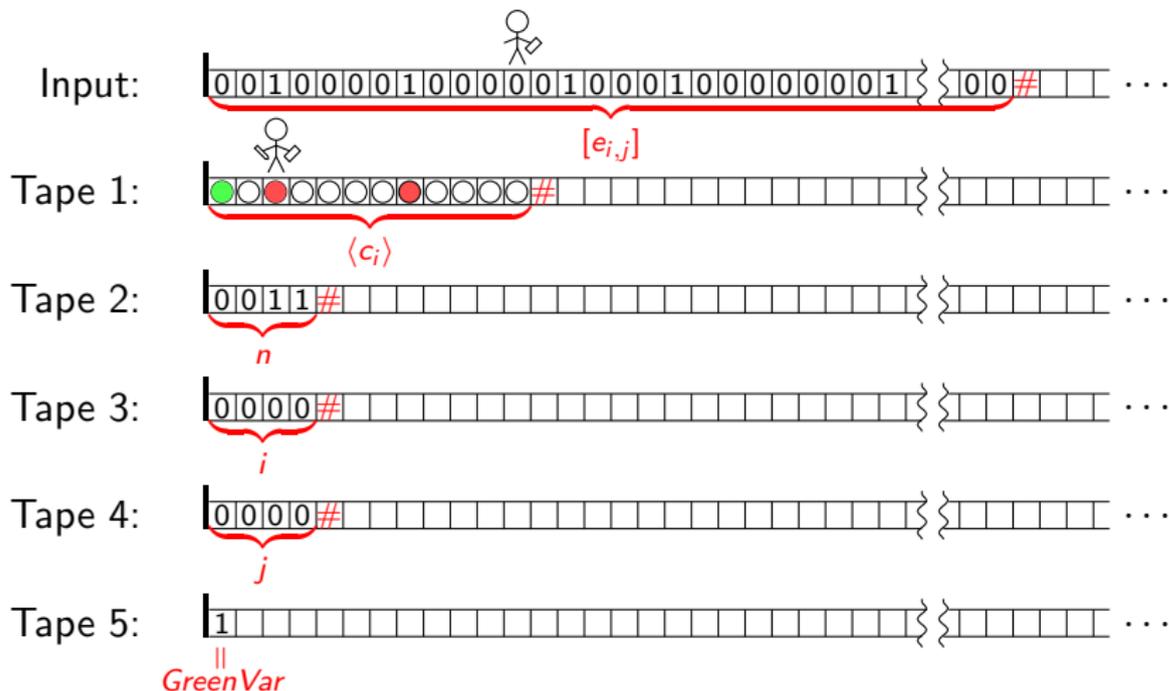


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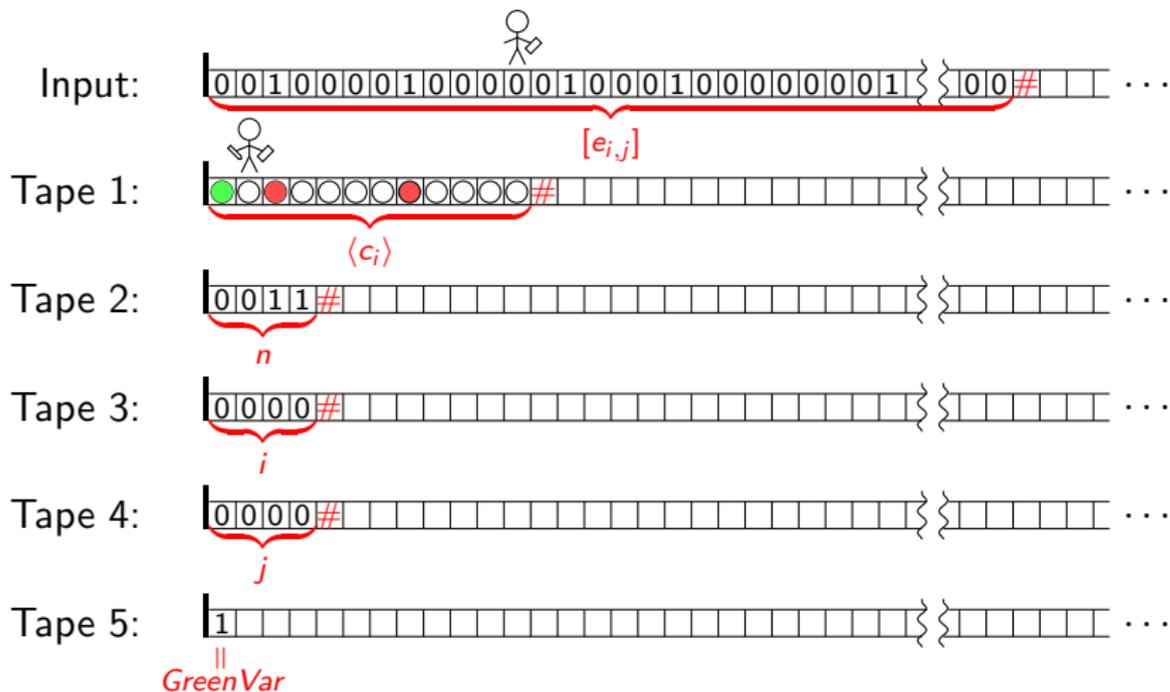


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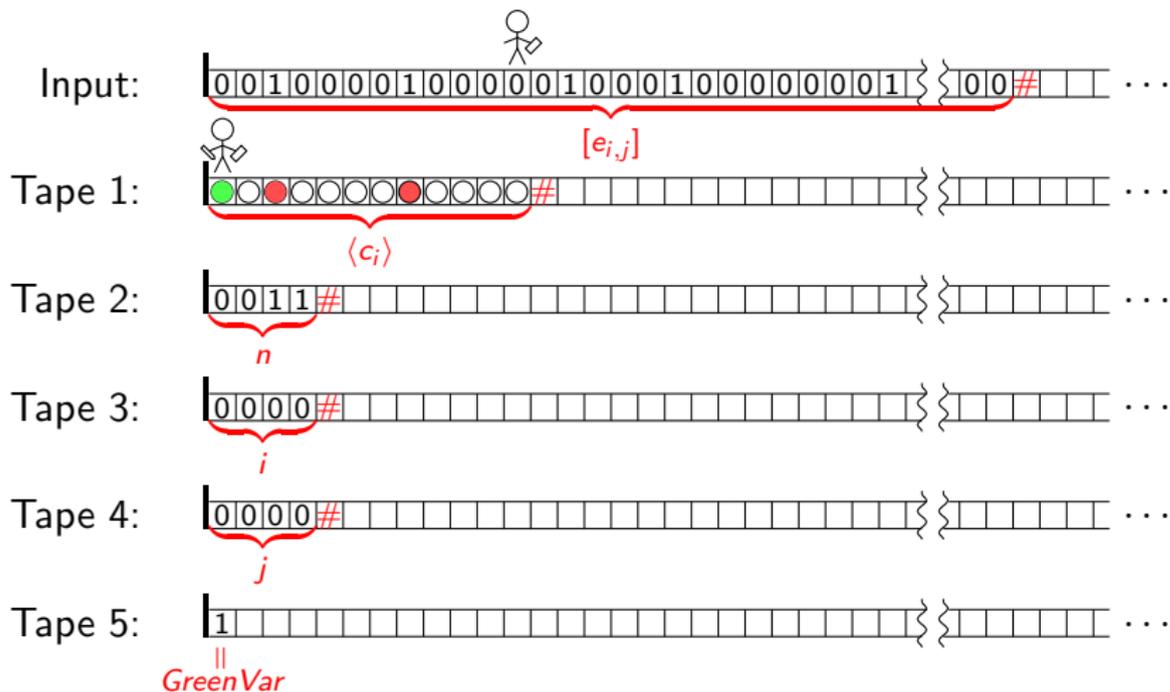
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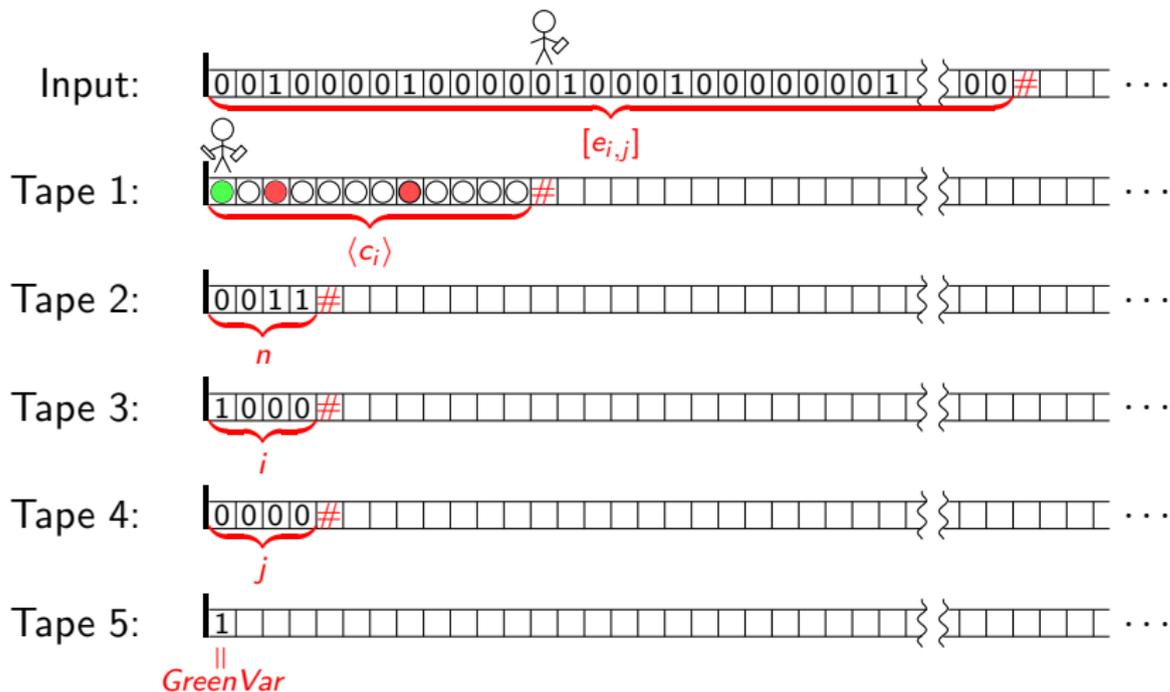
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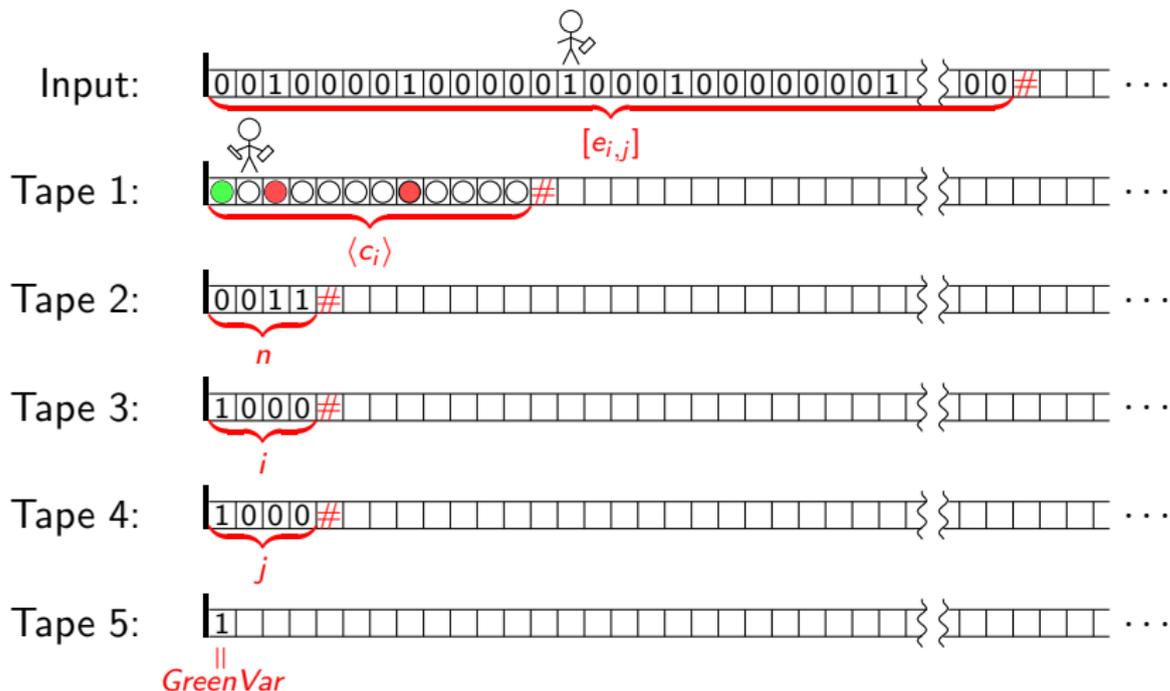
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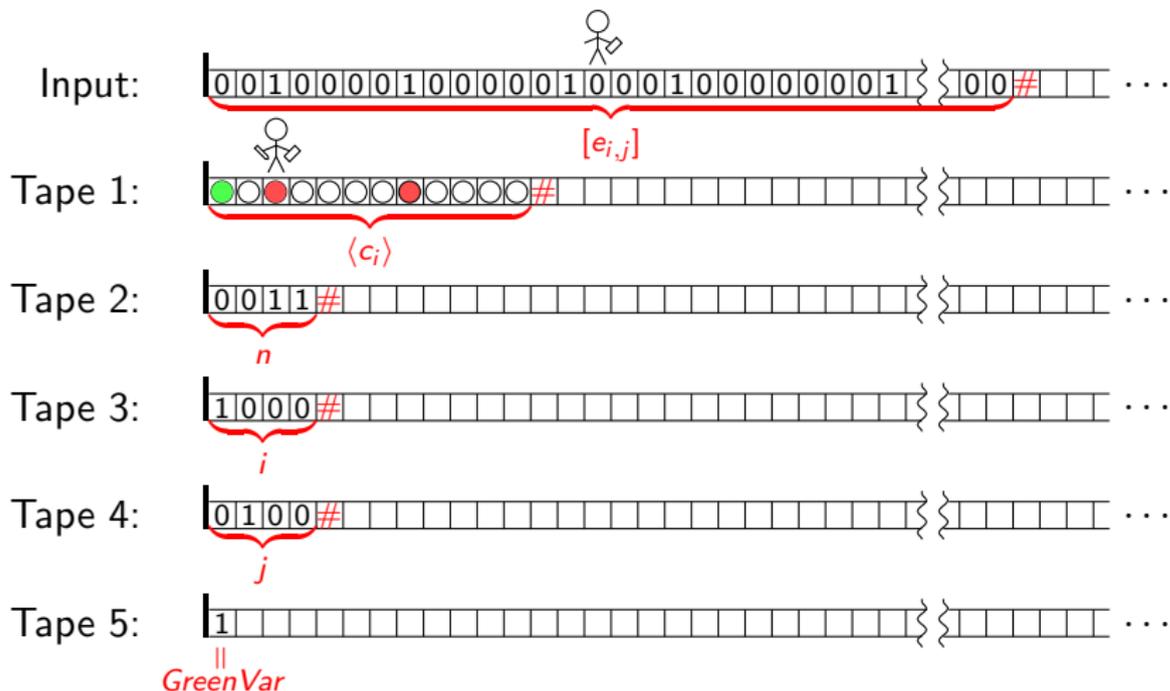
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# Implementing the algorithm for *PATH*



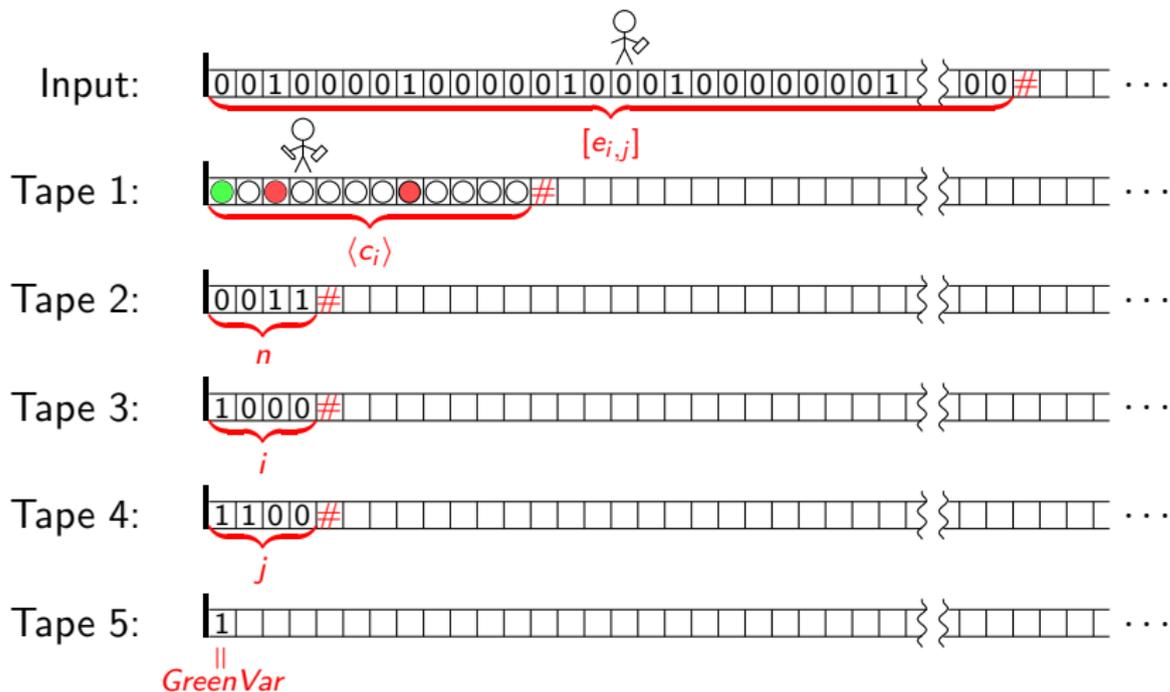
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# Implementing the algorithm for *PATH*



Main loop: For  $i, j = 0$  to  $n - 1 \dots$

# Implementing the algorithm for *PATH*



Main loop: and so on ...

# Pseudo-code revisited

Point: overhead needed to keep track of  $i, j, c_i, c_j$ .

Thus:

- While *GreenVar* = *yes* do:
  - For  $i = 0$  to  $n - 1$ ; for  $j = 0$  to  $n - 1$ 
    - if  $e_{i,j} = 1$  and  $c_i = \textit{green}$  and  $c_j = \textit{white}$   
then set  $c_j := \textit{red}$ .

$n$  loops  
 $n^2$  cases

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SUMMARY: on an input graph  $G = (V, E)$  with  $|V| = n$ , our algorithm decides the answer to *PATH* using:

Heuristics	$3n$ color changes
Pseudo-code	$O(n^3)$ operations
Turing machine	$O(n^4 \log n)$ steps (Time)

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Pseudo-code	$O(n^3)$ operations
Turing machine	$O(n^4 \log n)$ steps (Time) $O(n)$ memory cells (Space)

Let  $f : \mathbb{N} \rightarrow \mathbb{N}$  be given.

## Definition

A decision problem  $D$  (with a specified encoding of its inputs) is:

- 1 in  $TIME(f(N))$  if there exists a Turing machine solving  $D$  in at most  $O(f(N))$  steps on inputs of length  $N$ .

# Turing machine complexity

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A decision problem  $D$  (with a specified encoding of its inputs) is:

- 1 in  $TIME(f(N))$  if there exists a Turing machine solving  $D$  in at most  $O(f(N))$  steps on inputs of length  $N$ .
- 2 in  $SPACE(f(N))$  if there exists a Turing machine solving  $D$  requiring at most  $O(f(N))$  memory cells (not including the input tape) on inputs of length  $N$ .

# Complexity of *PATH*

Recall that our Turing machine solves *PATH* on graphs with  $n$  vertices in

- Time:  $O(n^4 \log n)$  steps
- Space:  $O(n)$  memory cells.

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## Theorem

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(Question: can we do better?..)

## Another problem: Boolean Formula Value (*FVAL*)

INPUT:

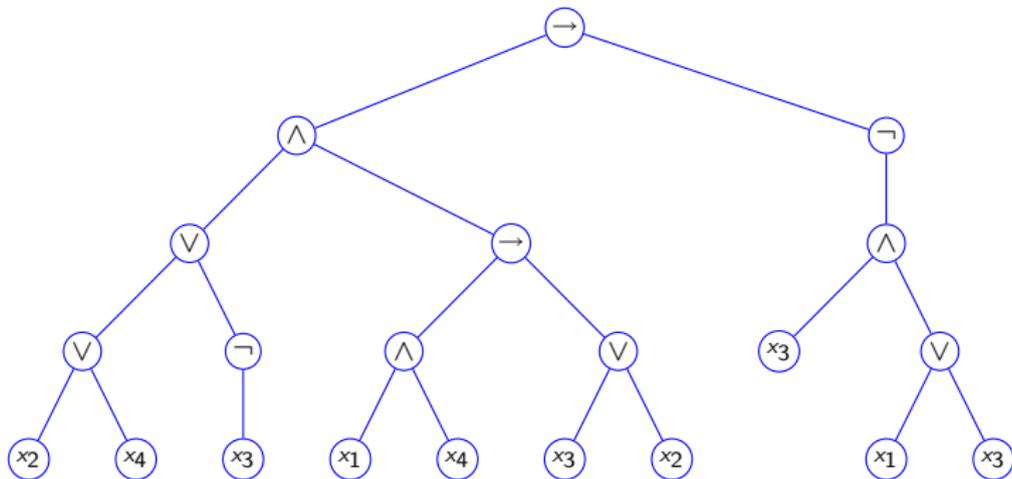
- A boolean formula  $\varphi$  in propositional variables  $x_1, \dots, x_n$ .
- A sequence  $\mathbf{c} = (c_1, \dots, c_n) \in \{0, 1\}^n$ .

QUESTION:

- Is  $\varphi(\mathbf{c}) = 1$ ?

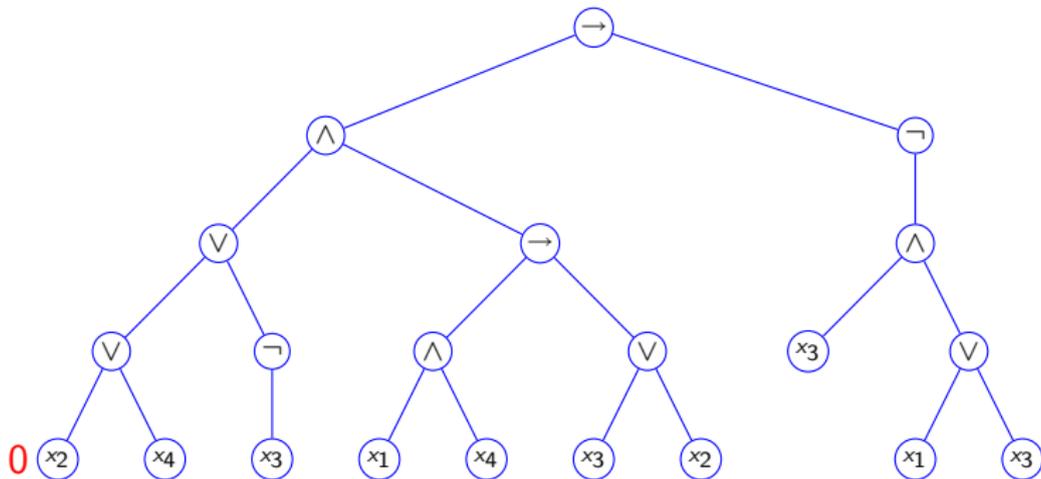
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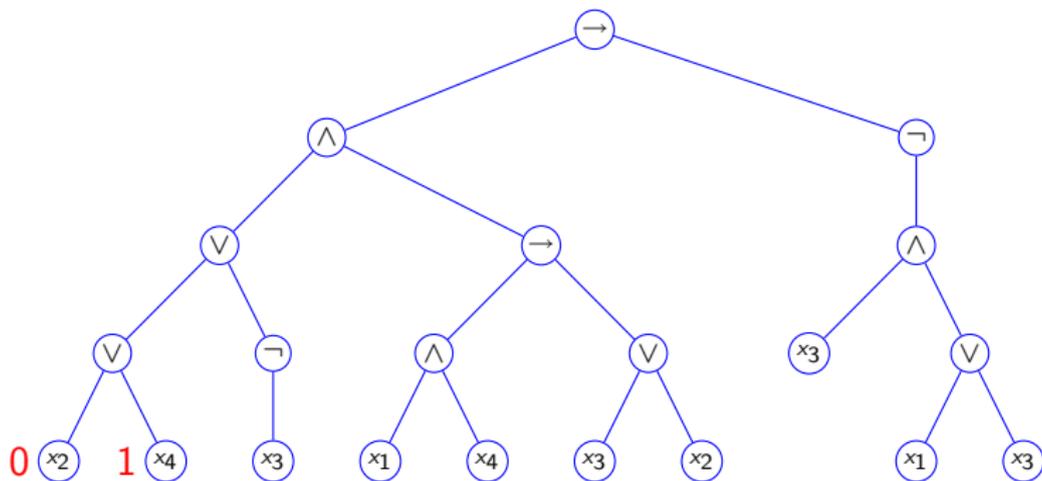
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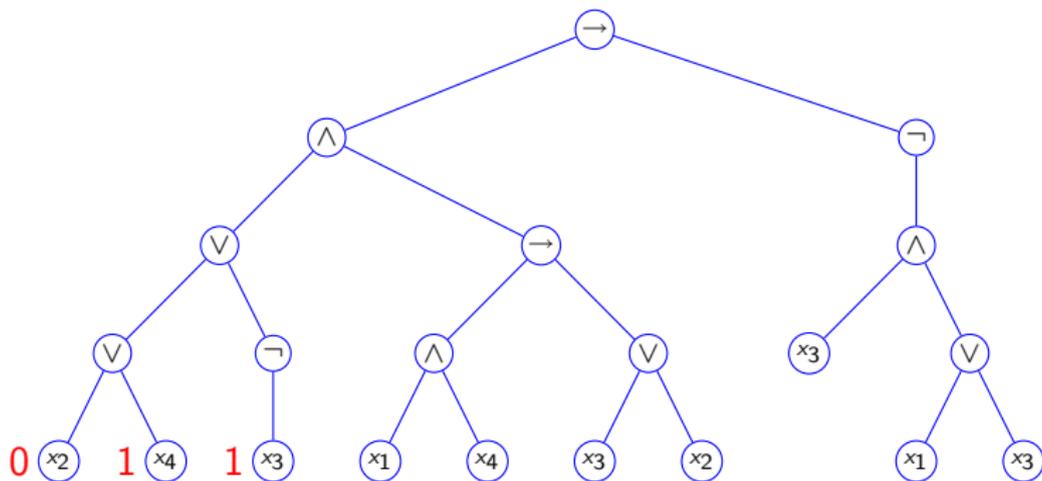
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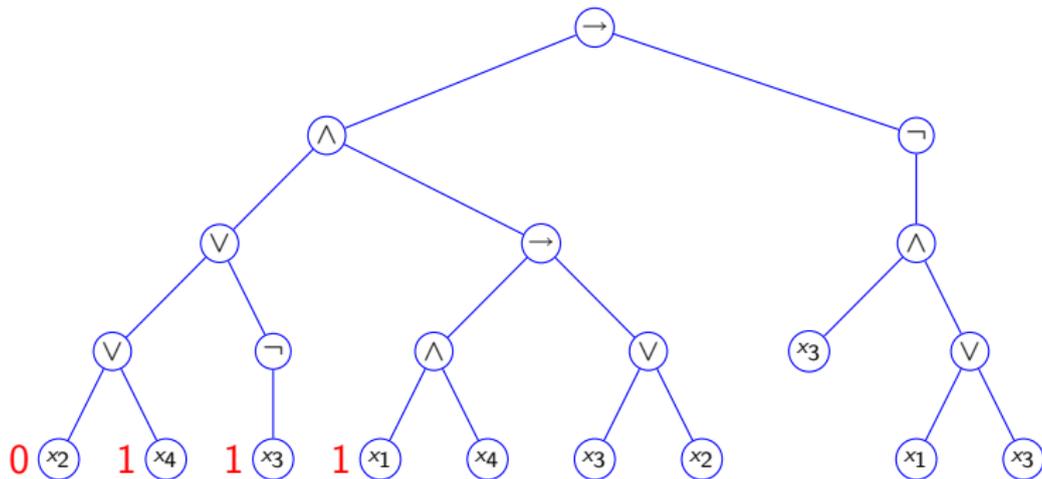
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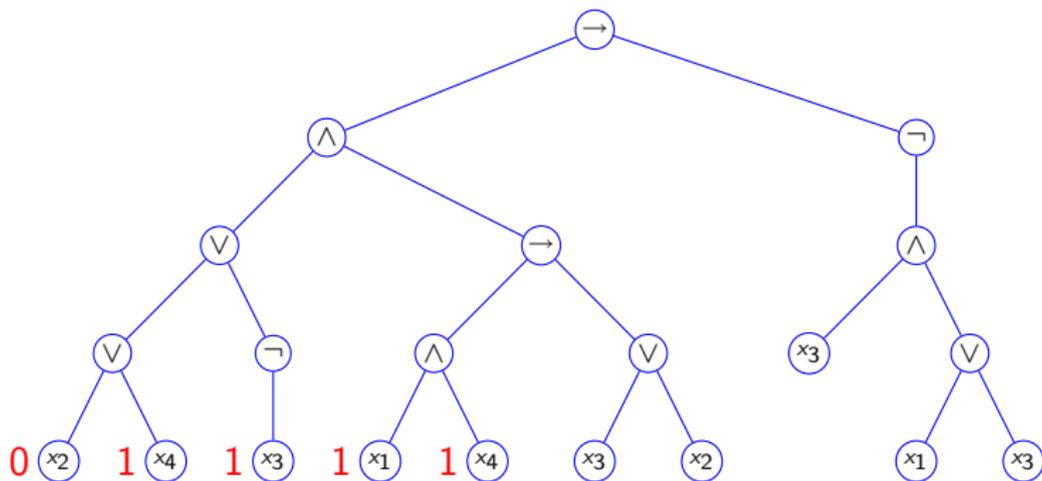
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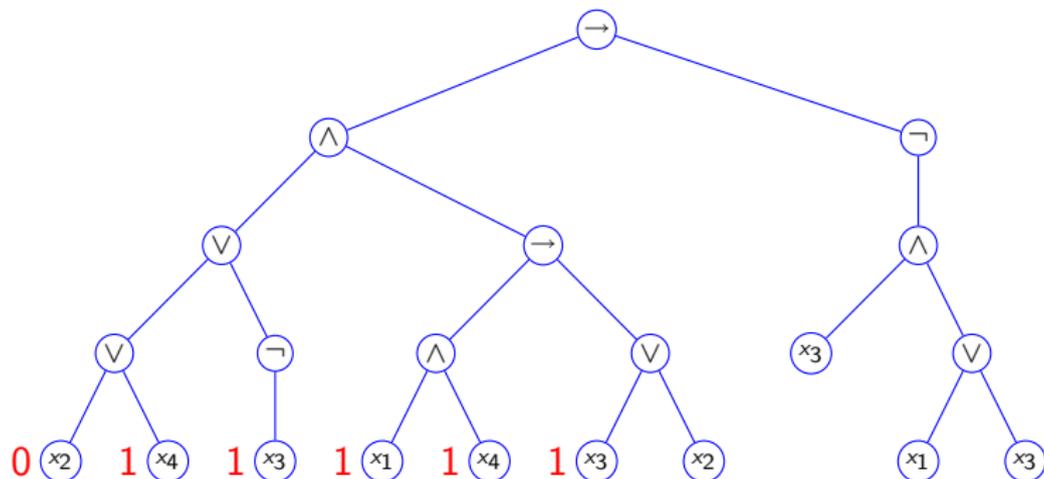
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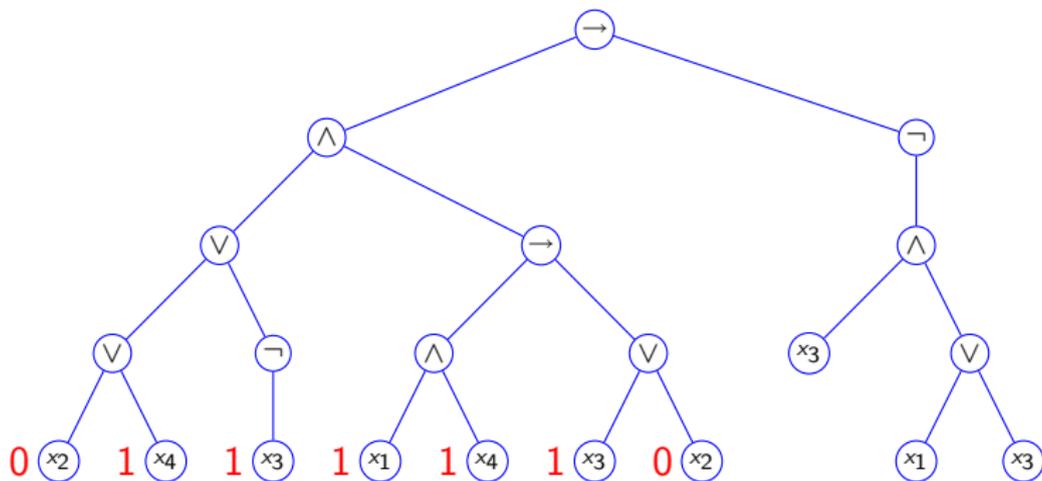
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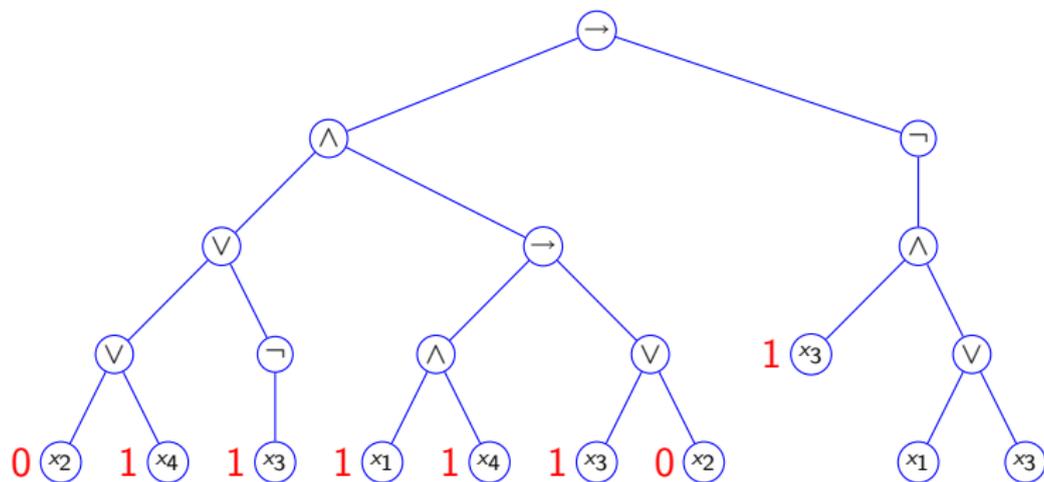
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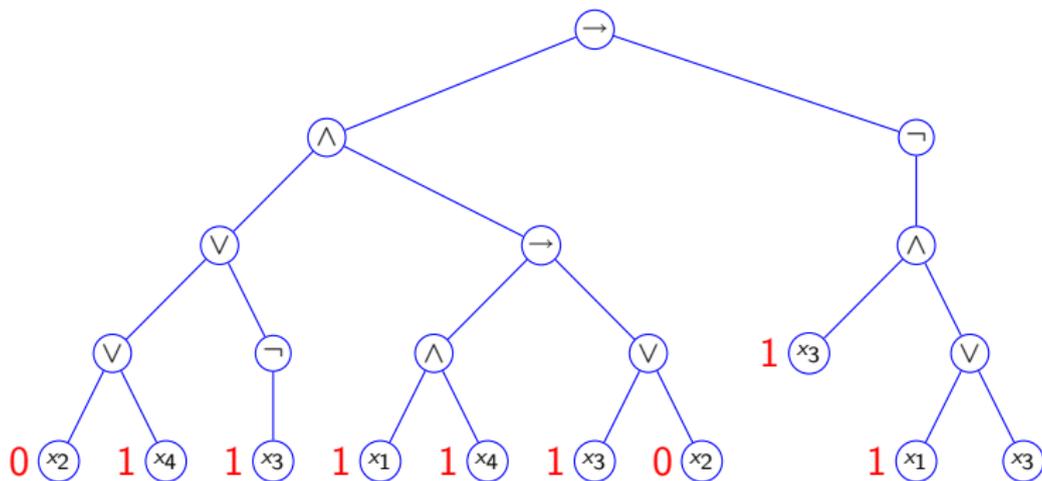
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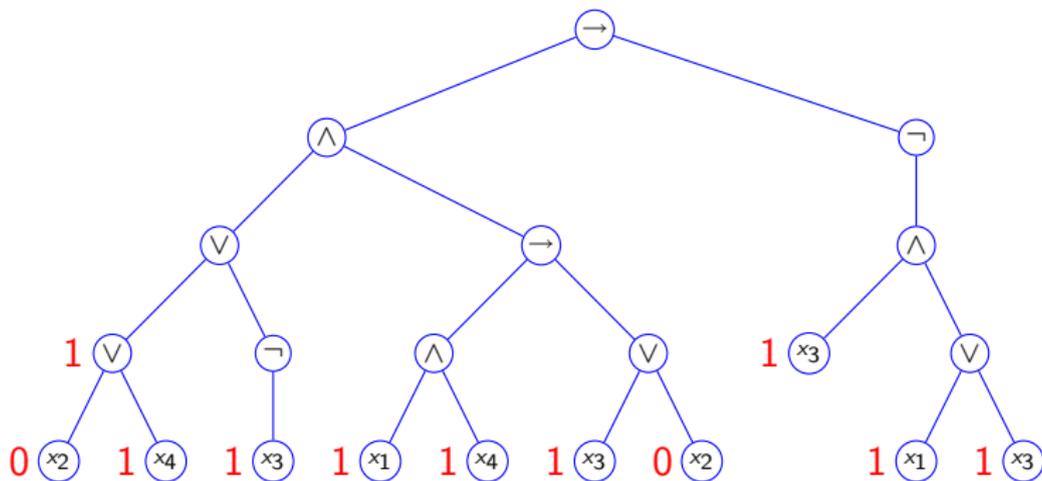
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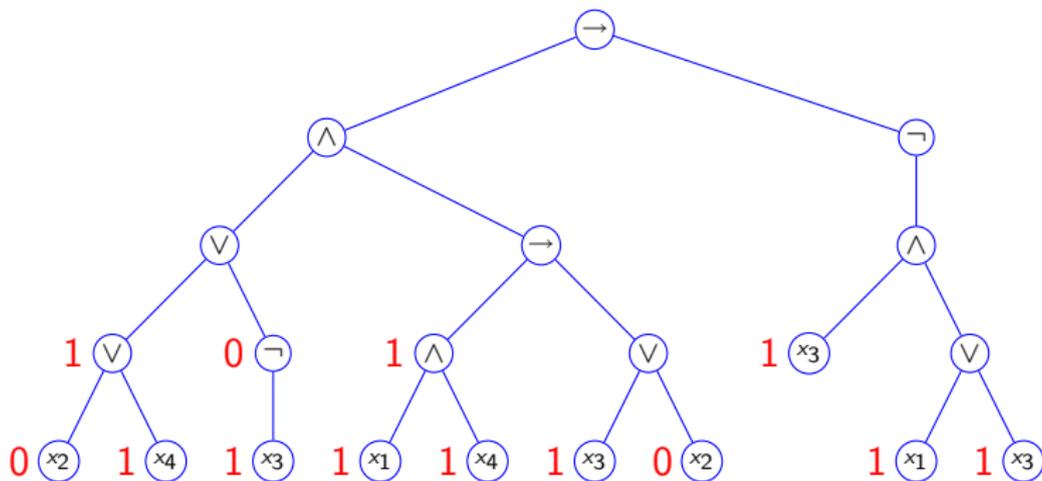
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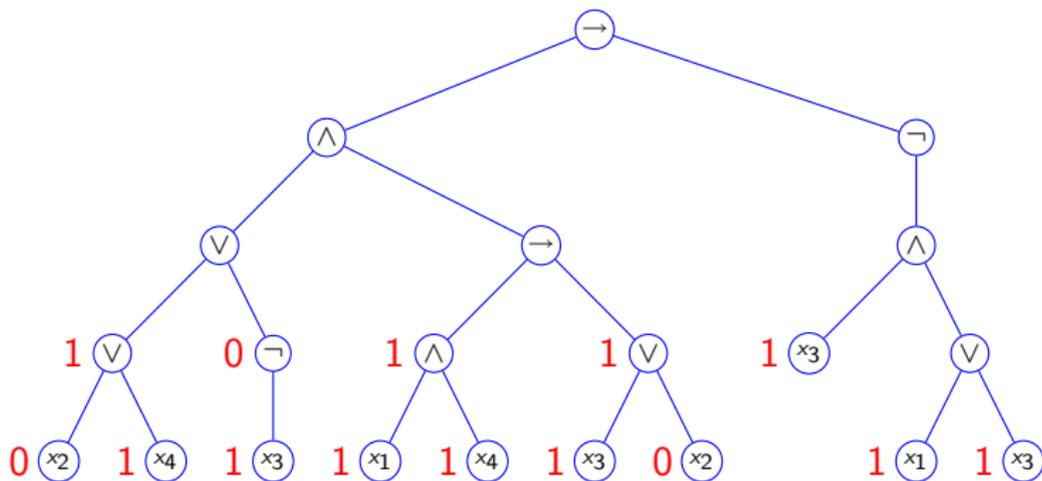
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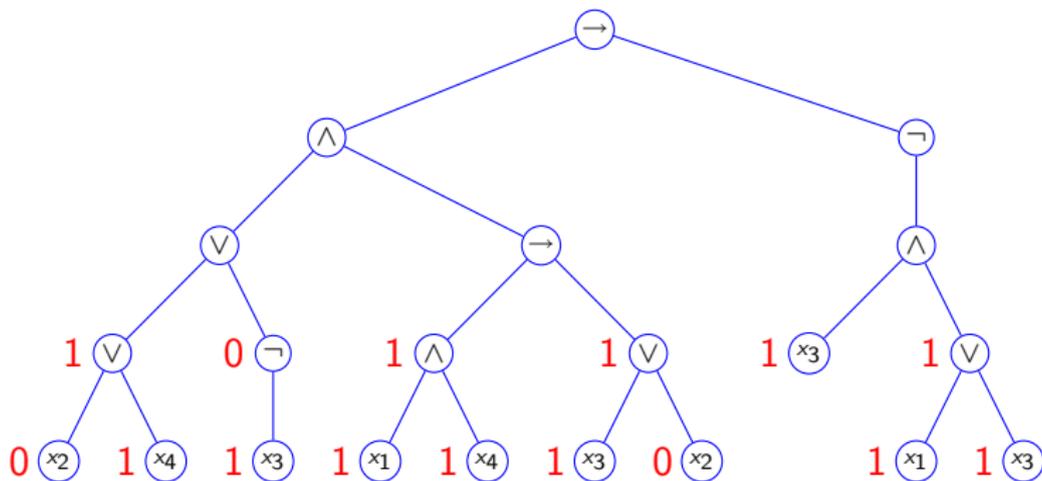
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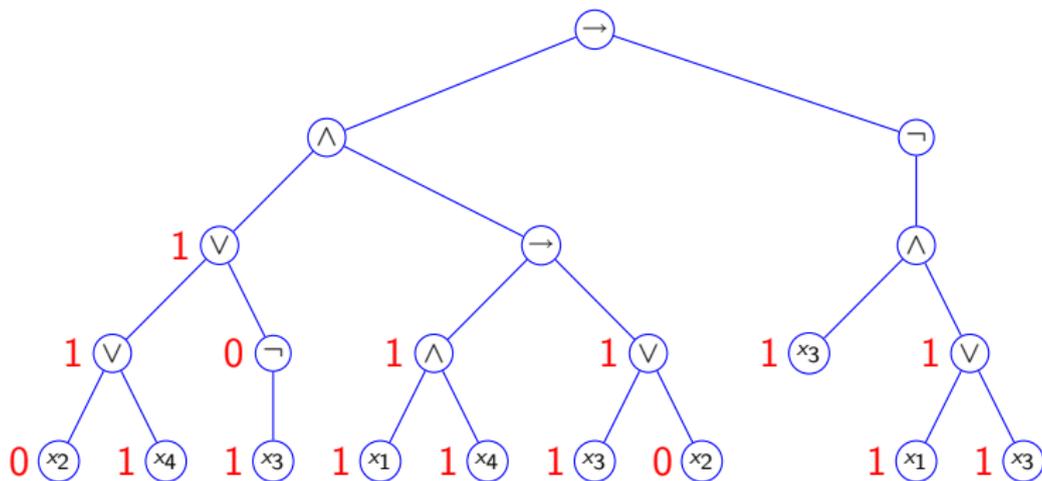
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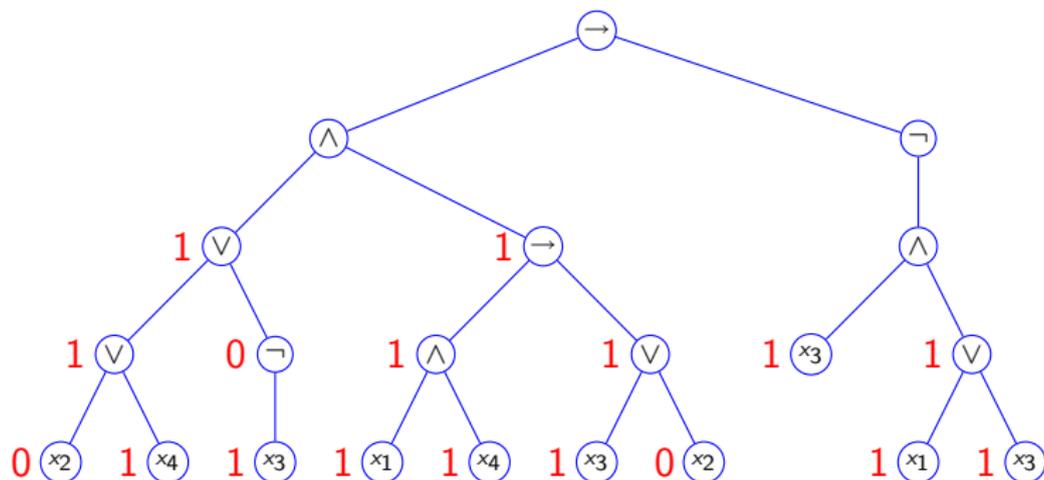
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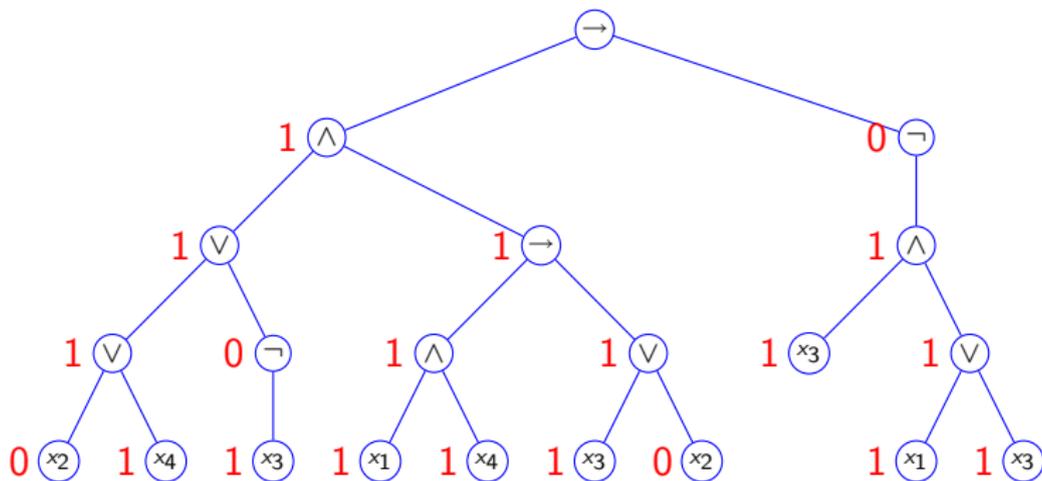






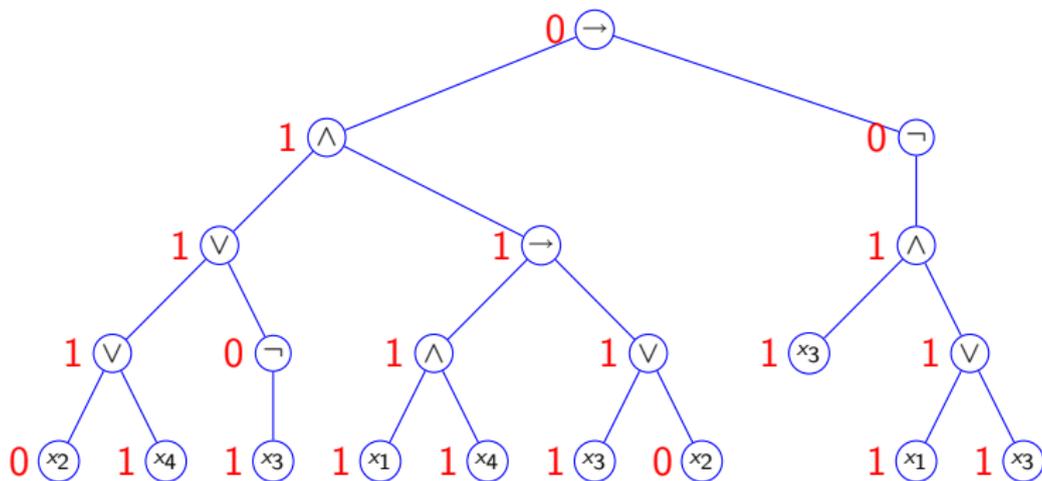
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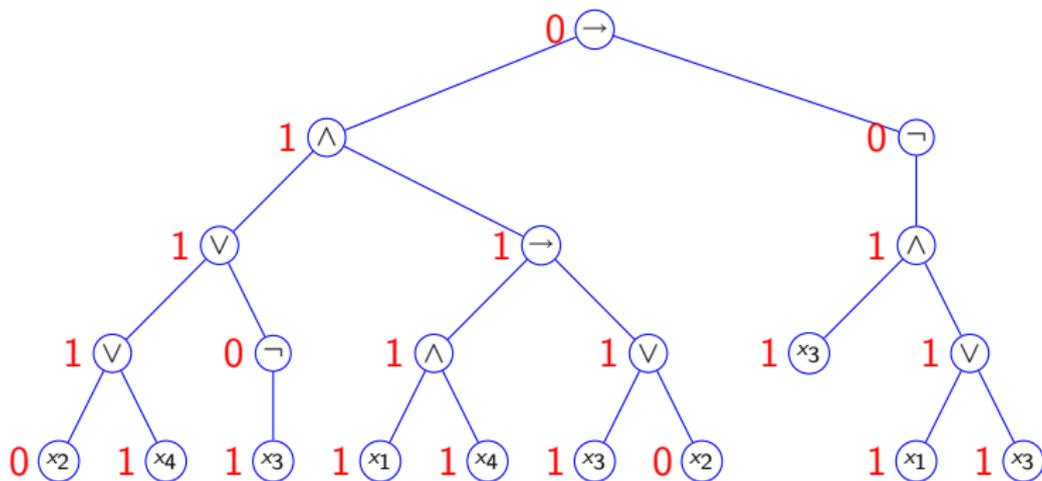
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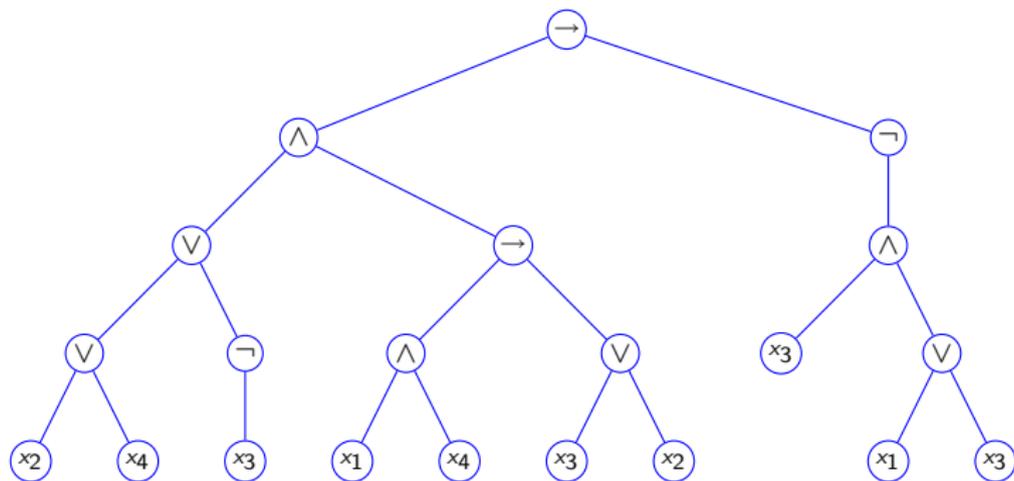


Seems to use  $TIME(N)$  and  $SPACE(N)$ .



# An algorithm for *FVAL*

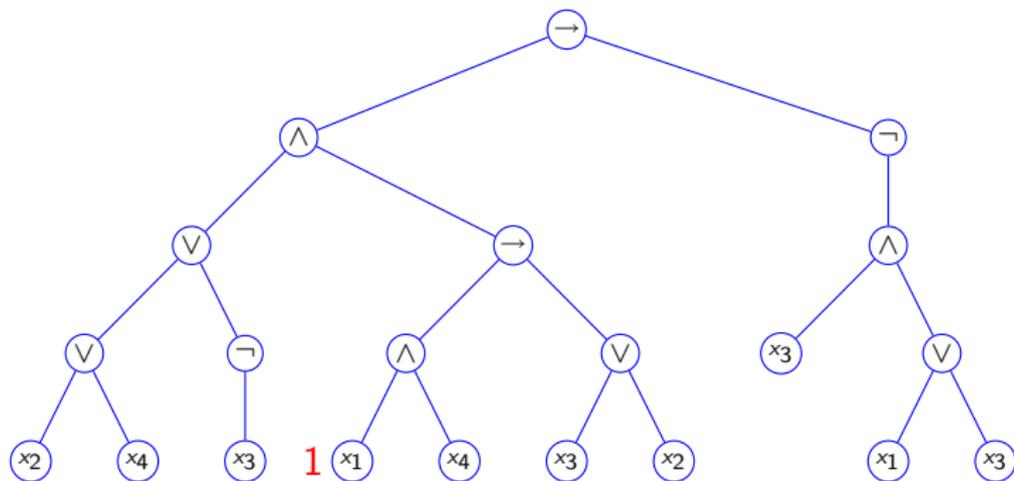
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But space can be re-used. In this example, 3 memory bits suffice.

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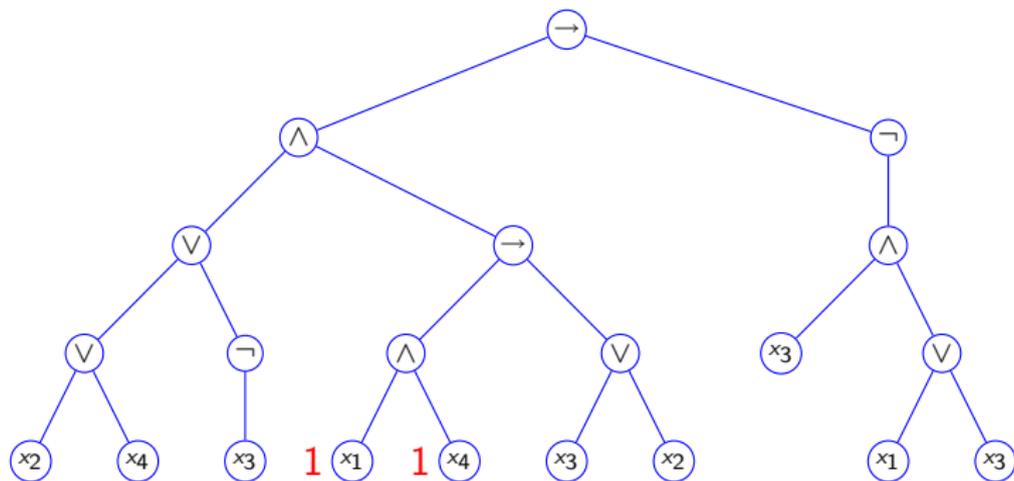
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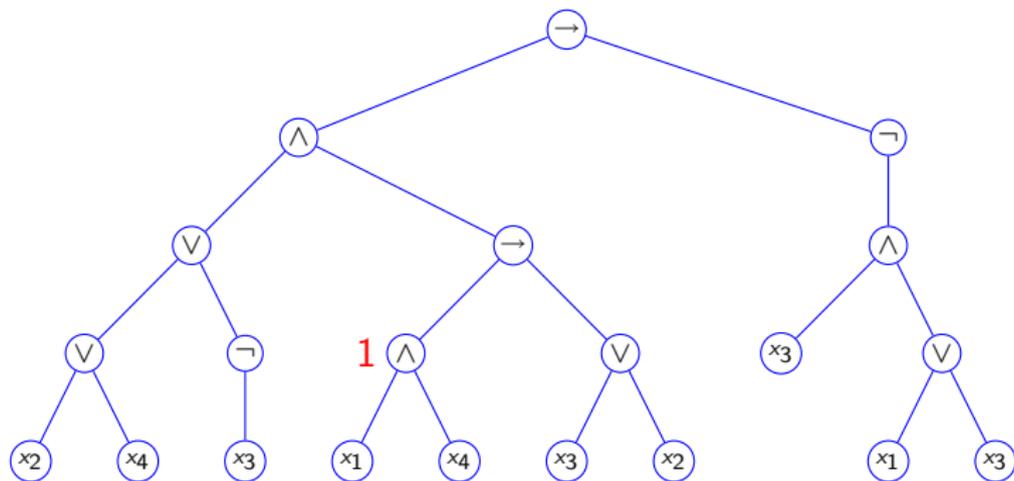
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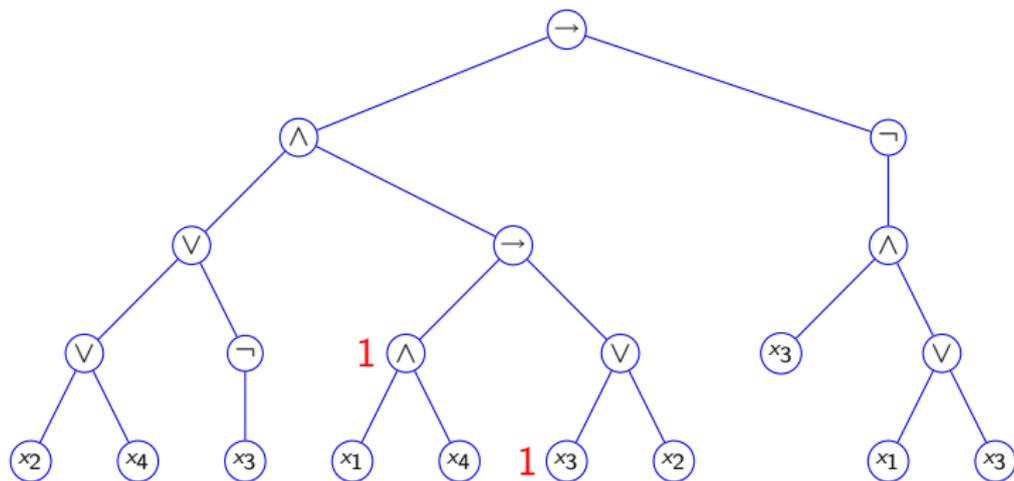
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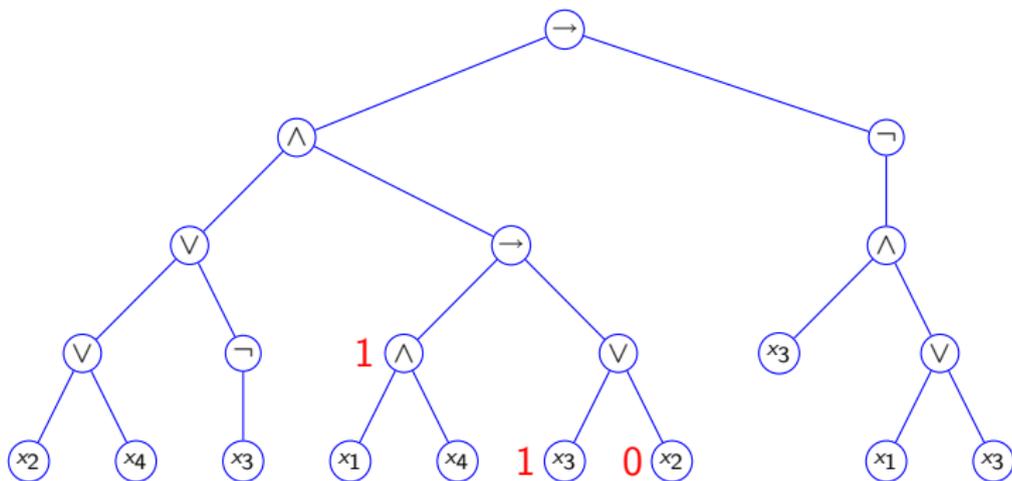
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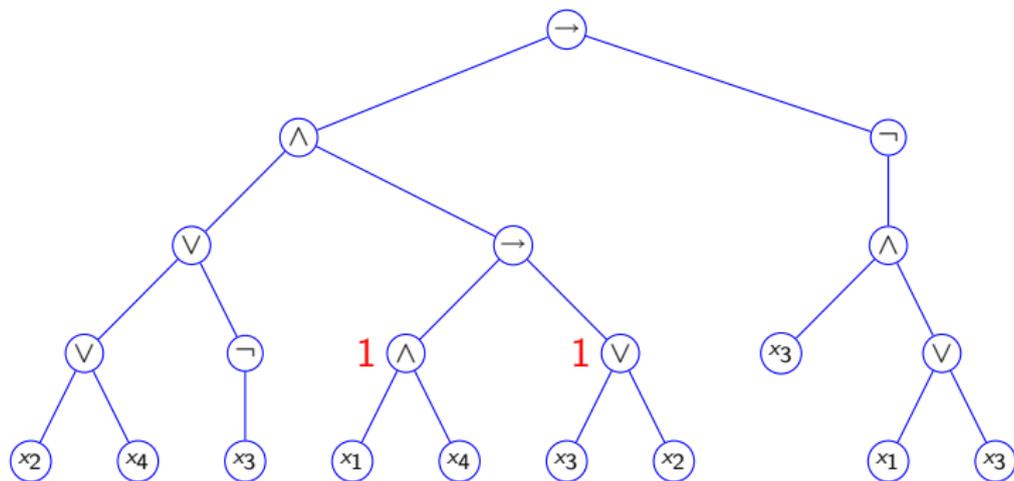
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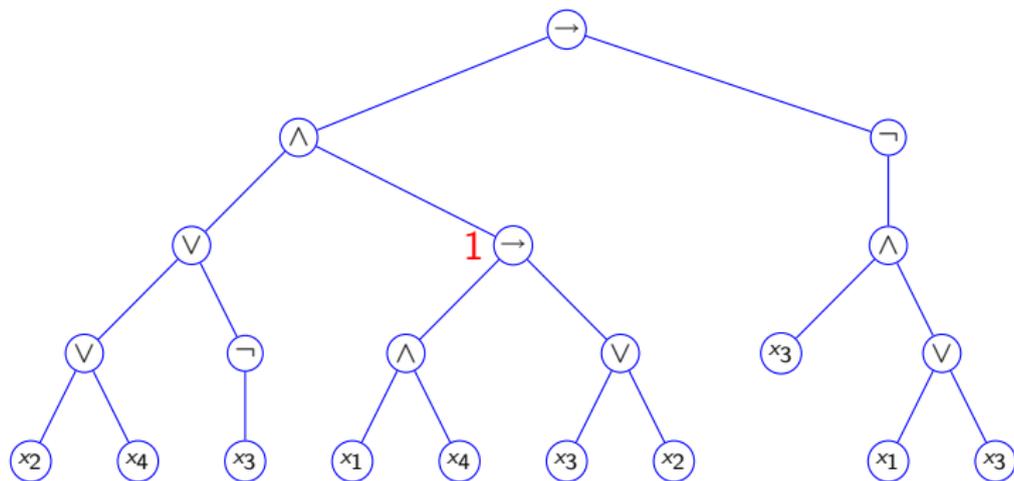
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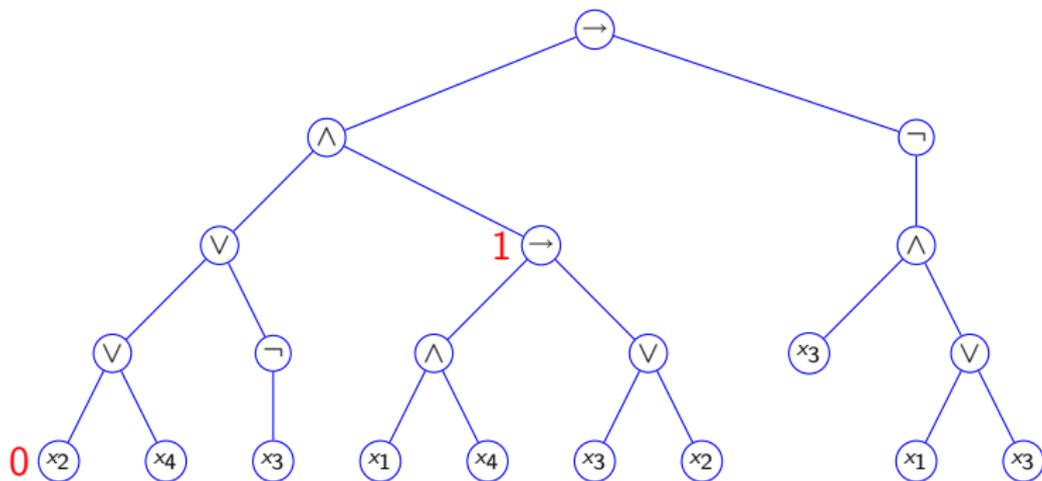
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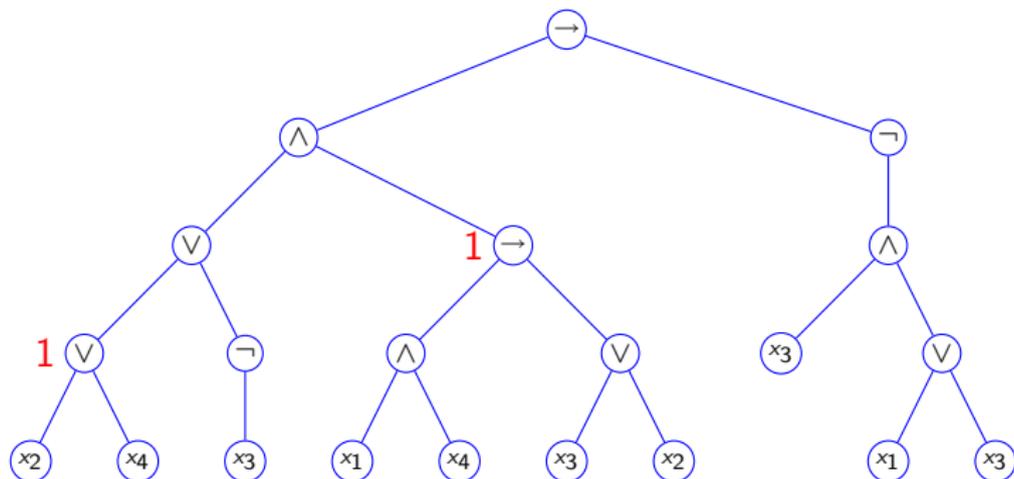


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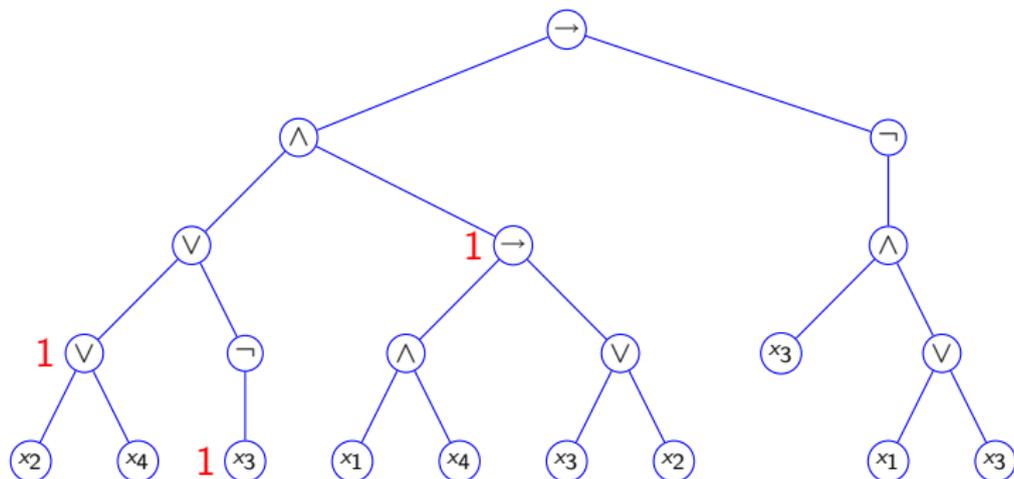
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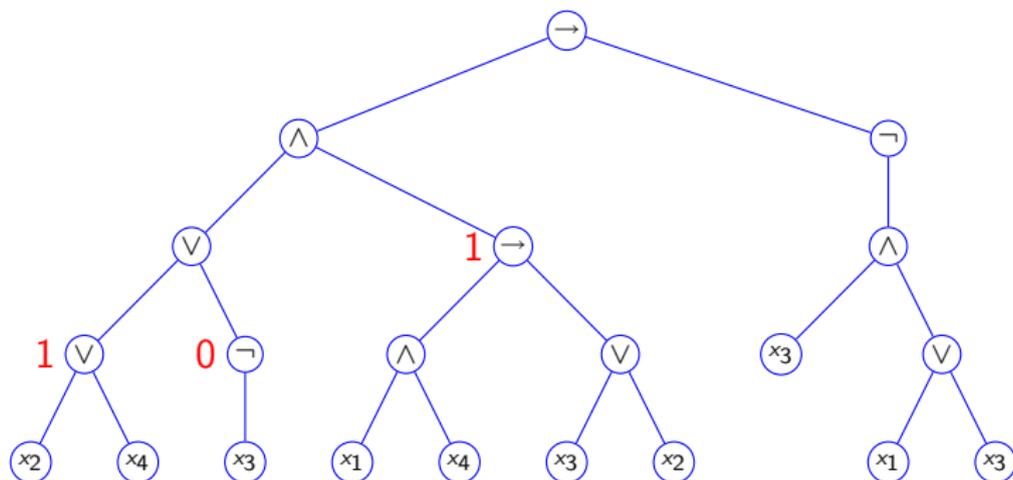
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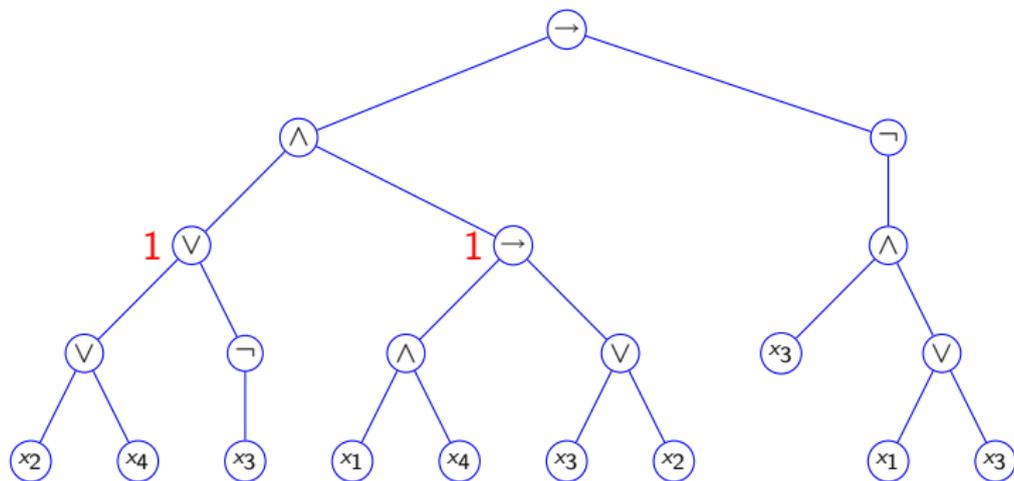
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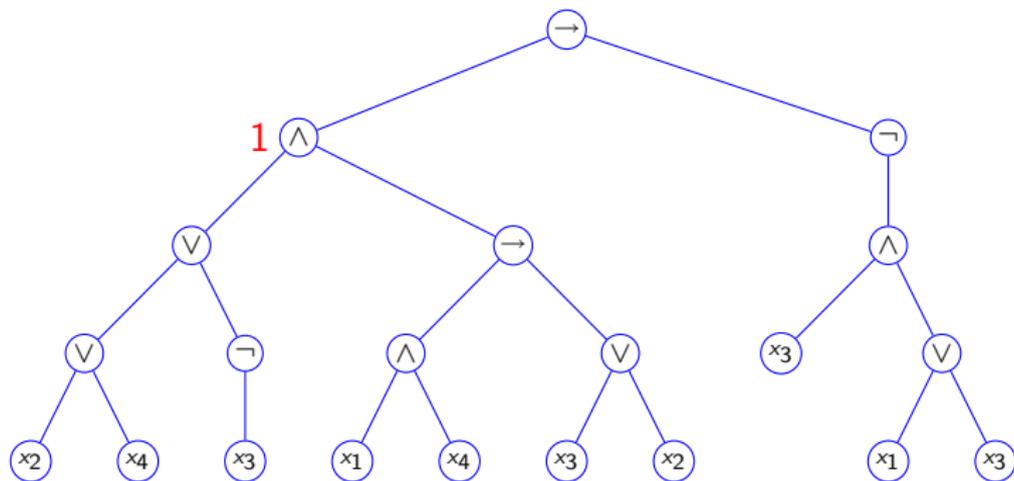
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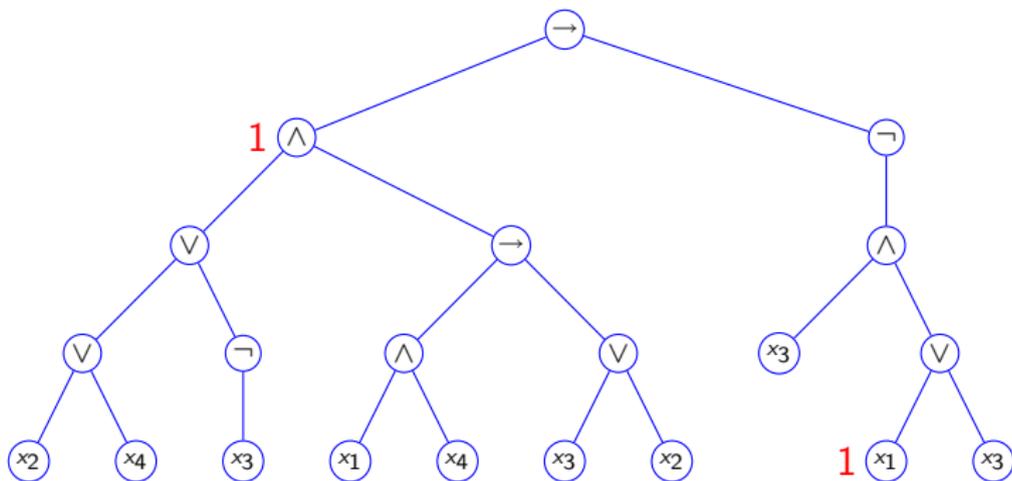
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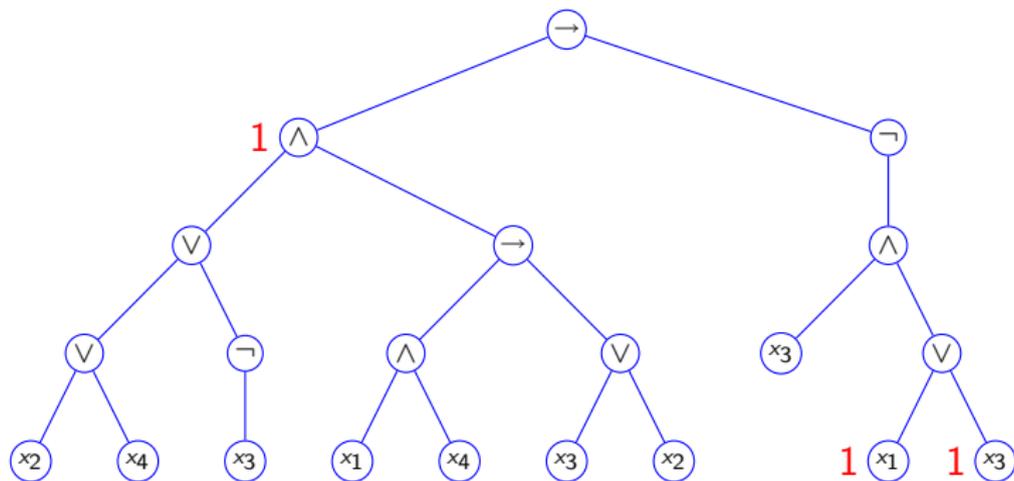
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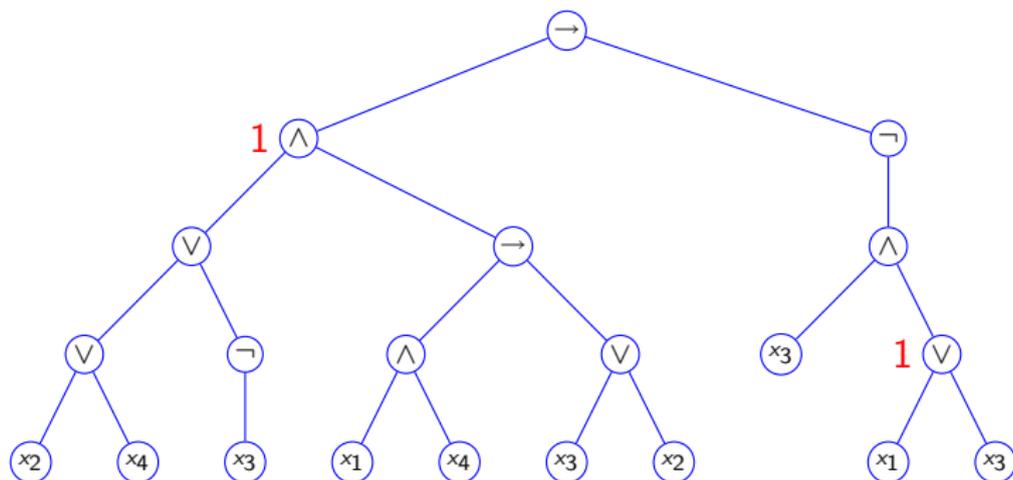
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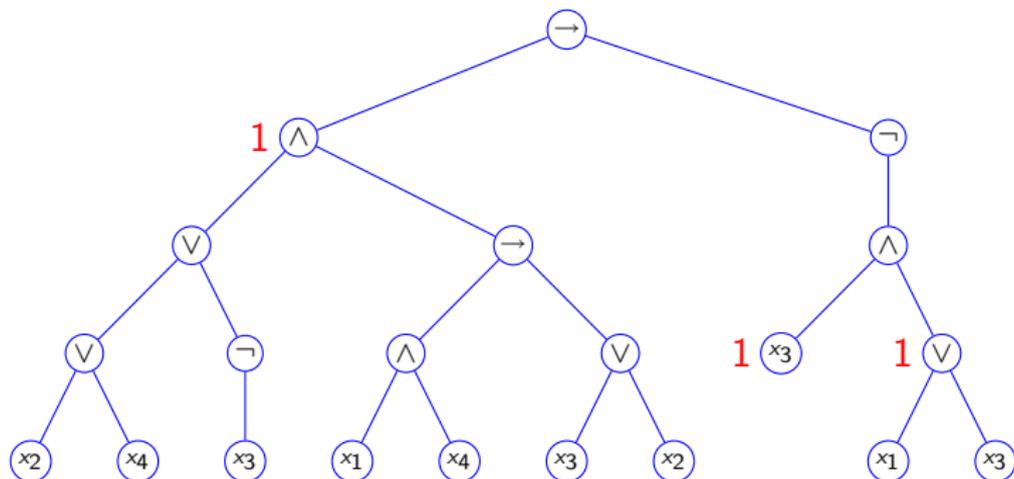
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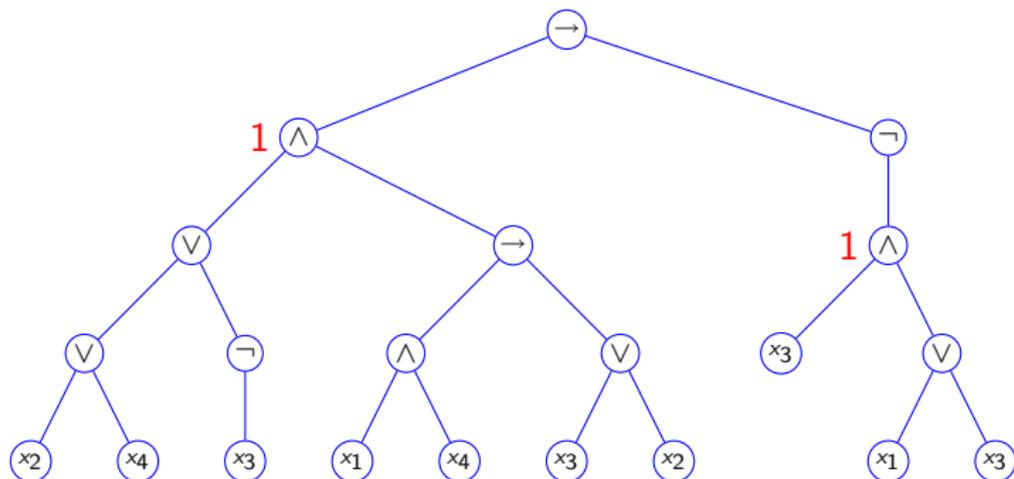
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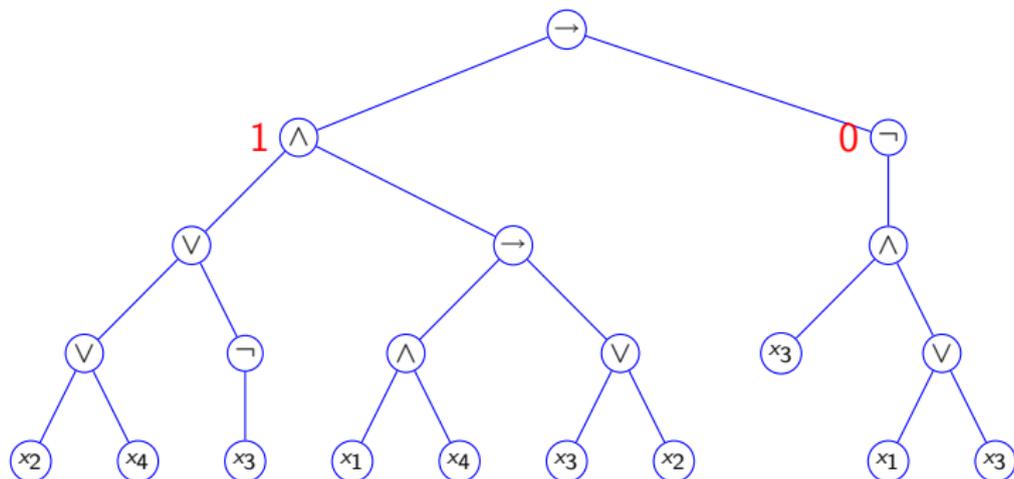
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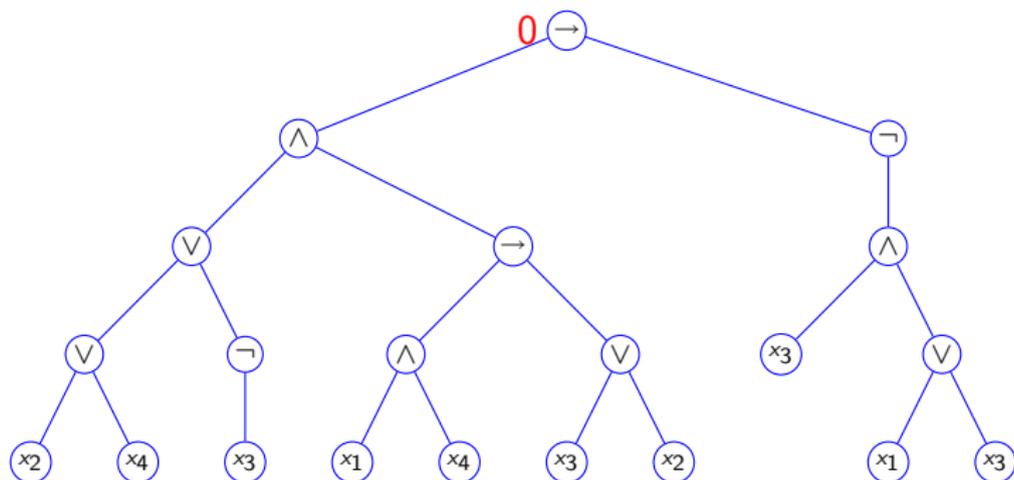
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# Complexity of *FVAL*

In general, a bottom-up computation, always computing a larger subtree first, can be organized to need only  $O(\log |\varphi|)$  intermediate values.

A careful implementation on a Turing machine yields:

# Complexity of *FVAL*

In general, a bottom-up computation, always computing a larger subtree first, can be organized to need only  $O(\log |\varphi|)$  intermediate values.

A careful implementation on a Turing machine yields:

Theorem (Nancy Lynch, 1977)

$$FVAL \in TIME(N^{2+\epsilon})$$

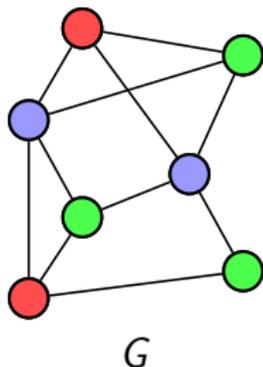
$$FVAL \in SPACE(\log N).$$



# A third problem: Graph 3-Colorability (3COL)

INPUT: a finite graph  $G = (V, E)$ .

QUESTION: Is it possible to color the vertices **red**, **green** or **blue**, so that no two adjacent vertices have the same color?



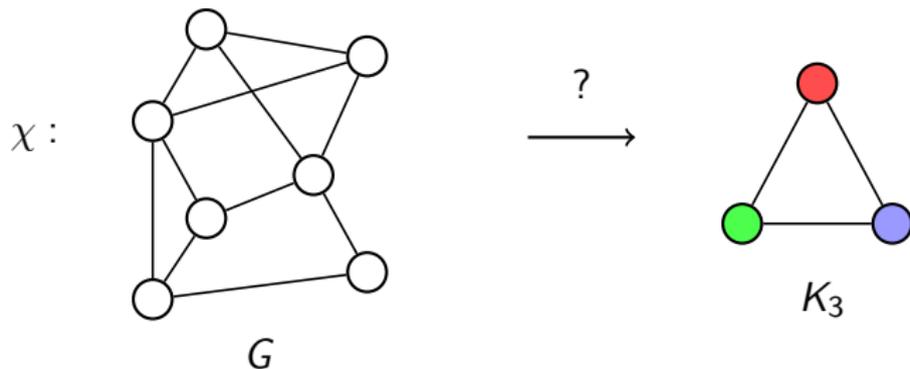
Yes

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Equivalently: does there exist a homomorphism



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(Question: can we do better?..)

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INPUT:

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- An operation  $g : A^k \rightarrow A$ .

QUESTION: Is  $g$  a term operation of  $\mathbf{A}$ ?

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In the worst case this could require as much as  $O(|A^{(A^k)}|) = 2^{(|A|^k)^{1+\epsilon}}$  time and space.

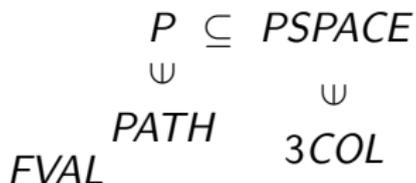
I.e., exponential in the size of the input. (More on this in Lecture 3.)

# Some important complexity classes

## Definition

- 1  $P = PTIME = \bigcup_{k=1}^{\infty} TIME(N^k) = TIME(N^{O(1)})$ .
- 2  $PSPACE = \bigcup_{k=1}^{\infty} SPACE(N^k) = SPACE(N^{O(1)})$ .

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- 4  $L = LOGSPACE = SPACE(\log(N))$ .

$$\begin{array}{ccccccc} L & \subseteq & P & \subseteq & PSPACE & \subseteq & EXPTIME \\ \Psi & & \Psi & & \Psi & & \Psi \\ & & PATH & & 3COL & & CLO \\ FVAL & & & & & & \end{array}$$

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In tomorrow's lecture I will:

- Introduce “nondeterministic” versions of these 4 classes.
- Introduce problems which are “hardest” for each class.